

Lecture 1 - scribbles

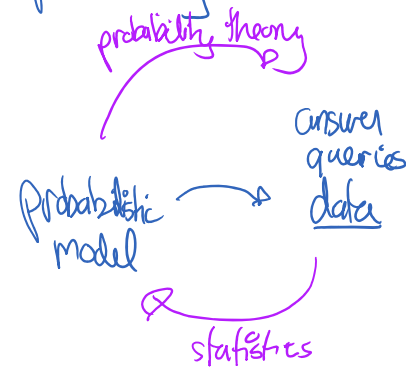
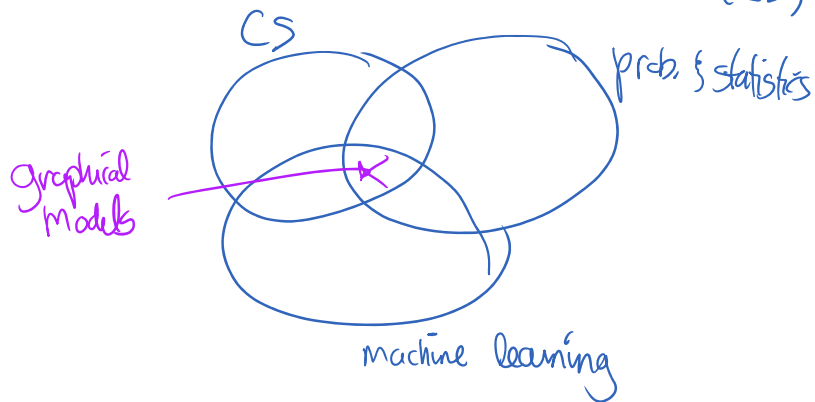
Tuesday, September 4, 2018 14:48

email sign-up by tomorrow : bit.ly/IFT6269-F18

probabilistic graphical model

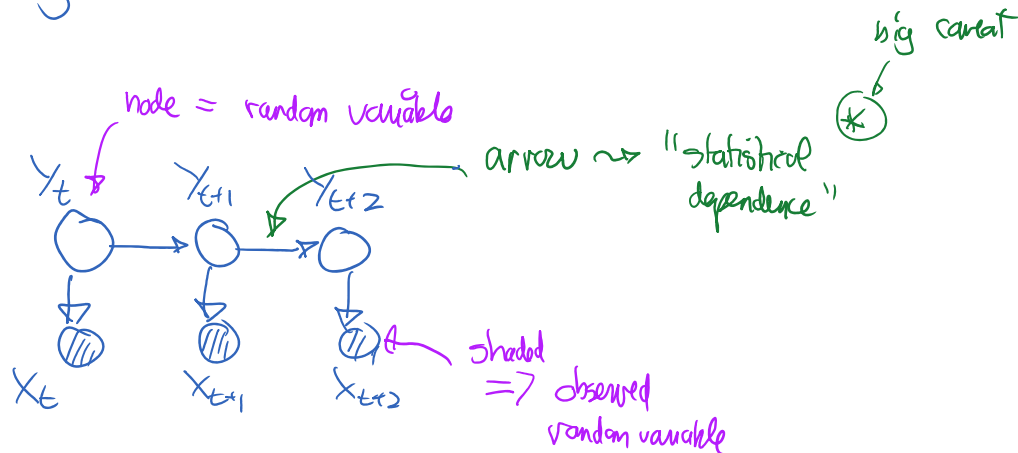
model Multivariate data

graphical model $\rightarrow$ mix of graph theory + prob. theory
(CS)



Applications:

Hidden Markov model



a) speech recognition: $x_t \rightarrow \text{phoneme}$
 $x_t \rightarrow \text{sound wave}$

b) part-of-speech tagging: $x_t \in \{ \text{DT} - \text{V} - \text{DT} - \text{ADJ} - \text{N} \}$ x_t : part-of-speech
 This is a red box x_t : words

c) Gene finding x_t $x_t \in \{ \text{G}, \text{T}, \text{A}, \text{C} \}$
 (*) [normally $\rightarrow$ multiple nucleotides per x_t]
 Coding vs non-coding (i.e. $x_t \in \{0, 1\}$)

d) control
 $y_{t+1} = A y_t + B v_t + \epsilon_t$
 $x_t = C y_t + \epsilon_t$
 matrices A, B, C
 latent state y_t
 control term (given by system) v_t
 noise ϵ_t
 here x_t, y_t are obs. vectors

if noise is Gaussian, HMM $\rightarrow$ Kalman filter

Why graphical models?

pos tagging observation $(x_1, \dots, x_T) \triangleq x_{1:T}$
 $x_t \in \{1, \dots, k\}$

size of vocabulary

want to model $p(x_{1:T})$

issue: exponential size state space

$\approx k^T$ parameters
to define a distribution
on $x_{1:T}$

trick: make a factorization assumption about p

$$p(x_1, \dots, x_T) = \underbrace{f_1(x_1)}_{\text{factor}} \underbrace{f_2(x_2|x_1)}_{\text{factor}} f_3(x_3|x_2) \cdots f_T(x_T|x_{T-1})$$

factor $\rightarrow$ 2 variables
 $\approx k^2$ parameters
clique in graphical model

T factors $\Rightarrow$

$$\boxed{T \cdot k^2 \text{ parameters}} \\ \ll k^T$$

theme: representation

computation:

say want to compute $p(x_1)$ "marginal"

distributivity:

$$a \cdot (b+c) = a \cdot b + a \cdot c$$

$$p(x_1) = \sum_{x_2, \dots, x_T} p(x_{1:T})$$

$\leftarrow$ exponential sum??

$$= \sum_{x_2, \dots, x_T} f_1(x_1) f_2(x_2|x_1) \cdots f_T(x_T|x_{T-1})$$

$$x_2, \dots, x_T = f_1(x_1) \left(\sum_{x_2} f_2(x_2|x_1) \left[\sum_{x_3} f_3(x_3|x_2) \dots \left(\sum_{x_T} f(x_T|x_{T-1}) \dots \right) \right] \right)$$

$\underbrace{\sum_{x_T} f(x_T|x_{T-1})}_{m_T(x_{T-1})}$



"message passing algorithm" to compute efficiently marginal $p(x_i)$

key themes:

representation: how to represent structured prob distributions?
semantic?

→ parameterization
full table paramet.
or
"exponential family"

estimation: given data, how do learn/estimate
the parameters of dist.

→ learning e.g. maximum likelihood

inference: answer questions about data

e.g. computing $p(y|x)$, or $p(x)$

conditional

marginal

→ computation

e.g. message passing

also approximate inference

conditional

marginal

also approximate inference
eg sampling
variational methods