

today : • FW } FCFW on SVMstruct
 • BCFW

continue FW for SVM struct

FW on dual is equivalent to batch subgradient update on primal with step-size relationship

$$\alpha^{(t)} \rightarrow w^{(t)} = A\alpha^{(t)} \quad \gamma^{(FW)} = \lambda \beta^{\text{subgradient}}$$

recall : subgradient method converges
 of $O(\frac{1}{t})$

$$\text{when step-size } \beta_t \leq \frac{1}{\mu} O(\frac{1}{t})$$

FW method with
 fixed step-size schedule

$$\beta_t = \frac{2}{t+2}$$

$$\text{gives } d(\alpha^*) - d(\alpha^{(t)}) \leq \frac{2C_S}{t+2}$$

* FW-gap :

$$\left\langle -\nabla f(\alpha^{(t)}), s^{(t)} - \alpha^{(t)} \right\rangle$$

$$= \frac{1}{n} \sum_{i=1}^n \left[H_i(\tilde{y}_i; \alpha^{(t)}) - \underbrace{\alpha_i^{(t)}(\tilde{y}_i) H_i(\tilde{y}_i; w^{(t)})}_{\text{gap}} \right]$$

$$= p(w(\alpha^{(t)})) - d(\alpha^{(t)}) \quad [\text{Lagrangian gap of lecture 15}]$$

here, FW-gap = Lagrangian gap on $(w(\alpha^{(t)}), q^{(t)})$

[note: FW gap is not always lag. gap.]

e.g. CRF objective
 (dual)

* recall that

$$\min_{\alpha} g_S \stackrel{\text{FW gap}}{\leq} 3 \cdot \frac{2C_S}{t+2} \quad p(w) = d(\alpha^*)$$

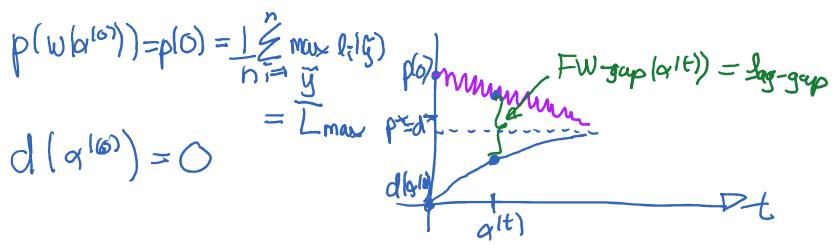
\Rightarrow guarantees on $p(w(\alpha^{(t)})) - p(w^*) + d(\alpha^*) - d(\alpha^{(t)})$
 primal subopt. dual subopt.

$$\text{also, } g^{FW}(\hat{\alpha}_{WT}^{(t)}) \leq 3 \cdot \frac{2C_S}{t+2}$$

weighted avg.

when $g^{FW}(\cdot)$ is convex [this is case when f is a quadratic]

$$p(w(\alpha^{(t)})) = p(0) = \frac{1}{n} \sum_{i=1}^n \max_{\tilde{y}_i} l_i(\tilde{y}_i) \quad p(0) \underset{\text{minimum}}{\text{minimum}} \quad \text{FW-gap}(\alpha^{(t)}) = \text{lag-gap}$$

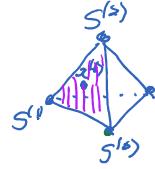


FCFW "Fully corrective FW" variant

algorithm: Re-optimize f over conv-hull ($\{S^{(w)}\}_{w=0}^t$)
FW corners

→ think of it as doing "fancy line-search" on the "correction polytope"

Note: could use AFW to do correction step app.



(see "banner FW" paper)

[special case: min norm pt. alg. MNP] sequence of affine projections + line search
→ state of the art alg. for submodular opt.

* turns out that (batch) FCFW on dual SUMstruct is equivalent to the constraint generation / cutting plane alg. on the 1-slack formulation (primal)

why? every $S^{(t)}$ corresponds $(\hat{y}_i^{(t)})_{i=1}^n$
 $\alpha \in \text{conv}(\{S^{(w)}\}_{w \leq t}) \quad \alpha = \sum_{w \leq t} \tilde{\alpha}_w S^{(w)}$

g strongly convex
 $g(Ax) + b^T x$

"gen. strongly convex"

$$w = A\alpha = \sum_{w \leq t} \tilde{\alpha}_w \left(\frac{1}{\lambda_n} \sum_{i=1}^n \gamma_i (g_i(w)) \right)$$

to summarize:

$O(n)$
oracle calls
per iteration

primal problem

batch subgradient
 $B_E = \frac{\partial f}{\partial x}$

1-slack cutting plane

dual problem

batch FW
can do line search to get β_E

complexity of alg.
in # oracle calls

$$O\left(\frac{n B^2}{\lambda E}\right)$$

$$O\left(n^{n^v} \log\left(\frac{1}{\epsilon}\right)\right) \rightarrow v \geq 1 \text{ (open problem)}$$

relate to
pyramidal width
of marginal polytope

$O(1)$

{

stochastic subgradient
method
(no line search)

~~BCFW~~
(not equivalent)

BCFW
(line search)

14h5]

Block-coordinate optimization

"huge scale" optimization → [Nesterov 2010–2012]

proposed: randomized block-coordinate projected gradient method

$$\begin{aligned} \text{setup: } & \min f(x) \\ \text{st. } & x \in \bigcup_{i=1}^n M_i \\ & x = (\underbrace{x_1, \dots, x_n}_{\text{block}}) \end{aligned}$$

$$\begin{aligned} \text{algorithm: } & \text{pick at random } i \\ & \text{then let } \begin{cases} x_i^{(t+1)} = \text{Proj}_{M_i} (x_i^{(t)}) - \frac{1}{L_i} \nabla f(x^{(t)}) \\ x_j^{(t+1)} = x_j^{(t)} \quad \forall j \neq i \end{cases} \end{aligned}$$

Lipschitz const.
 $\nabla f(x^{(t)})$

[only update block i at iteration]

$$\text{Nesterov showed} \quad \mathbb{E} f(x^{(t)}) - f^* \leq \frac{2}{t+4} \left[\frac{1}{n} \sum_{i=1}^n L_i \right] \|x_0 - x^*\|^2$$

(uniform sampling)

(for convex f with L_i -Lips. gradient per block)

Block-coordinate FW (BCFW): idea: do a FW step on block i

alg.: for $t=0, \dots$

pick i unif. at random from 1 to n

$$\text{let } s_i^{(t+1)} = \underset{s_i \in M_i}{\text{argmin}} \langle s_i, \nabla f(x^{(t)}) \rangle \quad [\text{FW corner for block } i]$$

$$\begin{cases} x_i^{(t+1)} = x_i^{(t)} (1 - \gamma_t) + \gamma_t s_i^{(t)} \\ x_j^{(t+1)} = x_j^{(t)} \quad \forall j \neq i \end{cases}$$

$$s_i^{(t+1)} = \begin{pmatrix} 0 \\ 0 \\ \vdots \\ s_i \\ 0 \end{pmatrix}$$

$$\begin{aligned} \gamma_t &= \text{line search} \\ &\text{argmin}_{\gamma \in [0, 1]} f(x^{(t)} + \gamma(s_i^{(t)} - x_i^{(t)})) \\ &\frac{2}{t+2n} \text{# of blocks} \end{aligned}$$

❶ an important property: FW gap = $\max_{s \in M_i} \langle -\nabla f(x), s - x \rangle =$

$$\sum_i \max_{s_i \in M_i} \langle -\nabla_i f(x), s_i - x_i \rangle$$

≡ $\sum_i g_i(x)$ "block FW gap"

as before, can show that $g_i(x) \geq f(x) - \min_y f(y)$
s.t. $y_i = g_i(y)$

$$g^{FW}(x) = \sum_i g_i^{FW}(x)$$

↳ motivated "gap sampling" variant

[Osokin et al. ICML 2016]