

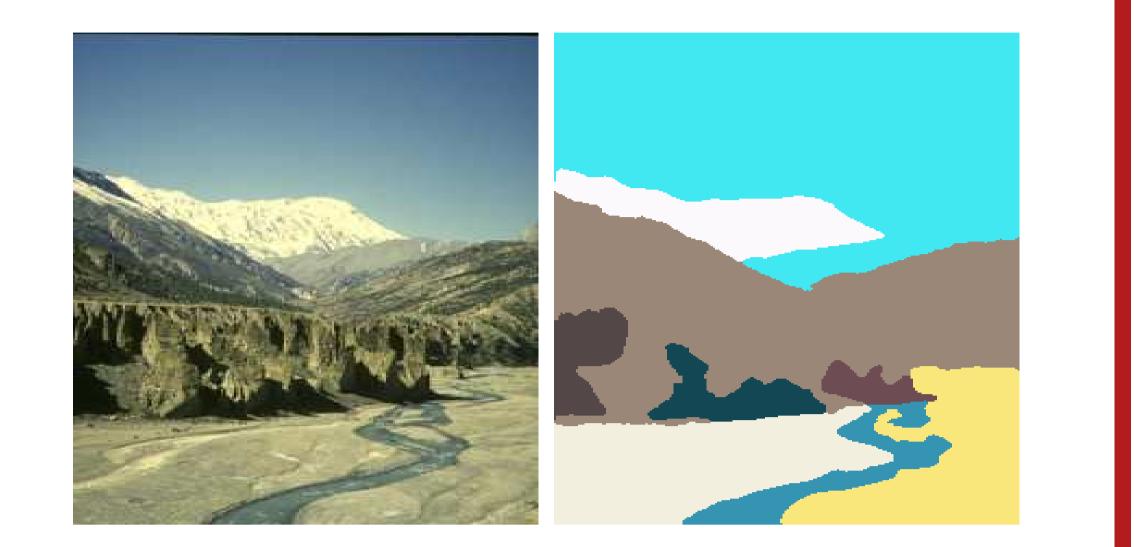
# A NEW MULTI-CRITERIA FUSION MODEL FOR COLOR TEXTURED IMAGE SEGMENTATION

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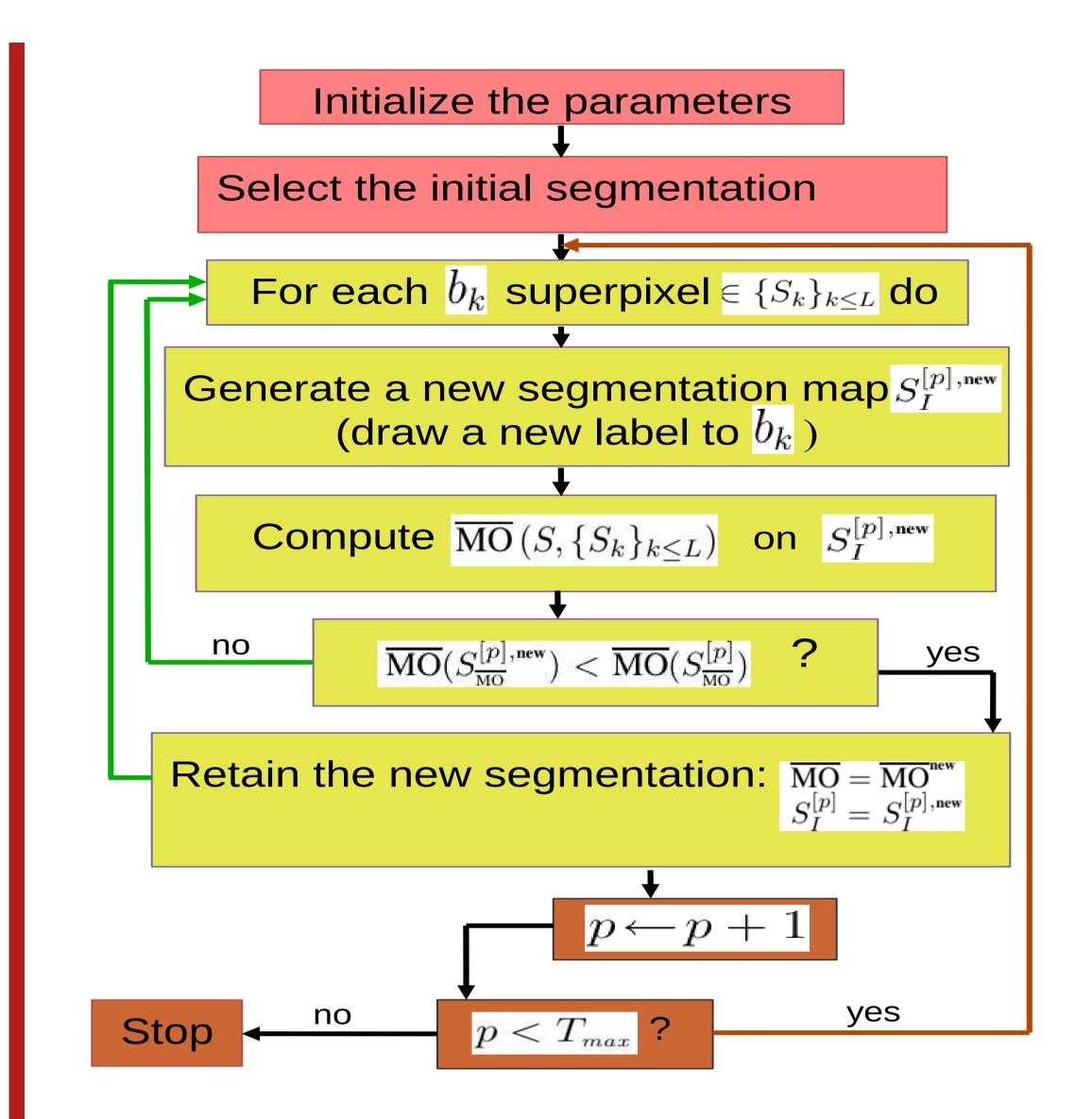
 Image segmentation aims to divide an image into several disjoint regions with uniform and homogeneous attributes

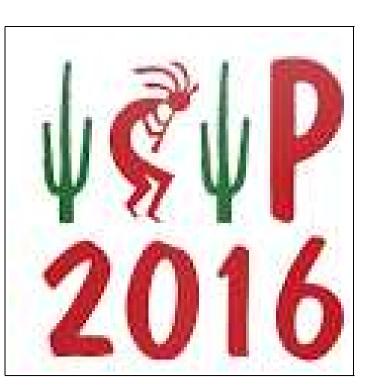


- $F_{\alpha}$ = 1  $\checkmark$  Similar boundaries exists between the two segmentations to be compared
- $F_{\alpha} = 0$   $\checkmark$  Maximum difference of boundaries between the two segmentations

## **Region-based Vol criterion**

- Based on the entropy
- Measures the amount of information that is lost





## **Problem:**

• Fusion of image segmentations based on the optimization of a single criterion may bias the performance of an image segmentation model

Key Idea 1: Combining multiple, quickly estimated segmentation maps of the same image to obtain a final refined segmentation



or gained in changing from one clustering to another

 $Vol(S^{a}, S^{b}) = H(S^{a}) + H(S^{b}) - 2l(S^{a}, S^{b})$  (2)

#### with

$$\begin{split} \mathsf{H}(S^{*}) &= -\sum_{i=1}^{R^{*}} \mathsf{P}(\mathsf{i}) \log \mathsf{P}(\mathsf{i}) = -\sum_{i=1}^{R^{*}} (\frac{n_{i}^{a}}{n}) \log (\frac{n_{i}^{a}}{n}) (\mathsf{3}) \\ \mathsf{H}(S^{*}) &= -\sum_{j=1}^{R^{*}} \mathsf{P}(\mathsf{j}) \log \mathsf{P}(\mathsf{j}) = -\sum_{j=1}^{R^{*}} (\frac{n_{j}^{b}}{n}) \log (\frac{n_{j}^{b}}{n}) (\mathsf{4}) \end{split}$$

 $I(S^{a}, S^{b}) = \sum_{i=1}^{R^{a}} \sum_{j=1}^{R^{b}} P(i,j) \log \left(\frac{P(i,j)}{P(i).P(j)}\right)$ (5)

#### where

 $S^{a} = \{C_{1}^{a}, C_{2}^{a}, \dots, C_{R^{a}}^{a}\}$ : Segmentation  $S^{b} = \{C_{1}^{b}, C_{2}^{b}, \dots, C_{R^{b}}^{b}\}$ : Segmentation n: Number of pixels within the image  $n_{i}^{a}$ : Number of pixels in the  $i^{th}$  cluster i of  $S^{a}$ 

## **Results**

Performances on the BSDS300

Algorithms	Vol $\downarrow$	$\textbf{BDE}\downarrow$	$\textbf{GCE}\downarrow$	PRI ↑
Humans	1.10	4.99	80.0	0.87
EFA-BMFM	1.87	8.16	0.19	0.80
VOIBFM [2]	1.88	8.49	0.21	0.81
FCR [3]	2.30	8.99	0.21	0.79

Distribution of the BDE and PRI measures over the 300

P(i) =  $n_i^a/n$ : Probability that a pixel belongs to cluster  $S^a$ P(i,j) =  $n_{ij}/n$ : Probability when a pixel  $\in$  to  $C_i^a$  and to  $C_j^b$ 

VoI= 0 A Maximum similarity between the tow segmentation

• *VoI* = 1 A Maximum difference between the two segmentations

Multi-criteria fusion model based on the entropy-weighted formula approach (EFA-BMFM)

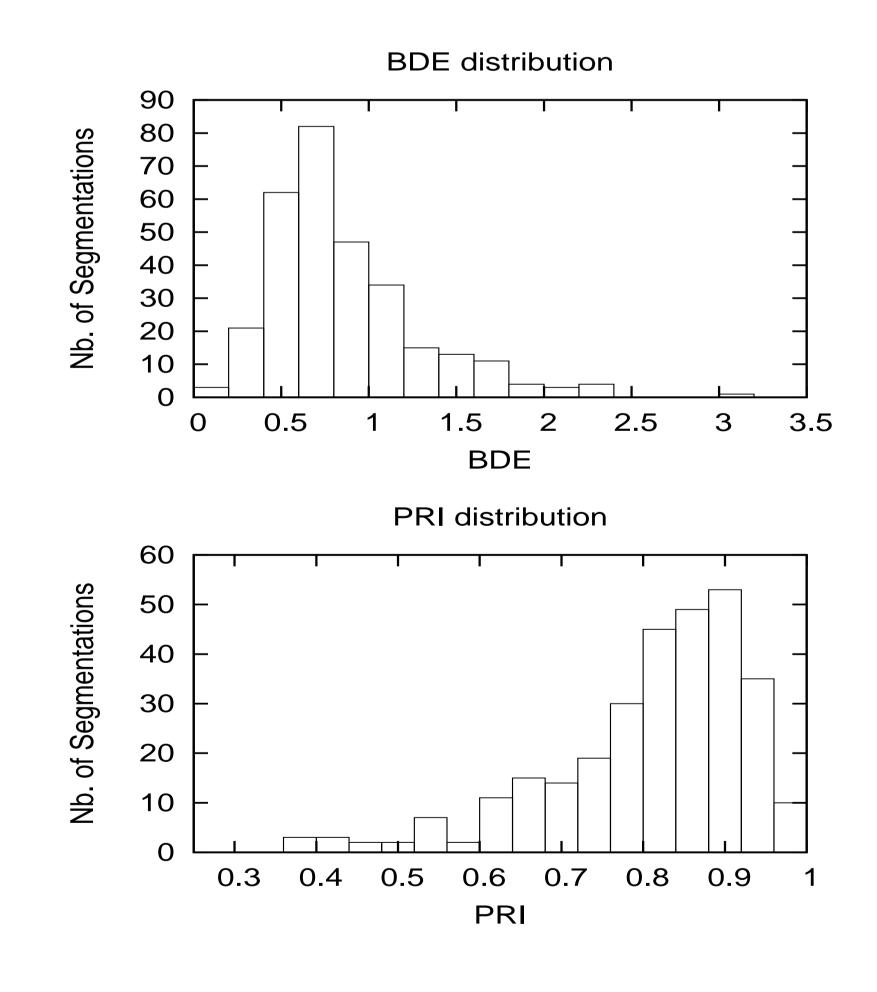
$$\hat{S}_{\overline{\mathsf{MO}}} = \arg\min_{S\in\mathcal{S}_n} \overline{\mathsf{MO}}\left(S, \{S_k\}_{k\leq L}\right)$$

(6)

with

$$\overline{\mathsf{MO}}(.) = \mathbf{w}_{vol} \overline{\mathsf{Vol}}(S, \{S_k\}_{k \le L}) + \frac{\mathbf{w}_{F}}{\overline{\mathsf{F}}_{\alpha}(S, \{S_k\}_{k < L})}$$
(7)

#### segmented images of the BSDS300

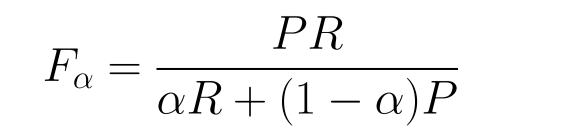


Example of segmentations result

Key Idea 2: Combining two conflicting and complementary segmentation criteria

**Contour-based F-measure criterion** 

• A combination of two complementary measures; precision (P) and recall (R)

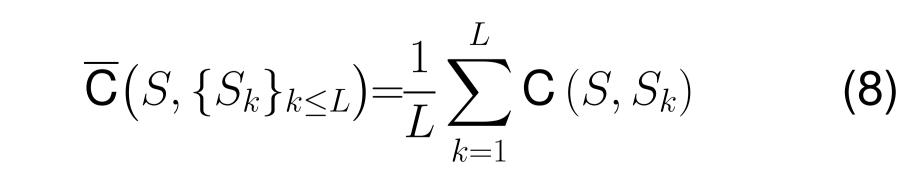


with

 $\alpha$ : Relative cost between P and R

where

(1)



## Optimization

 Based on the ensemble of regions provided by each individual segmentations to be fused

Algorithm: Iterative Conditional Modes (ICM)
[1]



## References

[1] J. Besag. On the statistical analysis of dirty pictures. *Journal of the Royal Statistical Society.*, B-48:259–302, 1986.

[2] M. Mignotte. A label field fusion model with a variation of information estimator for image segmentation. *Inf. Fusion*, 20(0):7–20, 2014.

[3] M. Mignotte. Segmentation by fusion of histogram-based K-means clusters in different color spaces. *IEEE Trans. Image Process.*, 17:780–787, 2008.