

Lecture 22 - scribbles

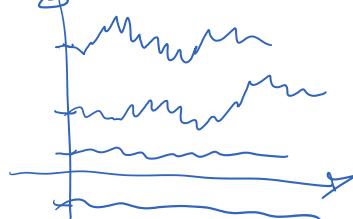
Friday, November 23, 2018 13:28

today: variational methods
mean field d.g.
estimation in PGM

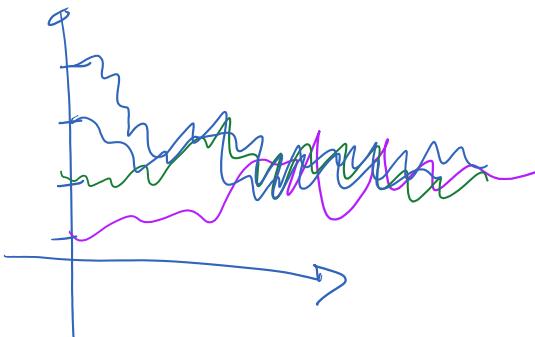
(Sampling chd): diagnostic of mixing

monitor mixing by running independent chains

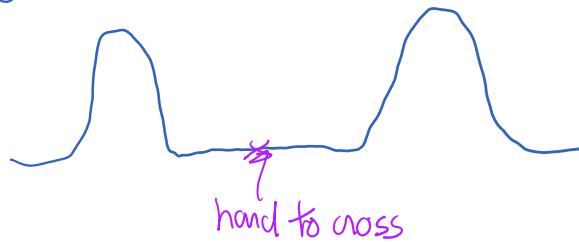
some measurement



"sticky chain"
→ slow mixing



usually slow mixing comes from difficulty to move between modes



→ annealing methods help this

physics analogy

energy

↓

↓

$$\text{proposal looks like } \frac{1}{Z} \exp\left(-\frac{k_B}{T} E(x)\right)$$

"temperature"
↑

high temperature
⇒ more exploration

example: "Annealed importance sampling"

14h47

Variational methods

general idea: say we want to approximate Θ^*

then, express it as solution to optimization problem

$$\Theta^* = \underset{\Theta \in \Theta}{\operatorname{argmin}} \quad f(\Theta) \quad \boxed{\text{OPT}}$$

Idea: approximate Θ^* by approximating OPT

Linear algebra example:

say want sol'n to $Ax=b$ i.e. $x=A^{-1}b$

$$\underset{x}{\operatorname{argmin}} \quad \|Ax-b\|^2$$

Variational EM (motivation)

recall EM trick: latent variable $p(x, z)$

unobserved

$$\log p(x|\theta) \geq \mathbb{E}_q [\log \frac{p(x, z|\theta)}{q(z)}] \triangleq J(q, \theta)$$

$$(\log p(x|e) - \mathcal{J}(q, \theta) = KL(q(\cdot) || p(\cdot | x, \theta))$$

E step: $\underset{\substack{q \in \text{all} \\ \text{distributions} \\ \text{on } z}}{\operatorname{argmax}} L(q, \theta^{(t)}) \Leftrightarrow \underset{q}{\operatorname{argmin}} KL(q || p(z|x, \theta^{(t)}))$

⊗ a variational approximation for the E-step

do $q_{\text{approx}}^{(t+1)} = \underset{\substack{q \in \overline{Q}_{\text{simple}} \\ \overline{q}}}{\operatorname{argmin}} KL(q || p(\cdot | x, \theta^{(t)}))$

source of approximation \rightarrow to approximate $p(z|x, \theta^{(t)})$

approximate M step $\hat{G}^{(t+1)} = \underset{G \in \mathbb{G}}{\operatorname{argmax}} \mathbb{E}_{q_{\text{approx}}^{(t)}} [\log p(x, z | G)]$

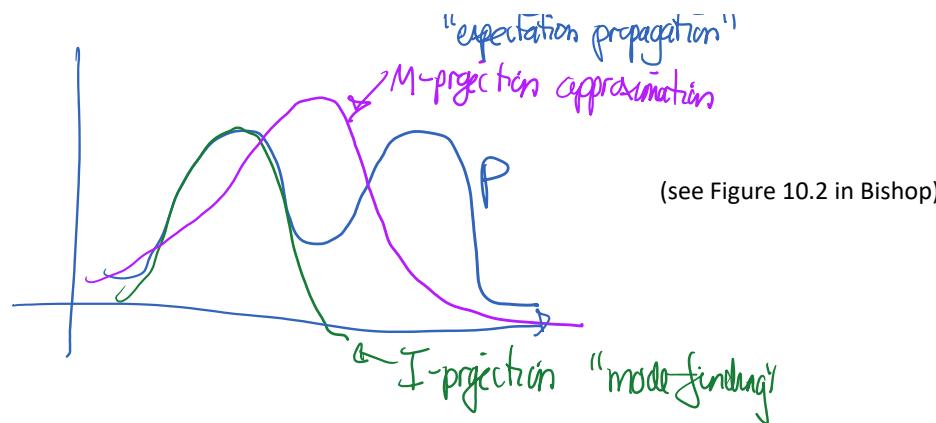
(still get a lower bound on $\log p(x|\theta^{(t)})$
but no monotonicity guarantees
for approximate EM)

more generally, using $\underset{q \in Q}{\operatorname{argmin}} KL(q || \underline{p})$ is a variational approach to approximate p

note: I-projection; if q is simple, can compute $\mathbb{E}_q [\log q]$

alternative: $\underset{q \in \mathbb{G}}{\operatorname{argmin}} KL(\underline{p} || q)$ M-projection

"motivation" EP algorithm \rightarrow moment matching
"expectation propagation"
M-projection approximation



Mean field approximation: (section 10.1 in Bishop)

let's suppose that $p(z)$ is in exponential family

$$z_1, \dots, z_p \quad p(z) = \exp(m^T T(z) - A(m))$$

mean field approximation: $Q_{MF} = \{q(z) = \prod_i q_i(z_i)\}$
set of fully factorized dist.

$$\begin{aligned} KL(q || p) &= \mathbb{E}_q [\log \frac{q(z)}{p(z)}] \\ &= -m^T \mathbb{E}_q [T(z)] + A(m) + \underbrace{\sum_z q(z) \log q(z)}_{\sum_i \left[\sum_j q_i(z_j) \log q_i(z_j) \right]} \\ &\lesssim \left(\sum_i q_i(z_i) \log q_i(z_i) \right) \end{aligned}$$

coordinate descent on q_i 's:

fix q_j for $j \neq i$

minimize w.r.t. to q_i $KL(q_i \cdot q_{\pi} || p)$

$$= -\mathbb{E}_{q_i} \left[\underbrace{n^T \mathbb{E}_{q_{T_i}}(T(z))}_{\triangleq f_i(z_i)} \right] + \text{cst.} + \sum_i q_i(z_i) \log q_i(z_i)$$

add Lagrange multiplier
for

$$\sum_i q_i(z_i) = 1 \rightarrow +\lambda \left(1 - \sum_i q_i(z_i) \right)$$

$$\frac{\partial}{\partial q_i(z_i)} = 0 \Rightarrow -f_i(z_i) + \log q_i(z_i) + 1 - \lambda = 0$$

$$q_i^*(z_i) \propto \exp(f_i(z_i))$$

⊕ general mean field update when target p is in exp family

$$q_i^{(t+1)}(z) \propto \exp(n^T \mathbb{E}_{q_{T_i}^{(t)}} T(z))$$

14th 40

Ising model example

$$T(z) = (z_i)_{i \in V} \quad z_i \in \{0, 1\}$$

$$(z_i z_j)_{\{i, j\} \in E}$$

$$\mathbb{E}_{q_{T_i}}(z_j) = q_j(z_j=1) \triangleq \mu_j$$

$$\mathbb{E}_{q_{T_i}}[z_i z_j] = z_i \mu_j$$

$\mu_j^{(t+1)}$

$$\#q_{7i} \circ L(z_i, \mu_j) = z_i \mu_j$$

$$n^T \mathbb{E}_{q_{7i}^{(t)}} T(z) = m_i z_i + \sum_{j \neq i} m_j \mathbb{E}_{q_{7i}^{(t)}} [z_j] + \\ + \sum_{j \in N(i)} m_{ij} \mathbb{E}_{q_{7i}^{(t)}} [z_i z_j] + \text{rest}_{(no z_i)}$$

result: $q_i^{(t+1)}(z_i) \propto \exp(m_i z_i + z_i \sum_{j \in N(i)} m_{ij} \mu_j^{(t)})$

$$\boxed{\mu_i^{(t+1)} = \sigma(m_i + \sum_{j \in N(i)} m_{ij} \mu_j^{(t)})}$$

MF update for $q_i(z_i)$
[with parameter μ_i]

Compare with

G-S update where $z_i^{(t+1)} = 1$ with prob $\sigma(m_i + \sum_{j \in N(i)} m_{ij} z_j^{(t)})$

here $\min_{q \in Q_{MF}} KL(q || p)$

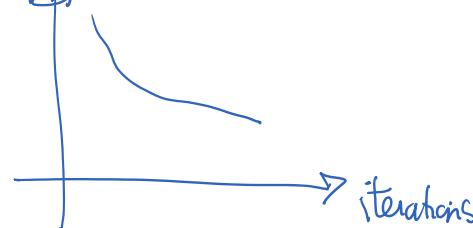
- $KL(\cdot || p)$ is a convex of q
- but Q_{MF} is a non-convex constraint set $\rightarrow M_{ij} = \mu_i \mu_j$
- \Rightarrow can get stuck in local minima

[See Lecture 22 last year for "marginal polytope"]
def. [set of feasible mean parameters]

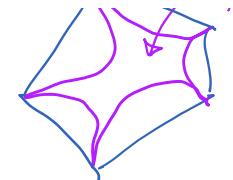


but can monitor progress by

$$KL(q^{(t)} \| p)$$



M



pros & cons of variational methods vs

⊕ optimization based
→ often faster
& easier to debug

sampling

⊖ noisy \Rightarrow hard to debug
mixing problem for chains

⊖ biased estimate

$$\mathbb{E}_{q(\infty)}[f(z)] \neq \mathbb{E}_p[f(z)]$$

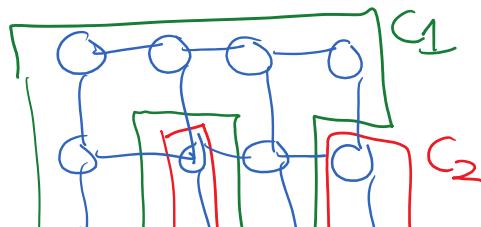
⊕ unbiased estimate

$$\mathbb{E}[\mathbb{E}_{q(\infty)}[f(z)]] = \mathbb{E}_p[f(z)]$$

↳ with respect to random sample

structured mean field: (see loc. 22 last year)

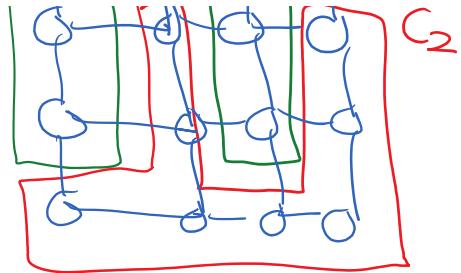
idea $q(z) = \prod_{j=1}^k q_j(z_{C_j})$



where C_1, \dots, C_k partition of V

and q_j 's are tractable distributions
(for example tree UBM)

[lecture 22 Fall 2017 link](#)



5 (for example tree PGM)

Estimation of parameters for PGM

DGM: parametric family $P_{\Theta} = \{ p_{\theta}(x) = \prod_i p(x_i | x_{\pi_i}, \theta_i) \mid \theta = (\theta_1, \dots, \theta_{|V|}) \in \Theta = \Theta_1 \times \dots \times \Theta_M \}$

ie. no tying of parameters

\Rightarrow MLE decouples in $|V|$ independent problems

$$\{x^{(i)}\}_{i=1}^n \quad p(\text{data} | \Theta) = \prod_{i=1}^n p(x^{(i)} | \Theta) = \prod_{i=1}^n \left(\prod_{j=1}^{|V|} p(x_j^{(i)} | x_{\pi_j}^{(i)}, \Theta_j) \right)$$

$$\log [] = \sum_{j=1}^{|V|} \underbrace{\left(\sum_{i=1}^n \log p(x_j^{(i)} | x_{\pi_j}^{(i)}, \Theta_j) \right)}_{f_j(\Theta_j)}$$

example: for discrete R.V. $\Rightarrow \hat{\Theta}_j^{\text{ML}} = \text{proportion of observations}$

$$\frac{\# (x_j = k, x_{\pi_j} = \text{something})}{\# (\text{something})}$$

($x_{\text{eq}} = \text{something}$)

(*) if have latent variable (i.e. unobserved variable)

→ use E.M.

UGM:

example for exp family

$$\rightarrow \exp(n_c^T T_c(x_c)) = \psi_c(x_c)$$

$$p(x|n) = \exp\left(\sum_c n_c^T T_c(x_c) - A(n)\right)$$

gradient ascent on log-likelihood:

$$\frac{1}{n} \sum_{i=1}^n \log p(x^{(i)}|n) = \sum_c n_c^T \left(\underbrace{\sum_{i=1}^n T_c(x_c^{(i)})}_{\hat{m}_c} \right) - A(n)$$

$$\nabla_{n_c} (\quad) = \hat{m}_c - m_c(n) \rightarrow \mathbb{E}_{p(x|n)} [T_c(x_c)]$$

To compute this, need inference

e.g. Ising model $T_{ij}(x_i, x_j) = x_i x_j$

$$\mathbb{E}[T_{ij}] = \mu_{ij}^o = p(x_i=1, x_j=1 | n)$$

perhaps use approximate inference → variational

15h26

sampling