

Lecture 8 - scribbles

Friday, September 28, 2018 13:34

today:
 - logistic regression
 - numerical optimization
 IRLS

Logistic regression model:

$$Y = \{0, 1\}$$

$$p(y=1|x) = \sigma(w^T x)$$

$$p(y=0|x) = 1 - \sigma(w^T x) = \sigma(-w^T x)$$

i.e. $Y|X=x$ is Bernoulli($\sigma(w^T x)$)

$$p(y|x) = \sigma(w^T x)^y \sigma(-w^T x)^{1-y}$$

given $(x_i, y_i)_{i=1}^n$, maximum conditional likelihood:

$$\ell(w) = \sum_{i=1}^n \log p(y_i|x_i; w) = \sum_{i=1}^n [y_i \log \sigma(w^T x_i) + (1-y_i) \log \sigma(-w^T x_i)]$$

derivative

$$\sigma'(z) = \sigma(z)\sigma(-z)$$

$$\nabla_w \sigma(w^T x_i) = x_i [\sigma(w^T x_i)\sigma(-w^T x_i)] \quad \text{let } v_i \triangleq w^T x_i$$

$$\nabla \ell(w) = \sum_{i=1}^n x_i [y_i \underbrace{\frac{\partial}{\partial w_i} \sigma(v_i)}_{\sigma'(v_i)} \sigma(-v_i) - (1-y_i) \underbrace{\frac{\partial}{\partial w_i} \sigma(v_i)}_{\sigma'(v_i)} \sigma(v_i)]$$

$$[y_i [\underbrace{\sigma(-v_i) + \sigma(v_i)}_{\sigma(0)}] - \sigma(v_i)]$$

$$\nabla \ell(w) = \sum_{i=1}^n x_i [y_i - o(w^T x_i)]$$

solve for $\nabla \ell(w) = 0 \Rightarrow$ need to solve a transcendental eq,

because $\frac{1}{1 + \exp(-w^T x_i)} (\dots) = 0$
 need to solve
 for this

contrast to
 least square regression.

$$\nabla \ell(w) = \sum_{i=1}^n x_i [y_i - w^T x_i]$$

linear in w

numerical optimization

want to minimize $f(w)$

$$\min_{w \in \mathbb{R}^d} f(w)$$

1) gradient descent (1st order method)

start at w_0

$$w_{t+1} = w_t - \underline{\lambda_t} \nabla f(w_t)$$

step-size

step-size rules:

a) constant step size $\gamma_t = \frac{1}{L} \leftarrow$ Lipschitz constant of ∇f

$$\|\nabla f(w) - \nabla f(w^*)\| \leq L \|w - w^*\|$$

b) decreasing step-size rule: $\gamma_t = \frac{c}{t}$ constant

usually want: $\sum_t \gamma_t = +\infty \quad \sum_t \gamma_t^2 < \infty$

c) choose γ_t by "line search" :

$$\min_{\gamma \in \mathbb{R}} f(w_t + \gamma d_t)$$

direction for update
(e.g. $-\nabla f(w_t)$)

↓ costly in general

instead do approximate search
e.g. Armijo line search
(see Boyd's book)

2) Newton's method (2nd order method)

motivation: minimizing a quadratic approximation:

$$\begin{aligned} \text{Taylor expansion: } f(w) &= f(w_t) + \nabla f(w_t)^T (w - w_t) + \frac{1}{2} (w - w_t)^T H(w_t) (w - w_t) \\ &\quad + O(\|w - w_t\|^3) \\ &= Q_t(w) + O(\|w - w_t\|^3) \end{aligned}$$

↑
Hessian $[H(w_t)]_{ij} = \frac{\partial^2 f}{\partial w_i \partial w_j}$
Taylor's remainder

$w_t \rightsquigarrow$ minimizing $Q_t(w)$

↑ quadratic model approximation

$$\nabla_w Q_t(w) = 0 \quad \nabla f(w_t) + H(w_t)(w - w_t) = 0$$

$$\Rightarrow w - w_t = -H^{-1}(w_t) \nabla f(w_t)$$

$$w_{t+1} = w_t - \underbrace{H^{-1}(w_t)}_{\text{inverse Hessian}} \nabla f(w_t)$$

Newton's update

inverse Hessian $\rightarrow O(d^3)$ time
to compute in general
 $O(d^2)$ space

Damped Newton: you add a stepsize to stabilize Newton's method

$$w_{t+1} = w_t - \underbrace{\gamma H^{-1}(w_t) \nabla f(w_t)}_{\text{step-size}}$$

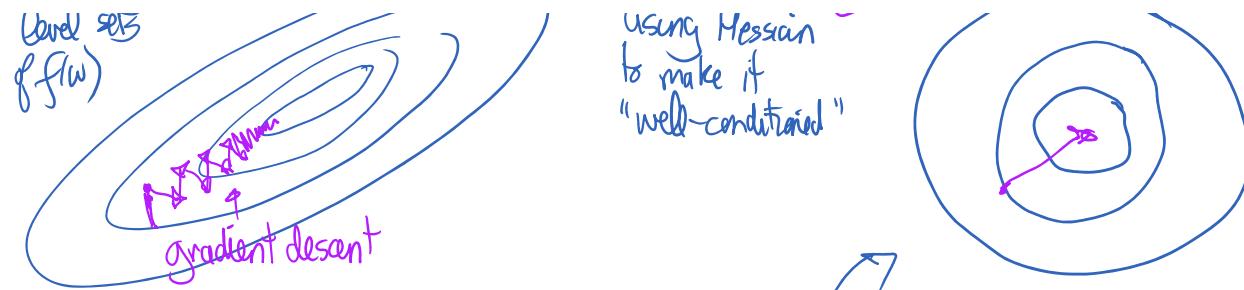
why Newton's method?

- much faster convergence in # of iterations vs gradient descent
- affine invariant \rightarrow invariant to rescaling of variables

Newton is transforming
space
using Hessian
to make it $\perp \dots$

level sets
 $f(f(w))$

but iterations are
costly $O(d^3)$ time
 $\rightarrow O(d^2)$ memory
vs.
 $O(d)$ for GD.



$$z = H^{-1}x$$

$$\nabla f(z) = H^{-1} \nabla f(x)$$

level sets
of $f(z)$

$$\frac{1}{2} z^T H z = c$$

$$\frac{1}{2} z^T P^T \Sigma P z = c$$

look at "quadratic forms"

(sidenote on implicit regularization properties of optimization method)

Newton's method for logistic regression : IRLS

$$\text{recall for log. reg., } \nabla l(w) = \sum_{i=1}^n x_i [y_i - \sigma(w^T x_i)]$$

$$H(l(w)) = \sum_{i=1}^n x_i x_i^T \sigma(w^T x_i) \sigma(-w^T x_i)$$

$$v^T H v = - \sum_{i=1}^n \underbrace{(v^T x_i)(x_i^T v)}_{(v^T x_i)^2 \geq 0} \underbrace{\sigma(-)\sigma(-)}_{\geq 0}$$

i.e. $v^T H v \leq 0 \quad \forall v \in \mathbb{R}^d$
 $\Rightarrow H \leq 0$

notation:

$$\text{recall } X = \begin{pmatrix} - & x_1^T \\ & \vdots \\ - & x_n^T \end{pmatrix}$$

$$\text{let } \mu_i \triangleq \sigma(w^T x_i) \in [0, 1]$$

i.e. concave function

Let $\mu_i \triangleq \sigma(w^T x_i) \in [0, 1]$

$$\nabla \ell(w) = \sum_{i=1}^n x_i [y_i - \mu_i] = X^T (y - \mu)$$

Hessian : $= - \sum_{i=1}^n x_i x_i^T \mu_i (1 - \mu_i) = -X^T D(w) X$ where $D_{ii} = \mu_i(1 - \mu_i)$

[note: D depends]

Newton's update (here Newton's updates are maximizing log-likeli. because it is concave)

Newton's update :

$$w_{t+1} = w_t - (-X^T D_t X)^{-1} X^T (y - \mu_t)$$

$$= (X^T D_t X)^{-1} [(X^T D_t X) w_t + X^T (y - \mu_t)]$$

$$w_{t+1} = (X^T D_t X)^{-1} [X^T D_t z_t] \quad \text{where } z_t \triangleq X w_t + D_t^{-1} (y - \mu_t)$$

This is a solution to "weighted least square problem"

$$\min_w \|D^{1/2} (z_t - X w)\|^2$$

w new target

$$\sum_{i=1}^n \frac{(z_i - x_i^T w)^2}{d_{ii}^{-1}}$$

Compare with Gaussian noise model for L.S.

$$\sum_i (y_i - x_i^T w)^2 / \sigma^2$$

$\frac{1}{n} \sum_{i=1}^n \frac{1}{d_{ii}} \rightarrow$
 Gaussian noise model
 for L.S.
 data dependent noise

Newton's method for logistic regression

= iterative reweighted least square (IRLS)

2 comments for assignment:

1) stopping criterion: $\|\nabla f(\omega)\| \leq \epsilon$

2) to compute $A^\top V A \backslash V$

Big data Logistic regression:

- cannot do $O(d^2)$ or $O(d^3)$ operations \Rightarrow first order methods

- if n is huge, you cannot do batch method

$$\text{Suppose } f(\omega) = \frac{1}{n} \sum_{i=1}^n f_i(\omega)$$

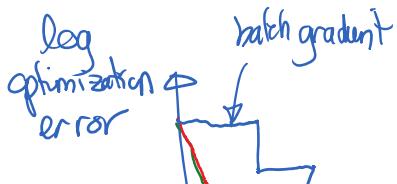
$$\nabla f(\omega) = \left(\sum_{i=1}^n \nabla f_i(\omega) \right)$$

gradient of one f.i.
"batch" gradient

instead you "incremental gradient methods"

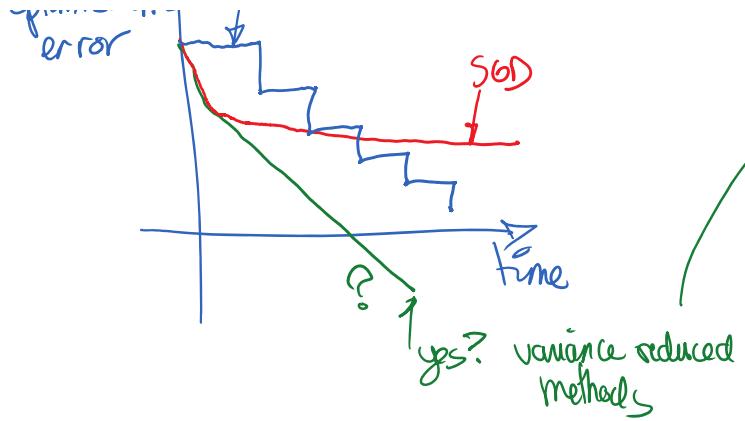
e.g. stochastic gradient descent (SGD): $\omega_{t+1} = \omega_t - \gamma_t \nabla f_{i_t}(\omega_t)$ $O(d)$ time
 where i_t is picked randomly

SGD \rightarrow cheap updates, but slower convergence per iteration



batch gradient \rightarrow expensive, but fast " " " "

SGD



SAG : stochastic averaged gradient

[2012]

$$G.D. : w_{t+1} = w_t - \gamma_t \sum_{i=1}^n \nabla f_i(w_t)$$

$$SAG : w_{t+1} = w_t - \gamma_t \sum_{i=1}^n v_i \quad \text{where } v_i = \nabla f_i(w_{old(i)})$$

vⁱ & memory

at each t, update only one $v_{i,t} \triangleq \nabla f_i(w_t)$

$$SAGA : w_{t+1} = w_t - \gamma \left(\nabla f_{i,t}(w_t) + \frac{1}{n} \sum_{j=1}^n (v_j - v_{i,t}) \right)$$

(default method
for logistic regression in Scikit-learn)