

Lecture 18 - BCFW

Thursday, March 14, 2019 13:37

today: • FW & FCFW on SUMstruct
• BCFW

continue FW for SUMstruct

FW on dual is equivalent to both subgradient update on primal with step-size relationship
 $\alpha^{(t)} \rightarrow w^{(t)} = A\alpha^{(t)}$
 $\gamma^{(FW)} = \lambda \beta^{(\text{subgradient})}$

recall: subgradient method converges at $O(\frac{1}{\epsilon})$
 when step-size $\rho_t \leq \frac{1}{\mu} O(\frac{1}{t})$

FW method with fixed step-size schedule

$$\gamma_t = \frac{2}{t+2}$$

gives $d(\alpha^*) - d(\alpha^{(t)}) \leq \frac{2C_g}{t+2}$

* FW-gap

$$\begin{aligned} & \langle -\nabla f(\alpha^{(t)}), s^{(t)} - \alpha^{(t)} \rangle \\ &= \frac{1}{n} \sum_{i=1}^n \left[H_i(\hat{y}_i^{(t)}; w^{(t)}) - \sum_{\tilde{y} \in \mathcal{Y}_i} \alpha_i^{(t)}(\tilde{y}) H_i(\tilde{y}; w^{(t)}) \right] \end{aligned}$$

$$= \rho(w(\alpha^{(t)})) - d(\alpha^{(t)}) \quad (\text{Lagrangian gap of lecture 18})$$

here, FW-gap = Lagrangian gap on $(w(\alpha^{(t)}), \alpha^{(t)})$

* recall that FW-gap

$$\begin{array}{c} d(\alpha^{(t)}) \quad p(w^{(t)}) = d(\alpha^*) \quad p(w^{(t)}) \\ \underbrace{\quad \quad \quad}_{\text{dual subpl.}} \quad \underbrace{\quad \quad \quad}_{\text{primal side}} \end{array}$$

note: FW gap is not always Lagrangian gap

* recall, that $\min_{s \leq t} g_s^{\text{FW gap}} \leq 3 \cdot \frac{2C_f}{t+2}$

[note: FW gap is not always Lagrangian gap]
e.g. CFF objective (dual)

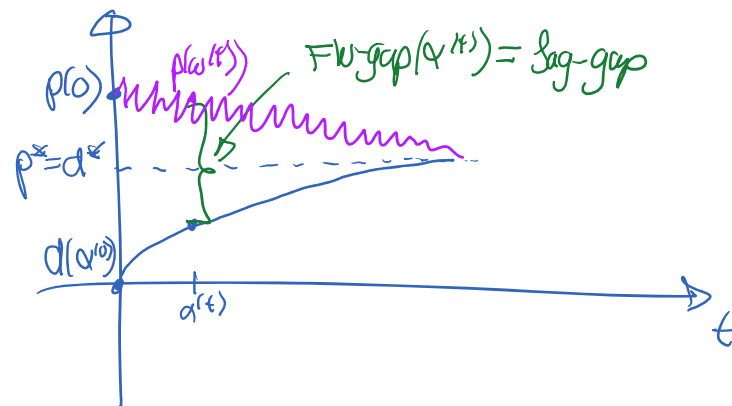
$\Rightarrow$ guarantees on $p(w^{(t)}) - p(w^*)$?

also, $g^{\text{FW}}(\hat{x}_{w^*}^{(t)}) \leq 3 \cdot \frac{2C_f}{t+2}$
 $\uparrow$
 weighted average

when $g(\cdot)$ is convex [this is the case when f is quadratic]

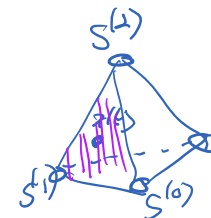
$$p(0) = \frac{1}{n} \sum_{i=1}^n \max_{\tilde{y}} R_i(\tilde{y}) = \bar{L}_{\max}$$

$$d(\alpha^{(0)}) = 0$$



FCFW "fully corrective FW" variant:

algorithm: re-optimize f over convex hull $(\{S^{(u)}\}_{u=0}^t)$
 $\uparrow$
 FW cones



$\rightarrow$ think of it as doing "fancy line-search" on the correction solution

note: could use Affine

→ think of it as doing "fancy line-search"
on the correction polytope

n.b.: could use
AFW to
do correction step

[special case: min norm point alg. (MNP)]
→ state of art alg. for submodular gpts

↳ sequence of affine projections
+ line search

(see "banier FW" paper)

turns out that (batch) FFW on dual of SVM struct

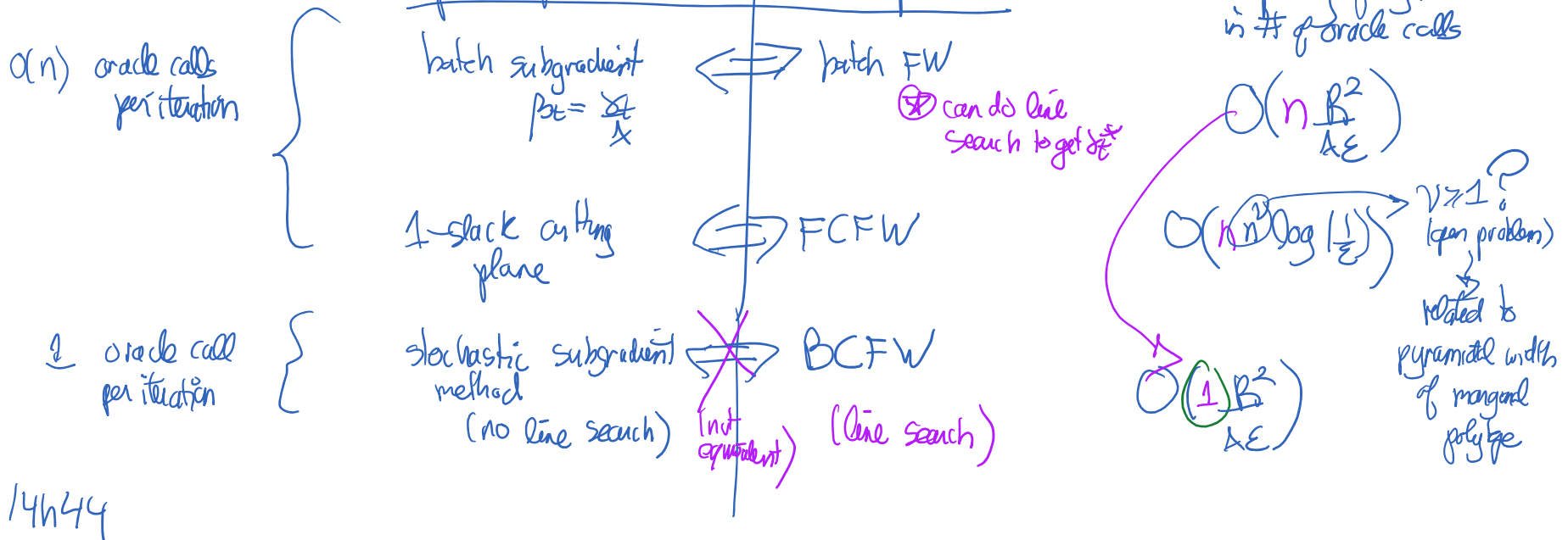
is equivalent to the constraint generation / cutting plane
approach on 1-slack formulation

why? every $s^{(t)}$ corresponds $\{\hat{y}_i^{(t)}\}_{i=1}^n$

$$\alpha \in \text{conv}(\{s^{(u)}\}_{u \in t}) \quad \alpha = \sum_{u \in t} \tilde{\varphi}_u s^{(u)}$$

$$w = A\alpha = \sum_{u \in t} \hat{\varphi}_u \left(\frac{1}{\Delta n} \sum_{i=1}^n \psi_i(\hat{y}_i^{(u)}) \right)$$

to summarize:



Block-coordinate optimization

"huge scale" optimization $\rightarrow$ [Nesterov 2010-2012]

proposed: randomized block-coordinate projected gradient method

Setup: $\min f(x)$
 $s.t. x \in \prod_{i=1}^n M_i$
 $x = (\underbrace{x_1, \dots, x_n}_{\text{block}})$

algorithm: pick at random i

then let $x_i^{(t+1)} = \text{Proj}_{M_i} \left(x_i^{(t)} - \frac{1}{L_i} \nabla_i f(x^{(t)}) \right)$
 $x_j^{(t+1)} = x_j^{(t)} \quad \forall j \neq i$

L_i is Lipschitz constant of $\nabla_i f(x^{(t)})$

$$\mathcal{I} = \underbrace{1, 2, \dots, n}_{\text{block}}$$

$$\begin{cases} x_j^{(t+1)} = x_j^{(t)} & \forall j \neq i \\ L_i \end{cases}$$

[only update block i at iteration t]

Nesterov showed (uniform sampling)

$$\mathbb{E} f(x^{(t)}) - f(x^*) \leq \frac{2}{t+1} \left[\sum_{i=1}^n L_i \right] \|x_0 - x^*\|^2$$

(for convex f with L_i -Lipschitz gradient per block)

(*) aside: in constrained optimization, $-\frac{1}{\delta_t}(x^{(t+1)} - x^{(t)})$ plays the role of $\nabla f(x^{(t)})$

Block-coordinate FW (BCFW): idea: do a FW step on block i

alg: for $t=0, \dots$

pick i uniformly at random

let $s_i^{(t)} = \arg \min_{s_i \in M_i} \langle s_i, \nabla_i f(x^{(t)}) \rangle$ [FW corner for block i]

$$\begin{cases} x_i^{(t+1)} = x_i^{(t)}(1-\gamma_t) + \gamma_t s_i^{(t)} \\ x_j^{(t+1)} = x_j^{(t)} & \text{for } j \neq i \end{cases}$$

$$\gamma_t = \begin{cases} \text{line search:} \\ \arg \min_{\gamma \in [0,1]} f(x^{(t)} + \gamma(s_{[i]}^{(t)} - x_{[i]}^{(t)})) \end{cases}$$

$2n$ $\rightarrow$ # of blocks
 $t+2n$

$$s_{[i]} = \begin{pmatrix} 0 \\ 0 \\ s_i \\ 0 \\ 0 \end{pmatrix}$$

(*) an important property: FW-gap = $\max_{s \in \mathcal{S}} \langle \nabla f(x), s - x \rangle = \sum \max_{s_i \in M_i} \langle \nabla_i f(x), s_i - x_i \rangle$

product structure $\downarrow$

⊛ an important property: $\text{FW-gap} = \max_{S \in M} \langle -\nabla f(x), S-x \rangle = \sum_i \max_{S_i \in M_i} \langle -\nabla f(x), S_i - x_i \rangle$

$$g^{\text{FW}}(x) = \sum_i g_i^{\text{FW}}(x)$$

$g_i(x)$ "block FW gap"

as before, can show $g_i(x) \geq f(x) - \min_y \sum_j \langle \nabla f(x), y_j - x_j \rangle$

↳ motivated "gap sampling" variant [Osokin et al. ICML 2016]

Convergence result for BCFW:

$$C_g^{(i)} \leq L_i \text{diam}(M_i)^2$$

$$C_g^{\otimes} \triangleq \sum_{i=1}^n C_g^{(i)}$$

$$\underbrace{\mathbb{E}[f(x^{(t)}) - f(x^*)]}_{\triangleq \varepsilon_t} \leq \frac{2n}{t+2n} [C_g^{\otimes} + f(x^{(0)}) - f(x^*)] \quad \text{for } \delta_t = \frac{2n}{t+2n}$$

if you use line search: $\varepsilon_t \leq \frac{2n C_g^{\otimes}}{t-t_0+2n}$
for $t \geq t_0$

where $t_0 \leq n \log 2 \frac{f(x^{(0)}) - f(x^*)}{C_g^{\otimes}}$

time to ensure $\varepsilon_t \leq C_g^{\otimes}$

one can show that $C_g^{\otimes} \leq C_g$ for quadratic functions

compare batch FW $\rightarrow \frac{2C_g}{t+2}$

vs.
BCFW with line $\rightarrow \frac{2n C_g^{\otimes}}{t-t_0+2n}$

VS,
BCFW with line search $\rightarrow \frac{2n \log^2}{\epsilon - \epsilon_0 + 2n}$

but BCFW is often n times cheaper than batch FW

$\Rightarrow$ BCFW is "never" slower than batch FW

complexity
of oracle calls
to reach ϵ -error
FW: $O\left(\frac{n \log^2}{\epsilon}\right)$

BCFW: $O\left(\frac{n \log^2}{\epsilon}\right)$