

Lecture 6 - scribbles - generalization error bounds

Thursday, January 24, 2019 13:36

today: • generalization error bounds
 & structural SVM

generalization error bounds

for binary classification,

a classical PAC bound is:

$$\text{for any fixed dist. } p \text{ on data with prob. } 1-\delta \text{ over } D_n$$

$$\forall w \in \mathcal{W} \quad L(w) \leq \hat{L}_n(w) + \frac{1}{\sqrt{n}} \sqrt{d \log d + \log \frac{2}{\delta}}$$

where d is VC-dimension

$$\mathcal{H} = \{h_w : w \in \mathcal{W}\}$$

VC-dimension of $\mathcal{H} \triangleq \max \{m : \exists \text{ a set of } m \text{ pts, s.t. } \forall \text{ labelings of those points, } \exists w \text{ s.t. } h_w \text{ gives the correct label on those points}\}$
 "shattering the set of pts"

of prediction functions on m pts. is 2^m

for linear classifiers of p parameters, VC-dim = $p+1$

* one issue for this bound is that is true for all distributions $\Rightarrow$ too loose bound

$\Rightarrow$ motivates going to data distribution dependent

⇒ motivates going to data distribution dependent
measure of complexity

example: empirical Rademacher complexity

$$\hat{R}_{D_n}(\mathcal{H}) \triangleq \mathbb{E}_{\sigma} \left[\sup_{h \in \mathcal{H}} \left| \frac{2}{n} \sum_{i=1}^n \sigma_i 1\{y_i \neq h(x_i)\} \right| \right]$$

"correlations
with random noise"

$\sigma_i = \begin{cases} +1 \\ -1 \end{cases}$ uniformly "Rademacher" R.V.

bound:

with prob $\geq 1-\delta$

$$\forall w \quad L(w) \leq \hat{L}_n(w) + \hat{R}_{D_n}(\mathcal{H}) + \frac{1}{\sqrt{n}} 3 \sqrt{\log \frac{2}{\delta}}$$

complexity depends on D_n (implicitly on $\mathcal{P}$)

high level idea to prove bound:

"double sample trick" → use a second sample D_n' for gen. error. $L(w) = \mathbb{E}_{D_n'} [\hat{L}_n(w)]$

+
"symmetrization trick" → bound sup of differences between $L(w)$ & $\hat{L}_n(w)$

+
union bound as used + concentration inequality

Structured prediction generalization bounds [Cortes & al. NIPS 2016]

general loss $l(y, y')$ s.t. $l(y, y') \neq 0$ if $y \neq y'$

suppose $S(x, y) = \sum_{C \in \mathcal{C}} S_C(x, y_C)$

$\rightarrow$ set of cliques of a graph. model factor factor

thm. 7 with prob $\geq 1 - \delta$ depends on $l(y, y')$

$$\forall w \in W \quad L(w) \leq \hat{S}_{\text{hinge}}(w) + 4\sqrt{2} \hat{R}_{D_n}^G(\mathcal{H}_w) + 3 \frac{L_{\max}}{\sqrt{n}} \sqrt{\log \frac{1}{\delta}}$$

where $\hat{R}_{D_n}^G \triangleq \frac{1}{n} \mathbb{E}_S \left[\sup_{w \in W} \sum_{i=1}^n \sqrt{|\mathcal{C}_i|} \sum_{C \in \mathcal{C}_i} \sum_{y_C \in \mathcal{Y}_C} \sigma_{i, C, y_C} S_C(x_i, y_C; w) \right]$

only depends $(x^{(i)})_{i=1}^n$

"empirical factor graph complexity"

set of labels for y_C

Rademacher r.v.

thm. 2: if $S_C(x, y_C; w) = \langle w, \varphi_C(x, y_C) \rangle$

and consider $W_\Lambda \triangleq \{w : \|w\|_2 \leq \Lambda\}$; let $R = \max_{i, C, \tilde{y}} \|\varphi_C(x_i, \tilde{y})\|_2$

then $\hat{R}_{D_n}^G(\mathcal{H}_{W_\Lambda}) \leq \frac{R \Lambda}{\sqrt{n}} |\mathcal{C}| \sqrt{\max_C |\mathcal{Y}_C|}$

so want small degrees?

back to bound: $L(w) \leq \hat{S}_{\text{hinge}}(w) + \left(\frac{R |\mathcal{C}| \sqrt{\max_C |\mathcal{Y}_C|}}{\sqrt{n}} \right) \Lambda$

back to bound: $L(w) \leq \text{Shinge}(w) + \underbrace{\left(\frac{K|E|}{\sqrt{n}} \max |f_c| \right)}_{\lambda_n} \underbrace{\|w\|_2}_{\lambda_n}$

min of RHS suggests

SVM struct dg. $\hat{w}_n = \arg \min_w \text{Shinge}(w) + \frac{\lambda_n \|w\|_2^2}{2}$

missing link: (1) $\min_{\text{st. } \|w\| \leq R} f(w)$ (if f is convex) $\xrightarrow{\text{use Lagrangian duality}} \exists a \lambda \in \mathbb{R}_+ \text{ st. } \min f(w) + \frac{\lambda \|w\|_2^2}{2}$ (2)
gives same solution as (1)

side note: penalized formulation less sensitive to choice of λ vs. constrained formulation

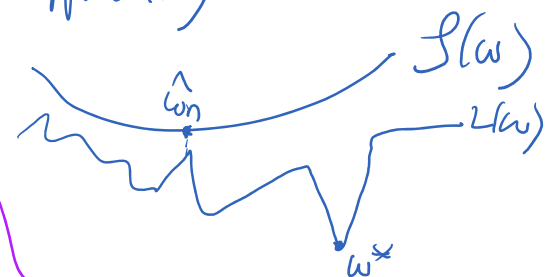
can think of SVM struct as minimizing upper bound on generalization error

properties:

- minimizes upper bound, hope that minimizes app. $L(w)$

but no general guarantees?

- can evaluate bound to get guarantees



correct:
here, no consistency
guarantee

next: consistency...

next: consistency
14h34

guarantee

consistency & calibration def.:

need to relate $Q(w)$ to $L(w)$ = tool "calibration function" [Steinwart]

relationship is usually very complicated

→ current results look mainly at non-parametric setting (no # of parameters)

all functions $h: X \rightarrow Y$ are considered $\Rightarrow$ this evacuates the dependence on x in the analysis

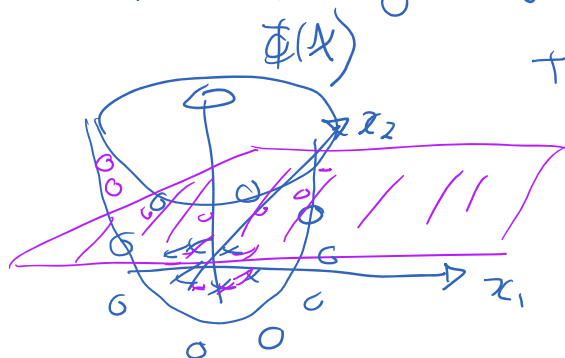
i.e. we suppose that $S(x, y; w)$ can be arbitrary for any x (i.e. w is n -dim) $\rightarrow$ could use a universal kernel

$$S(\cdot, \cdot; w) \in \mathcal{H}_{X \times Y}$$

RKHS

motivation: generalize $\langle w, \phi(x) \rangle$ to higher dim. space

+ kernel trick $\langle \phi(x), \phi(x') \rangle = k(x, x')$



$$\Phi: X \rightarrow \mathbb{R}^3$$

$$\Phi\left(\begin{pmatrix} x \\ y \end{pmatrix}\right) = \begin{pmatrix} x_1^2 \\ \sqrt{2} x_1 x_2 \\ x_2^2 \end{pmatrix}$$

o o

$$\begin{pmatrix} \sqrt{2}x_1x_2 \\ x_2^2 \end{pmatrix}$$

$$\langle \Phi(x), \Phi(x') \rangle_{\mathbb{R}^3} = (\langle x, x' \rangle_{\mathbb{R}^2})^2 = k(x, x')$$

$$\text{polynomial kernel eg. } (\langle x, x' \rangle + 1)^d = \tilde{k}(x, x')$$

equivalent to mapping data to space of dimension exponential in d

$$\langle \Phi(x), \Phi(x') \rangle$$

even have ∞ -dim., e.g. $k(x, x') = \exp(-\frac{\|x - x'\|^2}{2})$ (RBF kernel)

RKHS (Reproducing Kernel Hilbert Space)

$$\Phi: \mathcal{X} \rightarrow \mathcal{H} \quad \text{s.t.} \quad \langle \Phi(x), \Phi(x') \rangle_{\mathcal{H}} = k(x, x') \quad (\text{uniqueness property of RKHS})$$

$$\text{let } \tilde{\mathcal{H}} = \text{span} \{ k(x, \cdot) : x \in \mathcal{X} \}$$

$$\text{e.g. } f \in \tilde{\mathcal{H}} \Rightarrow f = \sum_i \alpha_i k(x_i, \cdot) \quad \text{for some finite } \{x_i\}_{i=1}^{n(f)} \\ \alpha_i \in \mathbb{R}^{n(f)}$$

↳ "pre-Hilbert" space [inner product space]

$$\text{with } \langle f, g \rangle_{\tilde{\mathcal{H}}} \triangleq \sum_{i,j} \alpha_i^f \alpha_j^g \underbrace{k(x_i^f, x_j^g)}_{\langle k(x_i^f, \cdot), k(x_j^g, \cdot) \rangle_{\mathcal{H}}}$$

$$\|f\|_{\tilde{\mathcal{H}}} \triangleq \sqrt{\langle f, f \rangle_{\tilde{\mathcal{H}}}}$$

then RKHS $\mathcal{H}$ is = completion($\tilde{\mathcal{H}}$) using $\|\cdot\|_{\tilde{\mathcal{H}}}$ as your norm

then RKHS H is = completion($\tilde{H}$) using $\|\cdot\|_{\tilde{H}}$ as you norm

ie. add all limit points of $\tilde{H}$ -Cauchy sequences to get H

you could think of $f = \sum_{i=1}^{\infty} \alpha_i k(x_i, \cdot)$

"reproducing" property of H : for $f \in H$

$$\langle f, k(x, \cdot) \rangle_H = f(x)$$

nice property of RKHS, fct. evaluation is cts.

$$\text{mapping } E_x: H \rightarrow \mathbb{R} \\ E_x(f) = f(x)$$

$$|f(x) - g(x)| = |\langle f - g, k(x, \cdot) \rangle_H|$$

$$\stackrel{\text{C.S.}}{\leq} \|f - g\|_H \|k(x, \cdot)\|_H \quad \text{ie. } E_x \text{ is Lipschitz cts.} \\ \text{with } L = \|k(x, \cdot)\|_H$$

⊛ this property
important to do statistics