

- today:
- variance reduction perspective
 - application to CRF

Variance reduction idea

X & Y are R.V.'s

goal: estimate $\mathbb{E}X$ using M.C. samples

Suppose: $\mathbb{E}Y$ is cheap to compute and Y is correlated with X

consider estimator

$\alpha \in [0, 1]$ $\Theta_\alpha \triangleq \alpha(X - Y) + \mathbb{E}Y$ to approximate $\mathbb{E}X$
 ↑ convex combo coeff. between $\mathbb{E}X \neq \mathbb{E}Y$

properties: $\mathbb{E}\Theta_\alpha = \alpha \mathbb{E}X + (1 - \alpha) \mathbb{E}Y \rightarrow$ unbiased (i.e. $\mathbb{E}\Theta_\alpha = \mathbb{E}X$)
 if $\mathbb{E}X = \mathbb{E}Y$ [not interesting] $\alpha = 1$

variance: $\text{var}(\Theta_\alpha) = \alpha^2 [\text{var}X + \text{var}Y - 2\text{cov}(X, Y)]$
 ↓ variance reduction ↓

for $\alpha = 1$ (unbiased setting) $\Theta_\alpha = X + \underbrace{(\mathbb{E}Y - Y)}_{\text{correction}}$

SGD setting:

X is $\nabla f_i(x_t)$; $\mathbb{E}X =$ batch gradient

SAG/SAGA algorithm: Y is g_i [past stored gradient]

$\mathbb{E}Y = \frac{1}{n} \sum_{i=1}^n g_i$

SAG alg: $\alpha = \frac{1}{n}$ (biased)

SAGA alg: $\alpha = 1 \rightarrow$ (unbiased)

SAG:	$x_{t+1} = x_t - \delta \left[\frac{1}{n} [\nabla f_{i_t}(x_t) - g_{i_t}^{(t)}] + \frac{1}{n} \sum_j g_j^{(t)} \right]$	(biased)
SAGA:	$x_{t+1} = x_t - \delta \left[\frac{1}{n} [\nabla f_{i_t}(x_t) - g_{i_t}^{(t)}] + \frac{1}{n} \sum_j g_j^{(t)} \right]$	(unbiased)
SVRG:	$x_{t+1} = x_t - \delta \left[\nabla f_{i_t}(x_t) - \nabla f_{i_t}(x_{old}) + \frac{1}{n} \sum_j \nabla f_j(x_{old}) \right]$	(unbiased)

(stochastic variance reduced)

SVRG (stochastic variance reduced gradient) $x_{t+1} = x_t - \gamma [\nabla f_{i_t}(x_t) - \nabla f_{i_t}(x_{old}) + \frac{1}{n} \sum_j \nabla f_j(x_{old})]$ (unbiased)

x_{old} is updated from outer loop

SVRG alg →

for $k=0, \dots$ (outer loop)

compute $g_{ref} \triangleq \frac{1}{n} \sum_j \nabla f_j(x^{(k)})$

for $t=0, \dots, T_{max}$
 sample i_t

$x_{t+1} = x_t - \gamma [\nabla f_{i_t}(x_t) - \nabla f_{i_t}(x^{(k)}) + g_{ref}]$

end

$x^{(k+1)} = x_{T_{max}}^{(k)}$

questions:

- what is T_{max} ?
- what is γ ?

original SVRG convergence result: need $\gamma \leq \frac{1}{L}$

$T_{max} \geq \frac{L}{\mu} = K \rightarrow$ to run alg., need to know K

\Rightarrow not adaptive to local strong convexity

tweak of SVRG (now called "loopless")

[Hoffmann & de. NeurIPS 2018] $T_{max} \sim \text{beam}(\dots)$

[at inner loop, do a batch gradient comp. with prob $\frac{1}{n}$]

then, get same convergence result as SAGA

\hookrightarrow comp. cost: size of inner loop $\mathbb{E}[T_{max}] = n$;

overall cost of SVRG ≈ 3 (SGD cost) for n updates

SAG / SAGA / loopless SVRG, convergence for convex fct. ($\mu=0$)

get $\min_{x \in \mathcal{X}} \mathbb{E} \| \nabla f(x_t) - \nabla f^* \|^2 = O(\frac{1}{T})$

[contrast this with $O(\frac{1}{\sqrt{T}})$ for SGD]

* Note: interpolation regime: $\| \nabla f_i(x^*) \| = 0 \forall i$

vs. just $\| \frac{1}{n} \sum_i \nabla f_i(x^*) \| = 0$

\hookrightarrow get similar rate as SVRG/SAGA with SGD

CRF optimization

SVM struct	$\min_w \frac{\lambda \ w\ ^2}{2} + \frac{1}{\lambda} \sum_{i=1}^n H_i(w)$	$\max_{\alpha_i \in \Delta_{ Y_i }} -\lambda \ w(\alpha)\ ^2 + \frac{1}{\lambda} \sum_{i=1}^n \sum_{j \in Y_i} \alpha_{ij} \psi_j(y_i)$
CRF	$\min_w \frac{\lambda \ w\ ^2}{2} + \frac{1}{n} \sum_{i=1}^n -\log p(y^{(i)} x^{(i)}; w)$ <p style="text-align: center;">$\log \left(\sum_{\tilde{y}} \exp(-w^T \psi(\tilde{y})) \right)$</p>	$\max_{\alpha_i \in \Delta_{ Y_i }} -\lambda \ w(\alpha)\ ^2 + \frac{1}{n} \sum_{i=1}^n \sum_{j \in Y_i} \alpha_{ij} \psi_j(y_i)$ <p style="text-align: center;">$\equiv \sum_{\tilde{y}} \alpha_{\tilde{y}} \log \alpha_{\tilde{y}}$</p>

KKT $\rightarrow w(\alpha) = \frac{1}{\lambda n} \sum_i \sum_{j \in Y_i} \alpha_{ij} \psi_j(y_i)$

$= \frac{1}{\lambda n} \sum_i \sum_{c \in C} M_{ic}(y_c) \psi_{ic}(y_c)$
 \hookrightarrow from MRF

$p(y|x; w) \propto \exp(\langle w, \psi(x, y) \rangle)$

* at optimality

$\alpha_i^*(y) = p(y | x^{(i)}; w(\alpha^*))$

$\alpha_i^* \in$ interior of $\Delta_{|Y_i|}$
 write sparse soln in SVM struct

15h27

CRF optimization

- primal is smooth [vs. non-smooth for SVM struct]
- for a while, batch L-BFGS was method of choice [batch \Rightarrow slow for large n]
- [Collins & al. JMLR 2008]: online exponentiated gradient (OEG)

block-coordinate method on dual; exponentiated gradient step on block dual obj.
 $\alpha_i(y)^{(t+1)} \propto \alpha_i(y)^{(t)} \exp(-\gamma_t \nabla_{\alpha_i} D(\alpha^{(t)}))$
 EG alg \rightarrow proximal gradient step using $KL(\alpha || \alpha^{(t)})$ as a Bregman divergence for prox term
 \rightarrow get linear convergence rate with cheap $O(1)$ updates (like SGD) [vs. $O(n)$ for batch methods]

[can think of it as a variance reduced method as well?]

- SAGA for CRF [Schmidl & al. AISTATS 2015]

$w^{(t+1)} = (1 - \lambda \gamma_t) w^{(t)} - \gamma_t \left[\sum_{i \in I_t} \nabla_{w_i} D_i(w^{(t)}) - g_i^{(t)} + \frac{1}{n} \sum_j g_j^{(t)} \right]$

- SDCA (stochastic dual coordinate ascent)

$\alpha_{i_t}^{(t+1)}(y) = (1 - \gamma_t) \alpha_{i_t}^{(t)}(y) + \gamma_t \underbrace{\sum_{j \in Y_i} \alpha_{ij}^{(t)}(y)}_{\in [0,1] \text{ (stabilize)}} + \gamma_t \underbrace{\psi_j(y)}_{p(y|x; w(\alpha^{(t)}))}$
 as relaxed fixed pt.

(coordinate ascent)

SOTA for CRF
[LePrieux et al. UAI 2018]
thanks to line search

as relaxed fixed pt.

$$\alpha_i^* = p(y|x_i; w(\alpha^*)) \alpha_i$$

$$p(y|x_i; w(\alpha^*)) \triangleq \alpha_i(w)$$

related to subgradient point

[note: BCFW is a special case of SDA on SVM struct obj!]

proximal gradient method

↳ generalization of projected gradient method to other non-smooth fcts.

composite framework $F(w) \triangleq f(w) + \Omega(w)$ where f is convex & L -smooth
 Ω " " but not nec smooth

• constrained opt. $\Omega(w) = \delta_M(w) \triangleq \begin{cases} 0 & \text{if } w \in M \\ +\infty & \text{o.w.} \end{cases}$
"indicator fct." on M

• l_1 -regularization $\Omega(w) = \|w\|_1$

proximal gradient update:

$$w_{t+1} = \underset{w}{\operatorname{argmin}} \underbrace{f(w_t) + \langle \nabla f(w_t), w - w_t \rangle + \frac{1}{2\delta_t} \|w - w_t\|_2^2}_{\triangleq B_t(w)} + \Omega(w)$$

• if $\delta \leq \frac{1}{L}$, then $f(w) \leq B_\delta(w) \forall w$

• we can rewrite $B_\delta(w) = \frac{1}{2\delta} \|w - [w_t - \delta \nabla f(w_t)]\|_2^2 + \text{cst.}$
(by completing the square)

⇒ if $\Omega(w) = \delta_M(w)$; we get projected grad., relg

$$w_{t+1} = \operatorname{Prox}_{\delta_t}^{\Omega} (w_t - \delta_t \nabla f(w_t))$$

↳ "proximal operator"

$$\operatorname{prox}_{\delta}^{\Omega}(z) \triangleq \underset{w}{\operatorname{argmin}} \left\{ \Omega(w) + \frac{1}{2\delta} \|w - z\|_2^2 \right\}$$

could be replaced by Bregman divergence to get other generaliz. (e.g. OEG)

⊛ like projection, prox operator is non-expansive (ie. 1-Lipschitz)

$$\text{ie. } \|\operatorname{prox}_{\delta}^{\Omega}(w) - \operatorname{prox}_{\delta}^{\Omega}(w')\|_2 \leq \|w - w'\|_2$$

(recall lecture 1 landscape of rates)

(*) like projection, prox operator is non-expansive (ie. 1-Lipschitz)

(recall lecture 1
landscape of
rates)

$$\text{ie. } \|\text{prox}_\gamma^2(w) - \text{prox}_\gamma^2(w')\|_2 \leq \|w - w'\|_2$$

\Rightarrow convergence rate for prox. gradient method on $F = f + \Omega$
are same as unconstrained gradient descent on f

* to be useful, need prox_γ^2 to be efficiently computable

$$\text{prox}_\gamma^{\|\cdot\|_2}(z) = \underset{w}{\text{argmin}} \|w\|_2 + \frac{1}{2\gamma} \|w - z\|_2^2$$

$$\text{"soft-thresholding"} \triangleq \begin{cases} \text{sgn}(z) [|z| - \gamma] & \text{if } |z| \geq \gamma \\ 0 & \text{o.w.} \end{cases}$$

(component-wise)

used e.g. for lasso: l_1 -regularized least square

FISTA \rightarrow accelerated prox. gradient method

\hookrightarrow SOTA for batch lasso

$$\min_w \left[\sum_{i=1}^n f_i(w) + \Omega(w) \right]$$

* sketch-based \rightarrow use proxSAGA for lasso; l_1 -reg. log-reg.

prox SAGA $w_{t+1} = \text{prox}_\gamma^{\Omega} \left(w_t - \gamma \left[\nabla f_t(w_t) - g_t^{(t)} + \frac{1}{n} \sum_{j=1}^n g_j^{(t)} \right] \right)$

could accelerate proxSAGA using "catalyst"
(see next class)