

Lecture 14 - dual SVM

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today

- IPM
- duality
- SVM dual

interior point method:

$$\begin{aligned} \min f(x) \\ \text{s.t. } Ax=b \\ x \geq 0 \end{aligned}$$

barrier method

$$\begin{aligned} \min f(x) + t \left(-\frac{1}{t} \log x \right) &\triangleq g_t(x) \\ \text{s.t. } Ax=b \end{aligned}$$

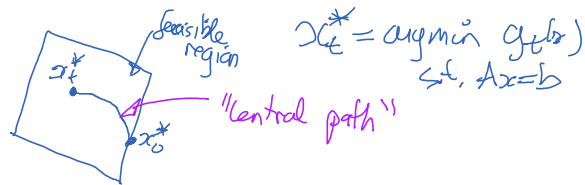
$t \geq 0$

barrier fct.

$-\log x$

$\sum \log x_i$

$$\text{dom}(g_t(x)) = \{x : x > 0\}$$



interior point method: run Newton's method with warm start on $g_t(x)$ and decrease t with a geometric schedule

there is no condition # of g_t appearing
"self-concordant analysis"

Convergence: Newton's method takes $\log(\log(\frac{1}{\epsilon})) + c \log(g_t(x_0) - g_t(x^*))$ iterations to reach ϵ -accuracy

IPM: total # of Newton iterations is $\log(\frac{1}{\epsilon}) \cdot \text{some constants}$
 $\hookrightarrow$ dimensionality is appearing, but not the condition # of f (vs. gradient methods)

Review of Lagrangian duality

primal problem

$$p^* \triangleq \inf_x f(x) \quad \text{s.t. } h_i(x) \leq 0 \quad \forall i \in I$$

dual problem

$$\begin{aligned} d^* &= \sup_{\alpha \geq 0} d(\alpha) \\ d(\alpha) &= \inf_x f(x) + \sum \alpha_i h_i(x) \end{aligned}$$

Lagrangian dual fct.

Fenchel duality

Fenchel conjugate of f

$$f^*(y) \triangleq \sup_x \langle y, x \rangle - f(x)$$

$\uparrow$ x^* is s.t. $\nabla f(x^*) = y$

Fenchel duality:

$$p^* = \inf_{x \in \mathbb{R}^d} f(x) + g(Ax)$$

eg. $\frac{\|w\|^2}{2} + \frac{1}{n} \sum H_i(w)$

$A: \mathbb{R}^d \rightarrow \mathbb{R}^P$

$$d(\alpha) = \inf_x f(x) + \sum_i \alpha_i h_i(x)$$

$$d^* = \sup_{y \in \mathbb{R}^p} -f^*(A^T y) - g^*(y)$$

$\frac{\|w\|^2}{2} + \frac{1}{n} \sum_i H_i(w)$
 $\max_y \frac{1}{2} \|y\|^2 - \sum_i \alpha_i \langle y, y_i \rangle$

note: not unique?

saddle point perspective of log. duality

$$\inf_x f(x) \text{ s.t. } h_i(x) \leq 0 \forall i \in I$$

$$= \inf_x \left[\sup_{\alpha \geq 0} \underbrace{f(x) + \sum_i \alpha_i h_i(x)}_{\mathcal{L}(x, \alpha)} \right] \quad \text{"Lagrangian fct."}$$

$$\text{because } g(x) \triangleq \sup_{\alpha \geq 0} \sum_i \alpha_i h_i(x) = \begin{cases} +\infty & \text{if } x \text{ is not feasible} \\ & \text{i.e. } \exists i \text{ s.t. } h_i(x) > 0 \\ 0 & \text{o.w.} \end{cases}$$

$$= \delta_C(x)$$

$$\text{where } C \triangleq \{x : h_i(x) \leq 0 \forall i\}$$

$$p^* = \inf_x f(x) + \delta_C(x)$$

$$= \inf_x \sup_{\alpha \geq 0} \mathcal{L}(x, \alpha)$$

$$\Rightarrow \sup_{\alpha \geq 0} \inf_x \mathcal{L}(x, \alpha) \triangleq d^* \quad \inf_x \left(\sup_{\alpha \geq 0} \mathcal{L}(x, \alpha) \right) \geq \sup_{\alpha \geq 0} \inf_x \mathcal{L}(x, \alpha)$$

"weak duality"

Lagrangian dual fct.

strong duality $p^* = d^*$

KKT conditions $\Rightarrow$ necessary conditions for x^* & α^* to be primal & dual optimal when f & h_i are differentiable fcts.

- KKT conditions
- x^* is primal feasible (i.e. $h_i(x^*) \leq 0 \forall i$)
 - α^* is dual feasible ($\alpha^* \geq 0$)
 - $\nabla f(x^*) + \sum_i \alpha_i^* \nabla h_i(x^*) = 0$ [i.e. (x^*, α^*) stationary pt. of $\mathcal{L}(x, \alpha)$ with respect to x]
 - $\alpha_i^* h_i(x^*) = 0 \forall i$ "complementary slackness"



$\hookrightarrow \alpha_i^* > 0$ only on active constraints $h_i(x^*) = 0$

* if primal problem is convex (i.e. f & h_i are convex) and "Slater's condition" $\Rightarrow$ strong duality i.e. $p^* = d^*$

and KKT conditions are sufficient

$\exists x$ rel interior (dom. f)

(e.g. thus suppose get α^* by solving dual,)

$\exists x \text{ rel interior } (\text{dom } f)$
 $\text{s.t. } h_i(x) < 0 \forall i$
 when h_i is not affine

(e.g. thus suppose get α^* by solving dual,
 then get x^* through KKT conditions
 $\Rightarrow x^*$ solve primal

see counter-example for strong duality (see Boyd's book example 5.21)

$$\min f(x, y) \\ \text{s.t. } \frac{x^2}{y} \leq 0$$

$$\text{where } f(x, y) = \begin{cases} x^2/y & y > 0 \\ +\infty & \text{o.w.} \end{cases}$$

violates Slater's condition
 and no strong duality

then comments:

- $f(x) \geq d(\alpha) \quad \forall x \in \mathcal{X}, \alpha \text{ feasible}$
- $d(\alpha)$ is always concave in α
- $d(\alpha)$ is obtained through unconstrained opt.
- no unique "Lagrangian dual problem"

$$\text{e.g. } h_i(x) \leq 0 \Leftrightarrow ah_i(x) \leq 0 \text{ for some } a > 0$$

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SVM struct dual problem

$$\text{consider primal: } \min_{w, \xi} \frac{\lambda \|w\|^2}{2} + \frac{1}{n} \sum_{i=1}^n \xi_i$$

$$\text{s.t. } \frac{1}{n} \sum_{i=1}^n \xi_i \geq \frac{1}{n} \sum_{i=1}^n H_i(\tilde{y}_i; w) \quad \forall \tilde{y} \in \mathcal{Y}_i$$

$$\hookrightarrow \ell_i(\tilde{y}) - w^T \gamma_i(\tilde{y})$$

$$L(w, \xi; \alpha) = \left(\frac{\lambda}{2} \|w\|^2 + \frac{1}{n} \sum_i \xi_i + \frac{1}{n} \sum_{i, \tilde{y}} \alpha_i(\tilde{y}) \left[\underbrace{\ell_i(\tilde{y}) - w^T \gamma_i(\tilde{y})}_{h_{i, \tilde{y}}(w, \xi)} - \xi_i \right] \right)$$

$$\frac{\partial L}{\partial \xi_i} = 0 \Rightarrow \boxed{\sum_{\tilde{y}} \alpha_i(\tilde{y}) = 1} \quad \text{i.e. } \alpha_i \in \Delta(|\mathcal{Y}_i|)$$

$$\nabla_w L = 0 \Rightarrow \lambda w - \frac{1}{n} \sum_{i, \tilde{y}} \gamma_i(\tilde{y}) = 0$$

$$\boxed{w(\alpha) \triangleq \frac{1}{n} \sum_{i, \tilde{y}} \alpha_i(\tilde{y}) \gamma_i(\tilde{y})} \quad \text{KKT condition}$$

$$w(\alpha) \triangleq \frac{1}{\lambda n} \sum_{i \in \mathcal{Y}} \alpha_i l_i(\tilde{y}) \quad \text{KKT condition}$$

$$d(\alpha) = L(w(\alpha), \xi(\alpha); \alpha) = \frac{\lambda}{2} \|w(\alpha)\|^2 + \underbrace{\left(\sum_{i \in \mathcal{Y}} \alpha_i l_i(\tilde{y}) \right)}_{\langle b, \alpha \rangle} - w(\alpha)^T \underbrace{\left(\sum_{i \in \mathcal{Y}} l_i(\tilde{y}) \right)}_{\lambda w(\alpha)}$$

notation: $\alpha \in \Delta_{|\mathcal{Y}_1|} \times \Delta_{|\mathcal{Y}_2|} \times \dots \times \Delta_{|\mathcal{Y}_n|}$
 $b = (b_i)_{i \in \mathcal{Y}} \quad b_i(\tilde{y}) \triangleq \sum_{j \in \mathcal{Y}_i} l_j(\tilde{y})$

$$d(\alpha) = \langle b, \alpha \rangle + \frac{\lambda}{2} \|w(\alpha)\|^2 - w(\alpha)^T \left(\underbrace{\sum_{i \in \mathcal{Y}} \alpha_i l_i(\tilde{y})}_{\lambda w(\alpha)} \right)$$

$b \in \mathbb{R}^m$ *exponentially big*

$A \in \mathbb{R}^{d \times m}$

$$w(\alpha) = A\alpha$$

$A \triangleq \left[\dots \underbrace{l_i(\tilde{y})}_{\substack{\text{column} \\ \frac{1}{\lambda n}}} \dots \right]$

$$d(\alpha) = \langle b, \alpha \rangle - \frac{\lambda}{2} \|A\alpha\|^2$$

dual problem: $\max_{\substack{\alpha_i \in \Delta_{|\mathcal{Y}_i|} \\ \text{is in}}} -\frac{\lambda}{2} \|A\alpha\|^2 + \langle b, \alpha \rangle$

(exponentially many dual variables)

complementary slackness: $\alpha_i^*(\tilde{y}) > 0 \Rightarrow h_i(\tilde{y}; w^*) = 0$

i.e. $\xi_i^* = l_i(\tilde{y}) - w^{*T} l_i(\tilde{y}) = H_i(\tilde{y}; w^*)$

define $\xi_i(\alpha) = \max_{\tilde{y}} H_i(\tilde{y}; w(\alpha))$

by primal feasibility, $\xi_i^* \geq H_i(\tilde{y}; w^*) \forall \tilde{y} \in \mathcal{Y}_i$

thus $\xi_i^* = \max_{\tilde{y} \in \mathcal{Y}_i} H_i(\tilde{y}; w^*) = H_i(w^*)$

Support vectors are when $\alpha_i^*(\tilde{y}) > 0$ (and $\tilde{y} \neq y^{(i)}$ because $l_i(y^{(i)}) = 0$)

[necessary condition $\tilde{y} \in \arg\max_{\tilde{y} \in \mathcal{Y}_i} H_i(\tilde{y}; w^*)$]

⊗ sparse solution α^*