

## EXAMPLES

**1.2.3.** To find the point of intersection of the two lines  $2x + 3y = 6$  and  $x - y = 1$ , we solve the system:

$$\begin{aligned} 2x + 3y &= 6 \\ x - y &= 1. \end{aligned}$$

Subtracting twice the second row from the first row yields the equation:  $5y = 4$ . Therefore:  $y = 4/5$ .

Substituting in the second equation, we get:  $x = 1 + y = 1 + 4/5 = 9/5$ .

**4.5.6.** Solve the systems of linear equations:

$$(i) \quad \begin{aligned} x - y + 2z &= 1 \\ 2x - 2y + 6z &= 0 \\ x + 2y + 3z &= 1 \end{aligned} \quad \text{and} \quad (ii) \quad \begin{aligned} x_1 + x_2 + 2x_3 + x_4 &= 0 \\ 2x_1 + 2x_2 + 3x_3 + 4x_4 &= 2 \\ x_1 + x_2 + x_3 - x_4 &= 2. \end{aligned}$$

$$(i) \quad \begin{pmatrix} x & y & z & | & \\ 1 & -1 & 2 & | & 1 \\ 2 & -2 & 6 & | & 0 \\ 1 & 2 & 3 & | & 1 \end{pmatrix} \xrightarrow{R2 \leftarrow R2 - 2R1} \begin{pmatrix} \frac{1}{1} & -1 & 2 & | & 1 \\ 0 & 0 & 2 & | & -2 \\ 1 & 2 & 3 & | & 1 \end{pmatrix} \xrightarrow{R3 \leftarrow R3 - R1} \begin{pmatrix} \frac{1}{1} & -1 & 2 & | & 1 \\ 0 & 0 & 2 & | & -2 \\ 0 & 3 & 1 & | & 0 \end{pmatrix}$$

$$\xrightarrow{R2 \leftrightarrow R3} \begin{pmatrix} \frac{1}{1} & -1 & 2 & | & 1 \\ 0 & \underline{3} & 1 & | & 0 \\ 0 & 0 & \underline{2} & | & -2 \end{pmatrix} \xrightarrow{R3 \leftarrow \frac{1}{2}R3} \begin{pmatrix} \frac{1}{1} & -1 & 2 & | & 1 \\ 0 & \underline{3} & 1 & | & 0 \\ 0 & 0 & \underline{1} & | & -1 \end{pmatrix}$$

Solution:  $z = -1$   
 $3y + z = 0 \Rightarrow y = 1/3$   
 $x - y + 2z = 1 \Rightarrow x = 1 + y - 2z = 10/3$

$$(ii) \quad \begin{pmatrix} x_1 & x_2 & x_3 & x_4 & | & \\ 1 & 1 & 2 & 1 & | & 0 \\ 2 & 2 & 3 & 4 & | & 2 \\ 1 & 1 & 1 & -1 & | & 2 \end{pmatrix} \xrightarrow{\begin{matrix} R2 \leftarrow R2 - 2R1 \\ R3 \leftarrow R3 - R1 \end{matrix}} \begin{pmatrix} \frac{1}{1} & 1 & 2 & 1 & | & 0 \\ 0 & 0 & -1 & 2 & | & 2 \\ 0 & 0 & -1 & -2 & | & 2 \end{pmatrix} \xrightarrow{R3 \leftarrow R3 - R2} \begin{pmatrix} \frac{1}{1} & 1 & 2 & 1 & | & 0 \\ 0 & 0 & -1 & 2 & | & 2 \\ 0 & 0 & 0 & 0 & | & 0 \end{pmatrix}$$

Solution:  $x_2, x_3$  free  
 $-x_3 + 2x_4 = 1 \Rightarrow x_3 = 2x_4 - 1$   
 $x_1 + x_2 + 2x_3 + x_4 = 0 \Rightarrow x_1 = -x_2 - 2x_3 - x_4 = 2 - x_2 - 5x_4$

In the preceding example, replace the number 2 on the right-hand side of the third equation by 3 and check that the corresponding system is inconsistent.

**7.** Pursue the reduction process on the preceding examples.

$$(i) \quad \begin{pmatrix} \frac{1}{1} & -1 & 2 & | & 1 \\ 0 & \underline{3} & 1 & | & 0 \\ 0 & 0 & \underline{1} & | & -1 \end{pmatrix} \xrightarrow{R2 \leftarrow R2 - R3} \begin{pmatrix} \frac{1}{1} & -1 & 2 & | & 1 \\ 0 & \underline{3} & 0 & | & 1 \\ 0 & 0 & \underline{1} & | & -1 \end{pmatrix} \xrightarrow{R1 \leftarrow R1 - 2R3} \begin{pmatrix} \frac{1}{1} & -1 & 0 & | & 3 \\ 0 & \underline{3} & 0 & | & 1 \\ 0 & 0 & \underline{1} & | & -1 \end{pmatrix}$$

$$\xrightarrow{R2 \leftarrow \frac{1}{3}R2} \begin{pmatrix} \frac{1}{1} & -1 & 0 & | & 3 \\ 0 & \underline{1} & 0 & | & \frac{1}{3} \\ 0 & 0 & \underline{1} & | & -1 \end{pmatrix} \xrightarrow{R1 \leftarrow R1 + R2} \begin{pmatrix} \frac{1}{1} & 0 & 0 & | & \frac{10}{3} \\ 0 & \underline{1} & 0 & | & \frac{1}{3} \\ 0 & 0 & \underline{1} & | & -1 \end{pmatrix}$$

Solution:  $x = 10/3, y = 1/3, z = -1$ .

$$(ii) \quad \begin{pmatrix} \frac{1}{1} & 1 & 2 & 1 & | & 0 \\ 0 & 0 & -1 & 2 & | & 2 \\ 0 & 0 & 0 & 0 & | & 0 \end{pmatrix} \xrightarrow{R1 \leftarrow R1 + 2R2} \begin{pmatrix} \frac{1}{1} & 1 & 0 & 5 & | & 2 \\ 0 & 0 & -1 & 2 & | & 2 \\ 0 & 0 & 0 & 0 & | & 0 \end{pmatrix}$$

Solution:  $x_2$  and  $x_4$  free,  $x_3 = 2x_4 - 1, x_1 = 2 - x_2 - 5x_4$ .

8.9.

$$\text{Let: } A = \begin{pmatrix} 1 & 2 & 3 \\ 0 & 4 & -1 \end{pmatrix} \quad B = \begin{pmatrix} 1 & 2 \\ 0 & 1 \end{pmatrix} \quad C = \begin{pmatrix} 1 & 1 \\ -1 & 0 \end{pmatrix} \quad D = \begin{pmatrix} 1 & -1 \\ 2 & -2 \end{pmatrix} \quad E = \begin{pmatrix} 1 & 1 \\ 1 & 1 \end{pmatrix}.$$

$$\text{Then: } AA^t = \begin{pmatrix} 14 & 5 \\ 5 & 17 \end{pmatrix} \quad A^t A = \begin{pmatrix} 1 & 2 & 3 \\ 2 & 20 & 2 \\ 3 & 2 & 10 \end{pmatrix} \quad BC = \begin{pmatrix} -1 & 1 \\ -1 & 0 \end{pmatrix} \neq CB = \begin{pmatrix} 1 & 3 \\ 1 & -2 \end{pmatrix}.$$

**Remark.** The matrices  $AA^t$  and  $A^t A$  are always symmetric.

Check that  $DE = 0$ , although  $D \neq 0$  and  $E \neq 0$ . However:  $ED = \begin{pmatrix} 3 & -3 \\ 3 & -3 \end{pmatrix} \neq 0$ .

**Remark.**  $(A + B)^2 = A^2 + AB + BA + B^2 \neq A^2 + 2AB + B^2$  unless  $AB = BA$ !

10. Let  $A = \begin{pmatrix} 1 & 2 & -1 \\ 0 & 2 & 4 \end{pmatrix}$  and  $B = \begin{pmatrix} 2 \\ 0 \end{pmatrix}$ . The matrix equation  $AX = B$  is equivalent to the system:

$$\begin{array}{l} x_1 + 2x_2 - x_3 = 2 \\ 2x_2 + 4x_3 = 0 \end{array} \quad \text{where } X = \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix}.$$

11. Let  $A = \begin{pmatrix} 1 & 2 & 3 \\ -1 & 1 & 0 \end{pmatrix}$ . Solve the equation  $AX = 0$ .

$$\begin{array}{ccc|c} x_1 & x_2 & x_3 & \\ \hline \underline{1} & 2 & 3 & 0 \\ -1 & 1 & 0 & 0 \end{array} \xrightarrow{R2 \leftarrow R2 + R1} \begin{array}{ccc|c} \underline{1} & 2 & 3 & 0 \\ 0 & \underline{3} & 3 & 0 \end{array}$$

Solution:  $x_3$  is free

$$3x_2 + x_3 = 0 \Rightarrow x_2 = -x_3$$

$$x_1 + 2x_2 + 3x_3 = 0 \Rightarrow x_1 = -2x_2 - 3x_3 = -x_3$$

12. Let  $A = \begin{pmatrix} 1 & 2 \\ 3 & 4 \end{pmatrix}$  and  $B = \frac{1}{2} \begin{pmatrix} -4 & 2 \\ 3 & -1 \end{pmatrix}$ . Since  $BA = I$ ,  $B$  is a left inverse of  $A$ . Thus it should also be a

right inverse (check it). Also:  $A^2 = \begin{pmatrix} 7 & 10 \\ 15 & 22 \end{pmatrix}$  and  $(A^2)^{-1} = (A^{-1})^2 = B^2 = \frac{1}{4} \begin{pmatrix} 22 & -10 \\ -15 & 7 \end{pmatrix}$ .

In 8.9. check that  $\text{tr}(BC) = -1 + 0 = \text{tr}(CB) = 1 + (-2) = -1$ .

13. Let us find the inverse of  $A = \begin{pmatrix} 0 & 1 & 2 \\ 1 & 0 & 1 \\ 1 & 1 & 1 \end{pmatrix}$ :

$$\left( \begin{array}{ccc|ccc} 0 & 1 & 2 & 1 & 0 & 0 \\ 1 & 0 & 1 & 0 & 1 & 0 \\ 1 & 1 & 1 & 0 & 0 & 1 \end{array} \right) \xrightarrow{R1 \leftrightarrow R2} \left( \begin{array}{ccc|ccc} \underline{1} & 0 & 1 & 0 & 1 & 0 \\ 0 & \underline{1} & 2 & 1 & 0 & 0 \\ 1 & 1 & 1 & 0 & 0 & 1 \end{array} \right) \xrightarrow{R3 \leftarrow R3 - R1} \left( \begin{array}{ccc|ccc} \underline{1} & 0 & 1 & 0 & 1 & 0 \\ 0 & \underline{1} & 2 & 1 & 0 & 0 \\ 0 & 1 & 0 & 0 & -1 & 1 \end{array} \right)$$

$$\xrightarrow{R3 \leftarrow R3 - R2} \left( \begin{array}{ccc|ccc} \underline{1} & 0 & 1 & 0 & 1 & 0 \\ 0 & \underline{1} & 2 & 1 & 0 & 0 \\ 0 & 0 & \underline{-2} & -1 & -1 & 1 \end{array} \right) \xrightarrow{R2 \leftarrow R2 + R3} \left( \begin{array}{ccc|ccc} \underline{1} & 0 & 1 & 0 & 1 & 0 \\ 0 & \underline{1} & 0 & 0 & -1 & 1 \\ 0 & 0 & \underline{-2} & -1 & -1 & 1 \end{array} \right)$$

$$\xrightarrow{R3 \leftarrow -\frac{1}{2}R3} \left( \begin{array}{ccc|ccc} \underline{1} & 0 & 1 & 0 & 1 & 0 \\ 0 & \underline{1} & 0 & 0 & -1 & 1 \\ 0 & 0 & \underline{1} & \frac{1}{2} & \frac{1}{2} & -\frac{1}{2} \end{array} \right) \xrightarrow{R1 \leftarrow R1 - R3} \begin{array}{ccc|ccc} I & & & & & A^{-1} \\ \underline{1} & 0 & 0 & -\frac{1}{2} & \frac{1}{2} & \frac{1}{2} \\ 0 & \underline{1} & 0 & 0 & -1 & 1 \\ 0 & 0 & \underline{1} & \frac{1}{2} & \frac{1}{2} & -\frac{1}{2} \end{array}$$

$$\begin{aligned}
A^{-1} &= E_6 E_5 E_4 E_3 E_2 E_1 \\
&= \begin{pmatrix} 1 & 0 & -1 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & -\frac{1}{2} \end{pmatrix} \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 1 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & -1 & 1 \end{pmatrix} \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ -1 & 0 & 1 \end{pmatrix} \begin{pmatrix} 0 & 1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 1 \end{pmatrix} \\
A &= E_1^{-1} E_2^{-1} E_3^{-1} E_4^{-1} E_5^{-1} E_6^{-1} \\
&= \begin{pmatrix} 0 & 1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 1 & 0 & 1 \end{pmatrix} \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 1 & 1 \end{pmatrix} \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & -1 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & -2 \end{pmatrix} \begin{pmatrix} 1 & 0 & 1 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix}
\end{aligned}$$

Now consider the equation  $AX = B$  with  $B = (1 \ 0 \ 2)^t$ . Its solution is:

$$X = A^{-1}B = \frac{1}{2} \begin{pmatrix} -1 & 1 & 1 \\ 0 & -2 & 2 \\ 1 & 1 & -1 \end{pmatrix} \begin{pmatrix} 1 \\ 0 \\ -2 \end{pmatrix} = \frac{1}{2} \begin{pmatrix} -3 \\ -4 \\ 3 \end{pmatrix} = \begin{pmatrix} -\frac{3}{2} \\ -2 \\ \frac{3}{2} \end{pmatrix}.$$

14. Let  $A = \begin{pmatrix} a & b & c \\ d & e & f \\ g & h & i \end{pmatrix}$

permutations      number of switches      parity      signed el. products

123	0	+	$aei$	
132	1	-	$-afh$	
213	1	-	$-bdi$	
231	2	+	$bfh$	
312	2	+	$-cdh$	
321	1	-	$-ceg$	$ A  = aei - afh - bdi + bfh + cdh - ceg$

If  $A = \begin{pmatrix} 2 & 2 & 3 \\ 0 & 4 & 0 \\ 0 & 0 & -2 \end{pmatrix}$  then  $|A| = 2 \cdot 4 \cdot (-2) = -16$  (the matrix is invertible).

15. Evaluation of a determinant by row reduction to a triangular form:

$$\begin{aligned}
&\begin{vmatrix} 0 & 2 & 3 \\ 4 & 0 & 4 \\ 2 & 3 & 1 \end{vmatrix} \xrightarrow[R2 \leftarrow -\frac{1}{4}R2]{=} \begin{vmatrix} 0 & 2 & 3 \\ 1 & 0 & 1 \\ 2 & 3 & 1 \end{vmatrix} \xrightarrow[R2 \leftrightarrow R1]{=} -4 \begin{vmatrix} 1 & 0 & 1 \\ 0 & 2 & 3 \\ 2 & 3 & 1 \end{vmatrix} \\
&\xrightarrow[R3 \leftarrow R3 - 2R1]{=} -4 \begin{vmatrix} 1 & 0 & 1 \\ 0 & 2 & 3 \\ 0 & 3 & -1 \end{vmatrix} \xrightarrow[R2 \leftarrow -\frac{1}{2}R2]{=} -8 \begin{vmatrix} 1 & 0 & 1 \\ 0 & 1 & \frac{3}{2} \\ 0 & 3 & -1 \end{vmatrix} \xrightarrow[R3 \leftarrow R3 - 3R2]{=} -8 \begin{vmatrix} 1 & 0 & 1 \\ 0 & 1 & \frac{3}{2} \\ 0 & 0 & -\frac{11}{2} \end{vmatrix} \\
&= -8 \times 1 \times 1 \times \left(-\frac{11}{2}\right) = 44 \neq 0 \text{ and the matrix is invertible (see 17.)}
\end{aligned}$$

16.17.  $\begin{vmatrix} a-3 & -2 \\ -2 & a-2 \end{vmatrix} = (a-3)(a-2) - 4 = a^2 - 5a + 2 = 0 \iff a = (5 \pm \sqrt{17})/2$ . If  $a \neq (5 \pm \sqrt{17})/2$ , then the matrix (call it  $A$ ) is invertible and  $|A^{-1}| = 1/|A| = 1/(a^2 - 5a + 2)$ .

18. Let  $A = \begin{pmatrix} 1^+ & 2^- & 3^+ \\ 2^- & 0^+ & -1^- \\ 0^+ & -1^- & 4^+ \end{pmatrix}$ . The cofactor expansion of  $\det(A)$  along row 2 yields:

$$|A| = -2 \begin{vmatrix} 2 & 3 \\ -1 & 4 \end{vmatrix} + 0 - (-1) \begin{vmatrix} 1 & 2 \\ 0 & -1 \end{vmatrix} = -22 - 1 = -23.$$

The expansion along the second column yields:

$$|A| = -2 \begin{vmatrix} 2 & -1 \\ 0 & 4 \end{vmatrix} + 0 - (-1) \begin{vmatrix} 1 & 3 \\ 2 & -1 \end{vmatrix} = -16 - 7 = -23.$$

An interesting strategy is to mix row reduction and cofactor expansion. For example:

$$\begin{vmatrix} 1 & 2 & 3 \\ 2 & 0 & -1 \\ 0 & -1 & 4 \end{vmatrix} \xrightarrow{R2 \leftarrow R2 - 2R1} \begin{vmatrix} 1 & 2 & 3 \\ 0 & -4 & -7 \\ 0 & -1 & 4 \end{vmatrix} = 1 \begin{vmatrix} -4 & -7 \\ -1 & 4 \end{vmatrix} \text{ (expansion along column 1)} = -23.$$

19. Let  $A = \begin{pmatrix} 0 & 1 & 2 \\ 1 & 0 & 1 \\ 1 & 1 & 1 \end{pmatrix}$ . Then:  $|A| \xrightarrow{R3 \leftarrow R3 - R2} \begin{vmatrix} 0 & 1 & 2 \\ 1 & 0 & 1 \\ 0 & 1 & 0 \end{vmatrix} = -1 \begin{vmatrix} 1 & 2 \\ 1 & 0 \end{vmatrix} = 2 \neq 0.$

$$\text{co}(A) = \begin{pmatrix} + \begin{vmatrix} 0 & 1 \\ 1 & 1 \end{vmatrix} & - \begin{vmatrix} 1 & 1 \\ 1 & 1 \end{vmatrix} & + \begin{vmatrix} 1 & 0 \\ 1 & 1 \end{vmatrix} \\ - \begin{vmatrix} 1 & 2 \\ 1 & 1 \end{vmatrix} & + \begin{vmatrix} 0 & 2 \\ 1 & 1 \end{vmatrix} & - \begin{vmatrix} 0 & 1 \\ 1 & 1 \end{vmatrix} \\ + \begin{vmatrix} 1 & 2 \\ 0 & 1 \end{vmatrix} & - \begin{vmatrix} 0 & 2 \\ 1 & 1 \end{vmatrix} & + \begin{vmatrix} 0 & 1 \\ 1 & 0 \end{vmatrix} \end{pmatrix} = \begin{pmatrix} -1 & 0 & 1 \\ 1 & -2 & 1 \\ 1 & 2 & -1 \end{pmatrix}$$

$$\text{adj}(A) = \begin{pmatrix} -1 & 1 & 1 \\ 0 & -2 & 2 \\ 1 & 1 & -1 \end{pmatrix} \text{ and } A^{-1} = \frac{1}{2} \begin{pmatrix} -1 & 1 & 1 \\ 0 & -2 & 2 \\ 1 & 1 & -1 \end{pmatrix}$$

20.

$$\begin{aligned} & x_2 + 2x_3 = 3 \\ \text{Let us solve, using Cramer's rule: } & x_1 + x_3 = 3 \\ & x_1 + x_2 + x_3 = 2 \end{aligned}$$

The matrix of the system is  $A = \begin{pmatrix} 0 & 1 & 2 \\ 1 & 0 & 1 \\ 1 & 1 & 1 \end{pmatrix}$  and its determinant is  $\det(A) \xrightarrow{R3 \leftarrow R3 - R2} \begin{vmatrix} 0 & 1 & 2 \\ 1 & 0 & 1 \\ 0 & 1 & 0 \end{vmatrix}$

$= - \begin{vmatrix} 1 & 2 \\ 1 & 0 \end{vmatrix} = 2$ . Thus we have:

$$x_1 = \frac{1}{\det(A)} \begin{vmatrix} \mathbf{3} & 1 & 2 \\ \mathbf{3} & 0 & 1 \\ \mathbf{2} & 1 & 1 \end{vmatrix} \xrightarrow{R3 \leftarrow R3 - R1} \frac{1}{2} \begin{vmatrix} 3 & 1^- & 2 \\ 3 & 0^+ & 1 \\ -1 & 0^- & -1 \end{vmatrix} = -\frac{1}{2} \begin{vmatrix} 3 & 1 \\ -1 & -1 \end{vmatrix} = 1$$

$$x_2 = \frac{1}{\det(A)} \begin{vmatrix} 0 & \mathbf{3} & 2 \\ 1 & \mathbf{3} & 1 \\ 1 & \mathbf{2} & 1 \end{vmatrix} \xrightarrow{R3 \leftarrow R3 - R2} \frac{1}{2} \begin{vmatrix} 0^+ & 3 & 2 \\ 1^- & 3 & 1 \\ 0^+ & -1 & 0 \end{vmatrix} = -\frac{1}{2} \begin{vmatrix} 3 & 2 \\ -1 & 0 \end{vmatrix} = -1$$

$$x_3 = \frac{1}{\det(A)} \begin{vmatrix} 0 & 1 & \mathbf{3} \\ 1 & 0 & \mathbf{3} \\ 1 & 1 & \mathbf{2} \end{vmatrix} \xrightarrow{R3 \leftarrow R3 - R2} \frac{1}{2} \begin{vmatrix} 0^+ & 1 & 3 \\ 1^- & 0 & 3 \\ 0^+ & 1 & -1 \end{vmatrix} = -\frac{1}{2} \begin{vmatrix} 1 & 3 \\ 1 & -1 \end{vmatrix} = 2.$$

21.  $P = (1, 2, -1)$   $Q = (2, 0, 3)$   $\mathbf{v} = \overrightarrow{PQ} = (2 - 1, 0 - 2, 3 - (-1)) = (1, -2, 4)$   $-\mathbf{v} = (-1, 2, -4)$   
 22.

$$A = (1, 2, 3) \quad B = (2, -1, 0) \quad C = (3, 0, 4)$$

$$\mathbf{u} = \overrightarrow{AB} = (1, -3, -3) \quad \mathbf{v} = \overrightarrow{BC} = (1, 1, 4) \quad \mathbf{u} + \mathbf{v} = \overrightarrow{AB} + \overrightarrow{BC} = (1 + 1, -3 + 1, -3 + 4) = (2, -2, 1) = \overrightarrow{AC}$$

$$-6\mathbf{u} = -6(1, -3, -3) = (-6, 18, 18)$$

$$\|\mathbf{u}\| = \sqrt{1^2 + (-3)^2 + (-3)^2} = \sqrt{19} \quad \|\mathbf{v}\|^2 = \sqrt{1^2 + 1^2 + 4^2} = \sqrt{18}$$

$$\mathbf{u} \cdot \mathbf{v} = (1, -3, -3) \cdot (1, 1, 4) = 1 \cdot 1 + (-3) \cdot 1 + (-3) \cdot 4 = -14$$

$$\cos(\mathbf{u}, \mathbf{v}) = \frac{\mathbf{u} \cdot \mathbf{v}}{\|\mathbf{u}\| \|\mathbf{v}\|} = \frac{-14}{\sqrt{19}\sqrt{18}} \approx -.757$$

and the angle between the vectors  $\overrightarrow{AB}$  and  $\overrightarrow{BC}$  is approximately  $139^\circ$ .

The dot product of the vectors  $(1, 2)$  and  $(4, -2)$  is zero. Hence they are orthogonal  $((1, 2) \perp (4, -2))$ .

23. Let  $\mathbf{u} = (1, 2, -2)$  and  $\mathbf{v} = (3, 0, 4)$ . Using cofactor expansion along the first row, we have:

$$\mathbf{u} \times \mathbf{v} = \begin{vmatrix} \mathbf{i} & \mathbf{j} & \mathbf{k} \\ 1 & 2 & -2 \\ 3 & 0 & 4 \end{vmatrix} = \mathbf{i}(8) - \mathbf{j}(4 - (-6)) + \mathbf{k}(0 - 6) = (8, -10, -6).$$

$$|\sin(\mathbf{u}, \mathbf{v})| = \frac{\|\mathbf{u} \times \mathbf{v}\|}{\|\mathbf{u}\| \|\mathbf{v}\|} = \frac{\sqrt{64 + 100 + 36}}{\sqrt{1 + 4 + 4}\sqrt{9 + 0 + 16}} = \frac{2\sqrt{2}}{3} \quad \cos(\mathbf{u}, \mathbf{v}) = \frac{\mathbf{u} \cdot \mathbf{v}}{\|\mathbf{u}\| \|\mathbf{v}\|} = -\frac{1}{3}$$

and check that  $\sin^2(\mathbf{u}, \mathbf{v}) + \cos^2(\mathbf{u}, \mathbf{v}) = 8/9 + 1/9 = 1$

24. Let  $O' = (-1, 2, 0)$  be the new origin. The point  $P = (11, 2, 3)$  in the old coordinate system  $xOy$  becomes  $P = (11 - (-1), 2 - 2, 3 - 0) = (12, 0, 3)$  in the new system  $x'O'y'$ .  
 25.  $\|\mathbf{u} + \mathbf{v}\|^2 = (\mathbf{u} + \mathbf{v}) \cdot (\mathbf{u} + \mathbf{v}) = \mathbf{u} \cdot \mathbf{u} + \mathbf{v} \cdot \mathbf{v} + \mathbf{u} \cdot \mathbf{v} + \mathbf{v} \cdot \mathbf{u} = \|\mathbf{u}\|^2 + \|\mathbf{v}\|^2 + 2\mathbf{u} \cdot \mathbf{v}$ .  
 26. Let  $\mathbf{u} = (2, -1, 3)$  and  $\mathbf{v} = (4, -1, 2)$ . We have:

$$\mathbf{w}_1 = \frac{\mathbf{u} \cdot \mathbf{v}}{\|\mathbf{v}\|^2} \mathbf{v} = \frac{15}{21}(4, -1, 2) = \left(\frac{20}{7}, -\frac{5}{7}, \frac{10}{7}\right)$$

$$\mathbf{w}_2 = \mathbf{u} - \mathbf{w}_1 = \left(-\frac{6}{7}, -\frac{2}{7}, \frac{11}{7}\right).$$

- 27.28.** • The plane  $x + 3y - z = 4$  has the normal vector  $\mathbf{n} = (1, 3, -1)$ . The two *unit* normal vectors are  $\mathbf{n}/\|\mathbf{n}\| = (1, 3, -1)/\sqrt{5}$  and  $(-1, -3, 1)/\sqrt{5}$ . This plane has the point-normal form (there are others):

$$1(x - 4) + 3(y - 0) - 1(z - 0) = 0.$$

- Let  $A = (1, 0, 1)$ ,  $B = (1, 2, 3)$  and  $C = (-1, 1, 0)$ , and  $ax + by + cz + d = 0$  be the equation of the plane through  $A$ ,  $B$  and  $C$ . We have:

$$\begin{aligned} a + c + d &= 0 \\ a + 2b + 3c + d &= 0 \\ -a + b + d &= 0. \end{aligned}$$

Let us solve this homogeneous system:

$$\begin{array}{cccc|c} a & b & c & d & \\ \hline \underline{1} & 0 & 1 & 1 & 0 \\ 1 & 2 & 3 & 1 & 0 \\ -1 & 1 & 0 & 1 & 0 \end{array} \longrightarrow \begin{array}{cccc|c} \underline{1} & 0 & 1 & 1 & 0 \\ 0 & \underline{2} & 2 & 0 & 0 \\ 0 & 1 & 1 & 2 & 0 \end{array} \longrightarrow \begin{array}{cccc|c} \underline{1} & 0 & 1 & 1 & 0 \\ 0 & \underline{1} & 1 & 0 & 0 \\ 0 & 0 & 0 & \underline{2} & 0 \end{array}.$$

Its solution is:  $d = 0$ ,  $c$  free,  $b = -c$ ,  $a = -c$ . A particular solution is found by assigning the value 1 to  $c$ , and the equation of the plane is:

$$-x - y + z = 0.$$

Alternatively, one could have found a vector normal to the plane:  $\mathbf{n} = \overrightarrow{AB} \times \overrightarrow{AC} = \begin{vmatrix} \mathbf{i} & \mathbf{j} & \mathbf{k} \\ 0 & 2 & 2 \\ -2 & 1 & -1 \end{vmatrix} = (-4, -4, 4)$ ,

and a point-normal form (using point  $A$ ) is:

$$-4(x - 1) - 4(y - 0) + 4(z - 1) = 0 \quad \text{i.e.} \quad x + y - z = 0.$$

- Let  $P = (1, 0, 2)$  and  $\mathbf{v} = (1, 2, -1)$ . The line going through  $P$  and having the same direction as  $\mathbf{v}$  has the parametric equation:

$$x - 1 = t \quad y - 0 = 2t \quad z - 2 = -t.$$

Its symmetric equation is:  $x - 1 = y/2 = (z - 2)/(-1)$ .

- To find the intersection of 2, 3 or more planes in 3D, we solve the corresponding system of equations which can have 0, 1 or infinitely many solutions, depending on the relative positions of the planes.

(i)

$$\begin{array}{cccc} x & + & y & + & z & = & 1 \\ & & & & y & - & z & = & 0 \\ 2x & + & y & & & = & 2 \end{array} \quad \begin{array}{ccc|c} x & y & z & \\ \hline \underline{1} & 1 & 1 & 1 \\ 0 & 1 & -1 & 0 \\ 2 & 1 & 0 & 2 \end{array} \longrightarrow \begin{array}{ccc|c} \underline{1} & 1 & 1 & 1 \\ 0 & \underline{1} & -1 & 0 \\ 0 & 0 & \underline{1} & 0 \end{array}$$

The intersection of the 3 planes occurs at the point  $(x, y, z) = (1, 0, 0)$ .

(ii)

$$\begin{array}{cccc} x & + & y & - & z & = & 1 \\ x & + & y & + & z & = & 5 \end{array} \quad \begin{array}{ccc|c} x & y & z & \\ \hline \underline{1} & 1 & -1 & 1 \\ 1 & 1 & 1 & 5 \end{array} \longrightarrow \begin{array}{ccc|c} \underline{1} & 1 & -1 & 1 \\ 0 & 0 & \underline{1} & 2 \end{array}$$

The solution is:  $z = 2$ ,  $y$  free and  $x = 3 - y$ . The parametric equation of the line of intersection of the two planes is:  $x = 3 - t$ ,  $y = t$ ,  $z = 2$ .

(iii) Let us find the point of intersection of the plane  $x + 2y - z = 2$  and the line  $x = t$ ,  $y = t + 2$ ,  $z = 2t - 1$ . We insert the parametric equations into the plane equation to obtain:

$$\begin{aligned} t + 2(t + 2) - (2t - 1) &= 2 \\ t &= 3 \end{aligned}$$

and the required point is  $(-3, -1, -7)$ .

29.

$$\left\| \frac{\mathbf{u}}{\|\mathbf{u}\|} \right\| = \frac{1}{\|\mathbf{u}\|} \|\mathbf{u}\| = 1.$$

$$\begin{aligned} \|\mathbf{u} + \mathbf{v}\|^2 + \|\mathbf{u} - \mathbf{v}\|^2 &= (\mathbf{u} + \mathbf{v}) \cdot (\mathbf{u} + \mathbf{v}) + (\mathbf{u} - \mathbf{v}) \cdot (\mathbf{u} - \mathbf{v}) \\ &= 2\mathbf{u} \cdot \mathbf{u} + 2\mathbf{v} \cdot \mathbf{v} + \mathbf{u} \cdot \mathbf{v} + \mathbf{v} \cdot \mathbf{u} - \mathbf{u} \cdot \mathbf{v} - \mathbf{v} \cdot \mathbf{u} \\ &= 2(\|\mathbf{u}\|^2 + \|\mathbf{v}\|^2). \end{aligned}$$

30. Examples of vector spaces: the set of real functions, the set of  $2 \times 2$  matrices of the form  $\begin{pmatrix} a & a+b \\ 0 & a+3b \end{pmatrix}$ , a line going through the origin.

Proof that  $k\mathbf{0} = \mathbf{0}$ :

$$\begin{aligned} \mathbf{0} + \mathbf{0} &= \mathbf{0} && \text{(axiom 4)} \\ \Rightarrow k(\mathbf{0} + \mathbf{0}) &= k\mathbf{0} \\ \Rightarrow k\mathbf{0} + k\mathbf{0} &= k\mathbf{0} && \text{(axiom 7)} \\ \Rightarrow k\mathbf{0} + k\mathbf{0} + (-k\mathbf{0}) &= k\mathbf{0} + (-k\mathbf{0}) && \text{(axiom 5)} \\ \Rightarrow k\mathbf{0} &= \mathbf{0} && \text{(axiom 5)} \end{aligned}$$

31. The first quadrant of  $R^2$ :  $Q_1 = \{(x, y) | x \geq 0, y \geq 0\}$  is not closed under scalar multiplication and therefore not a vector space.

The union of  $Q_1$  and the third quadrant  $Q_3 = \{(x, y) | x \leq 0, y \leq 0\}$  is closed under scalar multiplication but *not* under addition.

32. • A set containing the zero vector is always dependent.

• The subset  $\{(3, -1), (4, 5), (-4, 34)\}$  of  $R^2$  is dependent since it contains more than two vectors.

• The set  $\{(1, 2, 3), (-2, -4, -6)\}$  is dependent since the second vector is a multiple of the first.

• The set  $\{(1, 2), (3, 4)\}$  is an independent set since  $\alpha_1 \begin{pmatrix} 1 \\ 2 \end{pmatrix} + \alpha_2 \begin{pmatrix} 3 \\ 4 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$  implies that:  $\alpha_1 + 3\alpha_2 = 0$ ,  $2\alpha_1 + 4\alpha_2 = 0$ , and the unique solution to this homogeneous system is the trivial solution.

33. Let  $z_1 = 1 - 5i$  and  $z_2 = 3 + 4i$ . We have:

- $|z_1|^2 = 1^2 + (-5)^2 = 26$
- $z_1 z_2 = 3 - 20i^2 + 4i - 15i = 23 - 11i$
- $\overline{z_2} = 3 - 4i$
- $\frac{z_1}{z_2} = \frac{1 - 5i}{3 + 4i} = \frac{(1 - 5i)(3 - 4i)}{9 + 16} = \frac{1}{25}(-17 - 19i)$
- $iz = 2 - i \Rightarrow z = (2 - i)/i = \frac{2}{i} - 1 = \frac{2i}{-1} - 1 = -1 - 2i$

34. Let  $z = 1 + i = \sqrt{2} \left( \frac{1}{\sqrt{2}} + i \frac{1}{\sqrt{2}} \right) = \sqrt{2}(\cos \pi/4 + i \sin \pi/4)$ . We have:

$$\begin{aligned} z^3 &= 2\sqrt{2} \left( \cos \frac{3\pi}{4} + i \sin \frac{3\pi}{4} \right) \\ z^{\frac{1}{2}} &= 2^{\frac{1}{4}} \left( \cos \frac{\pi}{8} + i \sin \frac{\pi}{8} \right) \\ \text{or } z^{\frac{1}{2}} &= 2^{\frac{1}{4}} \left( \cos \left( \frac{\pi}{8} + \pi \right) + i \sin \left( \frac{\pi}{8} + \pi \right) \right) = 2^{\frac{1}{4}} \left( \cos \frac{-3\pi}{8} + i \sin \frac{-3\pi}{8} \right) \end{aligned}$$

35. Let  $z = 3e^{-i\pi}$ . We have:  $z = 3(\cos \pi + i \sin \pi) = -3$ . Also:  $\operatorname{Re}(z) = -3$ ,  $\operatorname{Im}(z) = 0$  and  $|z| = 3$ .