

Lecture 21 - scribbles - more optimization

Friday, March 31, 2017
15:02

- SAG for CRF
- proximal method, acceleration & non-convexity

SAG for CRF:

$$-\nabla f_i(w) = \sum_c \sum_{\tilde{y}_c} p(\tilde{y}_c | x^{(i)}, w) \psi_i(\tilde{y}_c)$$

$\Rightarrow$ store $(p(\tilde{y}_c | x^{(i)}, w))_{\tilde{y}_c, c}$ in memory for SAG/SAGA correction

uses other tricks: • NUS

- line search on step-size $\Rightarrow$ this requires marginal inference "oracle call" for every step-size tried

SAG for CRF

CEC

SDCA

a stochastic dual coordinate ascent

$$w^{(t+1)} = (1 - \lambda \delta_t) w^{(t)} - \delta_t \left[\nabla f_i(w^{(t)}) - g_i^t + \frac{1}{n} \sum_j g_j^t \right]$$

$$\alpha_i(\tilde{y})^{(t+1)} \propto \alpha_i(\tilde{y})^{(t)} \exp(-\delta_t \nabla_{\alpha_i(\tilde{y})} f(\alpha^{(t)}))$$

$$\text{do } \alpha_i(\tilde{y})^{(t+1)} = (1 - \delta_t) \alpha_i(\tilde{y})^{(t)} + \delta_t \tilde{S}_i(\tilde{y})^{yes}$$

$$w^{(t)} = A \alpha^{(t)}$$

$$\rightarrow \left[\dots \frac{1}{\lambda n} \psi_i(\tilde{y}) \right]$$

get this using "marginal inference"

[roughly: line search on $H(\alpha_k)$ $\leftarrow$ 1d line search]

Proximal gradient method:

- semi-minimization or Alternated gradient method for other non-smooth functions

→ generalization of projected gradient method to other non-smooth functions

composite framework: $F(w) = f(w) + \Omega(w)$ where f is convex and L -smooth

indicator of M but Ω is convex, not necessarily smooth

constrained opt. setting: $\Omega(w) = \begin{cases} 0 & \text{if } w \in M \\ +\infty & \text{otherwise} \end{cases}$

ℓ_1 -regularization: $\Omega(w) = \lambda \|w\|_1$

proximal gradient algorithm:

$$w_{t+1} = \arg \min_w \underbrace{f(w_t) + \langle \nabla f(w_t), w - w_t \rangle}_{B_t(w)} + \underbrace{\frac{1}{2\delta_t} \|w - w_t\|^2}_{\text{proximity term}} + \Omega(w)$$

if $\delta_t \leq \frac{1}{L}$; then $f(w) \leq B_t(w) \quad \forall w$

we can rewrite $B_t(w) = \frac{1}{2\delta_t} \|w - [w_t - \delta_t \nabla f(w_t)]\|^2 + \text{cst.}$ (by completing the square)

aside:

optimality condition on $F(w)$:

$$w^* = \arg \min_{w \geq 0} (w^* - \delta_t \nabla f(w^*))$$

$$w_{t+1} = \text{Prox}_{\delta_t}^{\Omega} (w_t - \delta_t \nabla f(w_t))$$

inf convolution

$$(\Omega \square \|\cdot\|_{\delta_t}^2)(z) = \inf_w \Omega(w) + \frac{1}{2\delta_t} \|w - z\|^2$$

$$\text{"proximal operator"}: \text{prox}_{\delta}^{\Omega}(z) \triangleq \arg \min_w \left\{ \Omega(w) + \frac{1}{2\delta} \|w - z\|^2 \right\}$$

strongly convex
⇒ unique minimizer

like for project, prox is non-expansive i.e. 1-Lipschitz

$$\text{i.e. } \|\text{prox}_{\delta}^{\Omega}(w) - \text{prox}_{\delta}^{\Omega}(w')\|_2 \leq \|w - w'\|_2$$

⇒ rates for unconstrained gradient method

transfer to proximal analog
 * to be useful, we need prox_γ^2 to be efficiently computable

$$\text{prox}_\gamma^2(z) = \arg\min_w \|w\|_2 + \frac{1}{2\gamma} \|w - z\|^2$$

$$\text{"soft-thresholding"} = \begin{cases} \text{sgn}(z) [|z| - \gamma] & \text{if } |z| \geq \gamma \\ 0 & \text{o.w.} \end{cases}$$

Catalyst algorithm [Lin, Maillard & Hachem NIPS 2015]

"meta-algorithm": outer loop which uses a linearly convergent alg.
 in the inner loop
 to get overall acceleration

main idea: use the accelerated proximal point algorithm
 with approximation in inner loop of prox operator

proximal point algorithm: is proximal gradient with $f \equiv 0$
 $w_{t+1} = \text{prox}_\gamma^2(w_t)$

Catalyst alg.: (for μ -strongly convex F)

let $q \triangleq \frac{\mu}{\mu+1}$ (γ is algorithmic parameter)

repeat:

$$w_{t+1} \approx \arg\min_w F(w) + \frac{1}{2\gamma} \|w - z_t\|^2 \quad \text{s.t.} \quad G_t(w_{t+1}) - \min_w G_t(w) \leq \frac{\gamma}{t}$$

to be specified

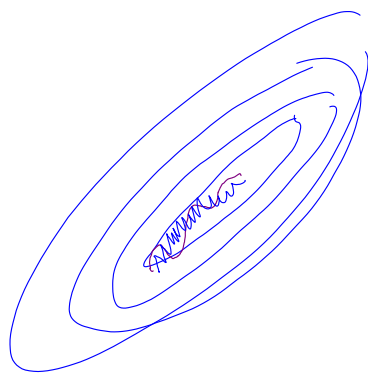
$\mathbb{E} G_t(w)$
 (using our inner alg. [e.g. SAGA FW])

(accelerated Nesterov ;
 trick piece) $Z_{t+1} = w_{t+1} + \beta_{t+1} (w_{t+1} - w_t)$
 like a 'momentum'

where β_{t+1} is found using fancy equation so that everything works
extrapolation

solve for α_{t+1} in equation $\alpha_{t+1}^2 = (1 - \alpha_{t+1}) \alpha_t^2 + \alpha_{t+1}$
 (pick $\alpha_{t+1} \in [0, 1]$)

$$\beta_{t+1} \triangleq \frac{\alpha_t (1 - \alpha_t)}{\alpha_t + \alpha_{t+1}}$$



Catalyst trick is: use γ and ϵ_0 .

s.t. overall # of inner loop calls give acceleration

with clever analysis of warm starting, strong convexity of inner loop problem
 result is is inner loop alg. has convergence $\exp(-\frac{\gamma}{L} t)$
 then with correct constants

go from $\frac{1}{\epsilon} \rightarrow \frac{1}{\epsilon^2}$ for outer loop convex minimization

$\frac{1}{K} \rightarrow \frac{1}{\sqrt{K}}$ for strongly convex case

Non-convex optimization:

convex: $\mathbb{E} f(w_t) - f^* \leq \epsilon_0$

non-convex: $\mathbb{E} \|\nabla f(w_t)\|^2 \leq \epsilon_0$

non-convex : $\mathbb{E} \|\nabla f(w_t)\|^2 \leq \epsilon$

$$\left(\begin{aligned} f(w) &\leq f(w_t) + \langle \nabla f(w_t), w - w_t \rangle + \frac{L}{2} \|w - w_t\|^2 \\ w_{t+1} &= w_t - \frac{1}{L} \nabla f(w_t) \\ f(w_{t+1}) &\leq f(w_t) - \frac{1}{2L} \|\nabla f(w_t)\|^2 \end{aligned} \right)$$

NIPS 2016 tutorial "Large-Scale Optimization: Beyond Stochastic Gradient Descent and Convexity"

[Suvri Sra slides](#)

Faster nonconvex optimization via VR

(Reddi, Hefny, Sra, Póczos, Smola, 2016; Reddi et al., 2016)

Algorithm	Nonconvex (Lipschitz smooth)
SGD	$O\left(\frac{1}{\epsilon^2}\right)$
GD	$O\left(\frac{n}{\epsilon}\right)$
SVRG	$O\left(n + \frac{n^{2/3}}{\epsilon}\right)$
SAGA	$O\left(n + \frac{n^{2/3}}{\epsilon}\right)$
MSVRG	$O\left(\min\left(\frac{1}{\epsilon^2}, \frac{n^{2/3}}{\epsilon}\right)\right)$

$$\mathbb{E}[\|\nabla g(\theta_t)\|^2] \leq \epsilon$$

Remarks

New results for convex case too; additional nonconvex results

For related results, see also (Allen-Zhu, Hazan, 2016)

Linear rates for nonconvex problems

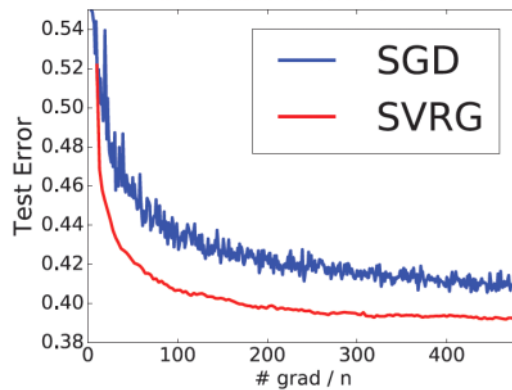
$$g(\theta) - g(\theta^*) \leq \frac{1}{2\mu} \|\nabla g(\theta)\|^2 \quad \Bigg| \quad \mathbb{E}[g(\theta_t) - g^*] \leq \epsilon \quad \text{😎}$$

Algorithm	Nonconvex	Nonconvex-PL
SGD	$O\left(\frac{1}{\epsilon^2}\right)$	$O\left(\frac{1}{\epsilon^2}\right)$
GD	$O\left(\frac{n}{\epsilon}\right)$	$O\left(\frac{n}{2\mu} \log \frac{1}{\epsilon}\right)$
SVRG	$O\left(n + \frac{n^{2/3}}{\epsilon}\right)$	$O\left((n + \frac{n^{2/3}}{2\mu}) \log \frac{1}{\epsilon}\right)$
SAGA	$O\left(n + \frac{n^{2/3}}{\epsilon}\right)$	$O\left((n + \frac{n^{2/3}}{2\mu}) \log \frac{1}{\epsilon}\right)$
MSVRG	$O\left(\min\left(\frac{1}{\epsilon^2}, \frac{n^{2/3}}{\epsilon}\right)\right)$	—

Variant of **nc-SVRG** attains this fast convergence!

(Reddi, Hefny, Sra, Póczos, Smola, 2016; Reddi et al., 2016) 22

Empirical results



CIFAR10 dataset; 2-layer NN

Pointers

- SAG for CRF paper:
 - Non-Uniform Stochastic Average Gradient Method for Training Conditional Random Fields
M. Schmidt, R. Babanezhad, M.O. Ahmed, A. Defazio, A. Clifton, A. Sarkar
[AISTATS 2015](#) | [code](#)
- Proximal gradient method
 - see [slides](#) of this [great optimization class by L. Vandenberghe](#)
- Catalyst -- meta-algorithm for acceleration:
 - A Universal Catalyst for First-Order Optimization
Hongzhou Lin, Julien Mairal, Zaid Harchaoui
[NIPS 2015](#)
- non-convex optimization:
 - see [slides](#) from Suvrit Sra at the NIPS 2016 tutorial on "Large-Scale Optimization: Beyond Stochastic Gradient Descent and Convexity" (e.g. table of rates on p. 20 and 22)

Other good optimization pointers:

- great coverage of convex optimization by Mark Schmidt at the Machine Learning Summer School in 2015) - [slides](#) | [video](#)
- two great classes on optimization:
 - EE236C - Optimization Methods for Large-Scale Systems (Spring 2016) - Prof. L. Vandenberghe, UCLA - [link](#)
 - Convex optimization class by Rayn Tibshirani at CMU - Fall 2015 - [link](#)
 - [slides](#) on the Frank-Wolfe lecture
 - [nice summary table](#)
- tutorial by Francis Bach on SAG et al. at NIPS 2016 -- [slides](#)