From Deep Learning of Disentangled Representations to Higher-Level Cognition

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Still Far from Human-Level AI

 Industrial successes mostly based on supervised learning



- Learning superficial clues, not generalizing well enough outside of training contexts, easy to fool trained networks:
 - Current models cheat by picking on surface regularities

The need for predictive causal modeling: rare & dangerous states

- Example: autonomous vehicles in near-accident situations
- Current supervised learning may not handle well these cases because they are too rare (not enough data)



- It would be even worse with current RL (statistical inefficiency)
- Long-term objective: develop better predictive models of the world able to generalize in completely unseen scenarios, but it does not seem reasonable to model the sequence of future states in all their details
- Human drivers: no need to die a thousand deaths

Deep Generative Models & GANs

- Simulation
- Filling-in missing data
- Generating text from speech, speech from text, image 2 image
- Inpainting, denoising, super-resolution
- Art, etc.

bicubic (21.59dB/0.6423)



SRResNet (23.53dB/0.7832)



SRGAN (21.15dB/0.6868)



Ledig et al. 2017

original



Deep Unsupervised Learning Takes off with GANs (NIPS'2014)





 Progress in unsupervised generative neural nets allows them to synthesize a diversity images, sounds and text imitating unlabeled images, sounds or text







Text 2 Image, Colorization

This bird is red and brown in color, with a stubby beak

The bird is short and stubby with yellow on its body

A bird with a medium orange bill white body gray wings and webbed feet

This small black bird has a short, slightly curved bill and long legs

A small bird with varying shades of brown with white under the eyes

A small yellow bird with a black crown and a short black pointed beak

This small bird has a white breast, light grey head, and black wings and tail















Lucy Li

Image 2 Image



Isola et al. 2016

What's Missing?

Deep Understanding

Humans outperform machines at autonomous learning

- Humans are very good at unsupervised learning, e.g. a 2 year old knows intuitive physics
- Babies construct an approximate but sufficiently reliable model of physics, how do they manage that? Note that they interact with the world, not just observe it.



What's Missing?

Abstract Representations

Learning Multiple Levels of Abstraction

- The big payoff of deep learning is to allow learning higher levels of abstraction
- Higher-level abstractions disentangle the factors of variation, which allows much easier generalization and transfer



How to Discover Good Representations

- How to discover abstractions?
- What is a good representation?
- Need clues to disentangle the underlying factors
 - Spatial & temporal scales
 - Marginal independence
 - Controllable factors



Acting to Guide Representation Learning & Disentangling



- Some factors (e.g. objects) correspond to 'independently controllable' aspects of the world
- Can only be discovered by acting in the world

Independently Controllable Factors

(Emmanuel Bengio, Valentin Thomas, Joelle Pineau, Doina Precup, Yoshua Bengio, 2017) (Valentin Thomas, Jules Pondard, Emmanuel Bengio, Marc Sarfati, Philippe Beaudoin, Marie-Jean Meurs, Joelle Pineau, Doina Precup, Yoshua Bengio, 2017)

- Jointly train for each aspect (factor)
 - A policy π_k (which tries to selectively change just that factor)
 - A representation (which maps state to value of factor) f_k Discrete case, $\phi \in \{1, ..., N\}$, define *selectivity*:

$$\sum_{k=1}^{N} \mathbb{E}_{(s_t, a_t, s_{t+1})} \left[\pi_k(a_t | s_t) \frac{f_k(s_{t+1}) - f_k(s_t)}{\sum_{k'} |f_{k'}(s_{t+1}) - f_{k'}(s_t)|} \right]$$
Optimize both policy π_k and representation f_k to minimize

$$\underbrace{\mathbb{E}_{s}[\frac{1}{2}||s - g(f(s))||_{2}^{2}]}_{\text{reconstruction error}} - \lambda \underbrace{\sum_{k} \mathbb{E}_{s}[\sum_{a} \pi_{k}(a|s) \log sel(s, a, k)]}_{\text{disentanglement objective}}$$

Predict the effect of actions in attribute space

Given initial state and set of actions, predict new attribute values and the corresponding reconstructed images



Given two states, recover the causal actions leading from one to the other



Continuous Set of Attributes: Attribute Embeddings = variable name

Principle

We map controllable factors to embeddings ϕ instead of coordinates k (one policy network). Discovers by itself the relevant number of features.

 $\phi = G(h, z) \in \mathbb{R}^n$ is now **generated** from h = f(s), $z \sim \mathcal{N}(0, 1)$:

$$\mathbb{E}_{(s_t, a_t, s_{t+1})} \mathbb{E}_{\phi} \left[\pi_{\phi}(a_t | s_t) \frac{A(f(s_{t+1}) - f(s_t), \phi)}{\mathbb{E}_{\phi' = G(h_t, z')} \left[|A(f(s_{t+1}) - f(s_t), \phi')| \right]} \right]$$

How much the **value** of property ϕ changed relatively to other properties.

Continuous Attributes Model: Computational Graph

Total objective = autoencoder loss + selectivity loss



• Off-policy A2C/PG method on a batch of ϕ

What's Wrong with our Unsupervised Training Objectives?

They are in pixel space rather than abstract space

Abstraction Challenge for Unsupervised Learning

- Why is modeling P(acoustics) so much worse than modeling P(acoustics | phonemes) P(phonemes)?
- Why are our current models not able to figure out phonemes AND model their distribution separately?
- May have to do with the different time scales and objective function at the wrong level of abstraction:
 - log-likelihood focuses most of its value on the vast majority of bits characterizing the acoustic details (instead of the higher-level linguistic structure)
 - it would be good to just predict the future in in abstract space rather than in the pixel space

The Consciousness Prior Bengio 2017, arXiv:1709.08568

• Conscious thoughts are very low-dimensional objects compared to the full state of the (unconscious) brain

0 0

- Yet they have unexpected predictive value or usefulness
 → strong constraint or prior on the underlying representation
- Thought: composition of few selected factors / concepts at the highest level of abstraction of our brain
- Richer than but closely associated with short verbal expression such as a sentence or phrase, a rule or fact (link to classical symbolic AI & knowledge representation)

How to select a few relevant abstract concepts in a thought? Content-based

Altention

On the Relation between Abstraction and Attention

- Attention allows to focus on a few elements out of a large set
- Soft-attention allows this process to be trainable with gradientbased optimization and backprop

Attention focuses on a few appropriate abstract or concrete elements of mental representation



The Attention Revolution in Deep Learning

Attention mechanisms exploit GATING units, have unlocked a breakthrough in machine translation:

Neural Machine Translation (ICLR'2015)



Now in Google Translate:
 current
 neural r



The Consciousness Prior Bengio 2017, arXiv:1709.08568

- 2 levels of representation:
 - High-dimensional abstract representation space (all known concepts and factors) *h*
 - Low-dimensional conscious thought *c*, extracted from *h*
- Example: *c* is a prediction about some future event, involves current variables and their values, and a prediction about a future variable
- Predictor needs to refer to a predicted variable by NAME (e.g. embedding) so as to be able to separate the name from the value and recover the prediction when a future event makes the variable observed (at a different value).



The Consciousness Prior Bengio 2017, arXiv:1709.08568

• Conscious prediction over attended variables A (soft attention)



Representing Agents, Objects, Policies

The controllable factors idea works on a small scale: ongoing work to expand this to more complex environments

- Expand to sequences of actions and use them to define options
- Notion of objects and attributes naturally falls out
- Extension to non-static set of objects: types & instances
- Objects are groups of controllable features: by whom? Agents
 - Factors controlled by other agents; mirror neurons
- Because the set of objects may be unbounded, we need to learn to represent policies themselves, and the definition of an object is bound to the policies associated with it (for using it and changing its attributes)

Research Program Towards Higher-Level Deep Learning

- Build a series of gradually more complex environments
- Design training frameworks for learning agents to discover the notion of objects, attributes, types, other agents, relations, the combinatorial space of policies, etc...
- Associate all these concepts to linguistic constructions: learn semantically grounded linguistic expressions.
 - Words are clues of higher-level abstractions
 - Language is an input/output modality

Ongoing Research: DL for AI neural nets \rightarrow cognition

- Learn more abstract representations which capture causality
- Independently controllable factors: some abstract factors are controllable aspects of the environment, disentangled
- Jointly learn conditional exploratory policies with intrinsic rewards + associated factors
- Naturally gives rise to the notion of objects, attributes & agents
- Natural language & consciousness prior: other clue about abstract representations



• Unsupervised RL research, performed in simulated environments

The Future of Deep AI



- Scientific progress is slow and continuous, but social and economic impact can be disruptive
- Many fundamental research questions are in front of us, with much uncertainty about when we will crack them, **but we will**
- Importance of continued investment in basic & exploratory AI research, for both practical (recruitment) short-term and long-term reasons
- Let us continue to keep the field open and fluid, be mindful of social impacts, and make sure AI will bloom for the benefit of all

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