

Lecture 4 - theory basics

Tuesday, January 26, 2021 14:36

today: theory basics

theory basics

decision theory setup

estimate $h_w: X \rightarrow Y$

$$\text{generalization error} = L_p(w) \triangleq \mathbb{E}_{(x,y) \sim P} [l(y, h_w(x))] \quad \text{task loss}$$

ultimate goal is to find $w^* = \arg \min_{w \in W} L_p(w)$

problem: do not know P ("true" distribution on (x,y))

suppose $\underbrace{(x^{(i)}, y^{(i)})}_{\triangleq D_n}^n$ i.i.d. P \rightsquigarrow we could look at

$$\hat{L}_n(w) = \frac{1}{n} \sum_{i=1}^n l(y^{(i)}, h_w(x^{(i)}))$$

from statistics / prob. theory.

$$\hat{L}_n(w) \xrightarrow{\text{a.s.}} L_p(w) \quad \text{for each fixed } w \quad (\text{point wise})$$

$$\text{this is } \underline{\text{weaker than}} \quad \sup_w |\hat{L}_n(w) - L_p(w)| \xrightarrow[n \rightarrow \infty]{\text{a.s.}} 0$$

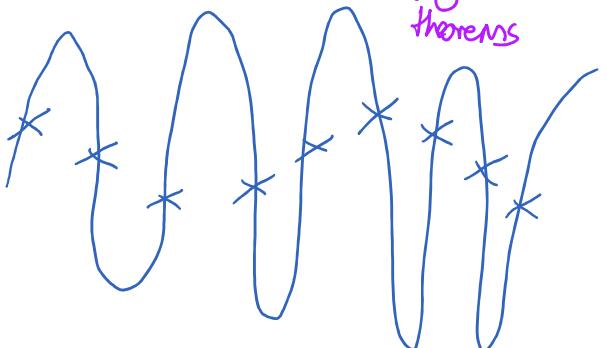
Note: minimizing the training error gives no guarantee in general?

\rightsquigarrow later no free lunch theorems

e.g. polynomial regression

for n points, can get zero training error with poly. of degree $n-1$

\Rightarrow "overfitting"



in learning theory: \rightarrow study properties of learning alg.

$$w_m$$

in particular, what can we say about $L_p(A|D_n)$

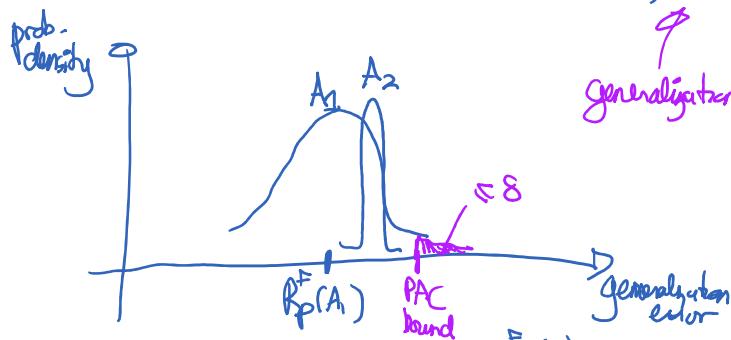
different approaches:

a) "frequentist risk" $R_{P,D}^F(A) \triangleq \mathbb{E}_{D_n \sim P \otimes \pi} [L_p(A|D_n)]$

b) PAC framework
"probably approximately correct"
 $P\{L_p(A(D_n)) > \text{some bound}\} \leq \delta$ ("tail bound")

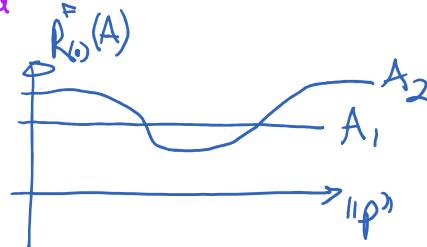
i.e. $L_p(A(D_n)) \leq \text{bound}$ with prob. $\geq 1 - \delta$

generalization error bound



issue with $R_p^F \rightarrow$ depends on p

"risk profiles":



weighted frequentist risk $\mathbb{E}_{\theta \sim \pi(\theta)} [R_{P,\theta}^F(A)]$

c) "Bayesian posterior risk"

$$R^{\text{post}}(w|D_n) \triangleq \mathbb{E}_{\theta \sim P \otimes \pi(D_n)} [L_p(w)]$$

Bayesian estimate $\hat{w}_n^{\text{Bayes}} = \underset{w}{\operatorname{argmin}} R^{\text{post}}(w|D_n)$

A^{Bayesian} is optimal for weighted frequentist risk using $\pi(\theta) = p(\theta)$

• prior $p(\theta)$ over dist.

• observation model $p(D|\theta)$

\Rightarrow posterior $p(G|D_n)$

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No free lunch!

Frequentist risk analysis learning alg. A

let \mathcal{P} be a set of distributions on $X \times \mathcal{Y}$

Sample complexity of A with respect to \mathcal{P}

is the smallest $n(\mathcal{P}, A, \varepsilon)$ s.t. $\forall n \geq n(\mathcal{P}, A, \varepsilon)$

we have $\sup_{P \in \mathcal{P}} [R_P^F(A; n) - L_P(h_P^*)] \leq \varepsilon$
 "uniform result" $h_P^* = \underset{h: X \rightarrow Y}{\operatorname{arg\min}} L_P(h)$

terminology : • A is consistent for dist. P

if $\lim_{n \rightarrow \infty} R_P^F(A; n) - L_P(h_P) = 0$

• A is uniformly consistent for a family \mathcal{P}

if $\lim_{n \rightarrow \infty} \left[\sup_{P \in \mathcal{P}} [R_P^F(A; n) - L_P(h_P)] \right] = 0$

Binary classification $Y = \{-1, +1\}$

I) if X is finite; then the "voting procedure" (assign the most frequent label to an input x)

is uniformly and universally consistent

\hookrightarrow i.e. \mathcal{P} is all distributions $X \times Y$

with (universal) sample complexity

$$n(\mathcal{P}, \varepsilon, \text{Averaging}) \leq \frac{|X|}{\varepsilon^2} \quad (\text{free lunch!})$$

II) if X is infinite

no free lunch theorem (for binary with 0-1 loss)

for any n and any learning alg. A

then $\sup_{\substack{P \text{ all} \\ \text{dist.}}} [R_P^F(A; n) - L_P(h_P^*)] \geq \frac{1}{2}$

i.e. \exists always a dist. P_A s.t. your A is worse than random prediction?
 for P_A

NF, IT :

for PA

NFL II:

[Thm. 7.2 in Perceval et al. 1996]

$$\sum_i \frac{1}{16}$$

let ϵ_n be any non-increasing seq. converging to 0
 for any A ,
 then \exists PA s.t. $[R_{PA}^F(A; n) - L_p(h_{PA}^*)] > \epsilon_n \text{ for } \epsilon_n \text{ could be arbitrarily slowly}$
 $\log(\log(\log(\dots(n))))^{10^{23}}$

Consequence: we need assumptions on $\underline{\Omega}_P$ to say anything useful

Occam's generalization error bound

- binary class. & OR loss
- consider W to be a countable set

let's define a prior over W : $\pi(w)$ i.e. $\sum_{w \in W} \pi(w) = 1 \quad \pi(w) \geq 0 \forall w$
 $|w|_\pi = \text{"description length" of } w \triangleq \log_2 \frac{1}{\pi(w)}$ $\sum_w 2^{-|w|_\pi} \leq 1$
 "Kraft's inequality"

Occam's bound

for any fixed P , with prob. $\geq 1-\delta$ over training set $D_n \sim P^{\otimes n}$

$$\forall w \in W \quad L_p(w) \leq \hat{L}_p(w) + \frac{1}{\sqrt{2n}} \Omega_\pi(w; \delta)$$

$$\text{where } \Omega_\pi(w; \delta) \triangleq \sqrt{(n/2)|w|_\pi + \ln(1/\delta)}$$

complexity measure

* bound is useful only for dist P s.t. $|w|_\pi$ is small

$$|w|_\pi = \log_2 \frac{1}{\pi(w)} \quad \begin{matrix} \downarrow \text{argmin}_{w \in W} L_p(w) \\ \text{if } \pi(w) \propto \exp(-||w||^2) \end{matrix}$$

$$\text{then } |w|_\pi = ||w||^2 + \text{const.}$$

proof: use 3 things

1) Chernoff bound

$$D \subseteq D_n \Rightarrow \hat{L}_n(w) \leq L(w) - \epsilon^2 \leq \text{err}/(2n^2) \quad H \gg 0$$

Note: G1 loss ass.
 appears in const.
 of Chernoff bound

Proofs: use \geq margins

1) Chernoff bound
(concentration inequality)

$$P\{\hat{L}_n \geq \hat{L}_n(w) \leq L(w) - \varepsilon\} \leq \exp(-2n\varepsilon^2) \quad \forall \varepsilon > 0$$

(appears in const. of Chernoff bound)

2) union bound

$$P\{\exists x \text{ s.t. } \text{prop}(x) \text{ is true}\} \leq \sum_x P\{\text{prop}(x) \text{ is true}\}$$

3) "Kraft's inequ."

$$\sum_w 2^{-|w|\pi} \leq 1$$

we say that w is naughty if bound fails
"bad"

$$L - \varepsilon > \hat{L}_n$$

$$\text{bad}(w) = \mathbb{1}\{\hat{L}_n(w) > L_n(w) + \frac{\varepsilon_n(w)}{\sqrt{2n}}\}$$

using Chernoff, $\hat{L}_n(w) \leq L(w) - \varepsilon_n(w)$ with small prob.

$$P\{\text{bad}(w)\} \leq \exp(-2n\varepsilon_n(w)^2) = \exp(-2n \frac{1}{2n} ((\ln 2)|w|\pi + (\ln \frac{1}{2}))$$

$$= 2^{-|w|\pi}$$

using union bound

$$P\{\exists w : \text{bad}(w)\} \leq \sum_w P\{\text{bad}(w)\} \leq S 2^{-|w|\pi} \stackrel{\text{Kraft}}{\leq} S$$

Surrogate Loss

NP hard to minimize $\hat{L}_n(w)$; replace with $\hat{L}_n(w)$ which is "surrogate"

e.g. hinge loss
log-loss

next: countable \rightarrow uncountable
"PAC-Bayes"