

Lecture 17 - scribbles

Tuesday, November 12, 2019 14:30

- max Ent. duality
- exponential family

quick presentation of Lagrangian duality

convex optimization problem : $\min_x f(x)$

- f, f_j are convex fct., s.t. $f_j(x) \leq 0 \quad \forall j=1, \dots, m$
- g_k affine fct. $g_k(x) = 0 \quad \forall k=1, \dots, n$

} "primal problem"

Lagrangian fct. $\mathcal{L}(x, \lambda, \nu) \triangleq f(x) + \sum_{j=1}^m \lambda_j f_j(x) + \sum_{k=1}^n \nu_k g_k(x)$

"Lagrange multipliers"

magic trick
(saddle pt. interpretation)
of Lagrangian duality

$$h(x) = \sup_{\lambda \geq 0, \nu} \mathcal{L}(x, \lambda, \nu) = \begin{cases} f(x) & \text{if } x \text{ is feasible} \\ +\infty & \text{if " " not feasible} \end{cases}$$

an equivalent problem to primal problem

inf $x \in \mathbb{R} \left(\sup_{\lambda \geq 0, \nu} \mathcal{L}(x, \lambda, \nu) \right)$

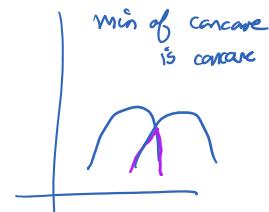
↓
duality trick
is to swap inf & sup

$h(x)$ fancy non-smooth fct.

$\sup_{\lambda \geq 0} \inf_x \mathcal{L}(x, \lambda, \nu)$

$\triangleq g(\lambda, \nu)$ Lagrange dual fct.

this fct. is always concave



Lagrange dual problem

$\sup_{\lambda, \nu} g(\lambda, \nu)$

dual variables

in general $\sup_{\lambda, \nu} \inf_x \mathcal{L}(x, \lambda, \nu) \leq \inf_x \sup_{\lambda, \nu} \mathcal{L}(x, \lambda, \nu)$

weak duality (always true)

\downarrow
 $\sup_{\lambda, \nu} \inf_x \mathcal{L}(x, \lambda, \nu) = \inf_x \sup_{\lambda, \nu} \mathcal{L}(x, \lambda, \nu)$

strong duality when $\sup_{\lambda, \nu} \mathcal{L} = \inf_x \sup_{\lambda, \nu} \mathcal{L}$

(\Leftrightarrow when primal is convex
+ constraint qualification condition (e.g. Slater's condition))

(can get optimal primal variables $\mathbf{x}^*(\lambda^*, \nu^*)$ using KKT conditions)

see chapter 5 in Boyd's book for more info on duality: <http://stanford.edu/~boyd/cvxbook/>

dual problem for max. entropy

MaxENT in primal form

(P)

$$\min_q \quad \text{KL}(q || u)$$

$$\begin{aligned} & \sum_x q(x) \log \frac{q(x)}{u(x)} \\ & q(x) \geq 0 \quad \forall x \\ & \sum_x q(x) = 1 \\ & \sum_x q(x) T_j(x) = \alpha_j \quad \forall j \end{aligned}$$

$u(x) \triangleq \frac{1}{|X|}$
 absorb this constraint
 by domain definition
 of $\text{KL}(q || u)$ i.e.
 $\text{KL}(q || u) = \begin{cases} +\infty & q(x) > 0 \\ \text{some} & \text{else} \end{cases}$

M

$$\mathcal{L}(q, \nu, c) = \sum_x q(x) \log \frac{q(x)}{u(x)} + \sum_j \nu_j (\alpha_j - \mathbb{E}_q[T_j(x)]) + c(1 - \sum_x q(x))$$

$$\frac{\partial}{\partial q(x)} = 1 + \log \frac{q(x)}{u(x)} - \sum_j \nu_j T_j(x) - c = 0$$

$$\Rightarrow q^*(x) = u(x) \exp(\sum_j \nu_j T_j(x) + c - 1)$$

Exponential family?

dual f.f.:

$$\text{plug back } q^* \text{ in } \mathcal{L}(\dots) \quad g(\nu, c) = \mathcal{L}(q^*, \nu, c)$$

$$= \mathbb{E}_{q^*} [\nu^T T(x) + c - 1] + \nu^T \alpha - \mathbb{E}_{q^*} [\nu^T T(x)]$$

$$= \nu^T \alpha + c - \sum_x u(x) \exp(\nu^T T(x)) \exp(c-1)$$

$\triangleq Z(\nu)$

max $g(\nu, c)$

$$\text{with respect to } c \quad D_c = 0 \quad \Rightarrow \quad 1 - Z(\nu) \exp(c-1) = 0$$

$$\Rightarrow \exp(c^*-1) = \frac{1}{Z(\nu)}$$

$$\text{plug back } c^*: \quad \max_c g(\nu, c) = \nu^T \alpha + c^* - Z(\nu) \frac{1}{Z(\nu)}$$

$$z(v) \quad C-1 = -\log(z(v))$$

dual problem
 $\max_{\gamma} \tilde{g}(\gamma)$

$$\tilde{g}(\gamma) \triangleq \gamma^T \alpha - \log Z(\gamma)$$

link with MLE:

$$\text{if } \alpha = \frac{1}{n} \sum_{i=1}^n T(x_i) = \mathbb{E}_{p_n} [T(X)]$$

$$\text{then } \tilde{g}(\gamma) = \frac{1}{n} \sum_{i=1}^n [\underbrace{\gamma^T T(x_i)}_{\log p(x_i | \gamma) + \text{const. where } p(x_i | \gamma) \propto \exp(\gamma^T T(x_i) - \ln Z(\gamma))} - \ln Z(\gamma)]$$

$$\text{i.e. dual problem is } \max_{\gamma} \tilde{g}(\gamma) = \max_{\gamma} \frac{1}{n} \sum_i \log p(x_i | \gamma) \text{ i.e. MLE}$$

to summarize: ML in the exp. family with $T(x)$ as sufficient statistics

is equivalent to Max. entropy with moment constraints on $T(x)$

$$\text{where } \alpha = \mathbb{E}_{p_n} [T(X)]$$

they are Lagrangian dual of each other

MLE in exp. family \Leftrightarrow moment matching in exp. family

$$\text{note: } \nabla_{\gamma} \ln Z(\gamma) = \frac{1}{Z(\gamma)} \nabla_{\gamma} \sum_x u^T x \exp(\gamma^T T(x)) = \sum_x \left(\frac{1}{Z(\gamma)} u^T x \exp(\gamma^T T(x)) \right) T(x)$$

$$p(x | \gamma)$$

$$\nabla_{\gamma} \ln Z(\gamma) = \mathbb{E}_{p(x | \gamma)} [T(x)] \triangleq \mu(\gamma) \text{ "model moment"}$$

$$\nabla_{\gamma} \tilde{g}(\gamma) = \underbrace{\mathbb{E}_{p_n} [T(x)]}_{\mu_n \text{ "empirical moment"}}$$

$$\nabla_{\gamma} \tilde{g}(\gamma) = 0 \Rightarrow \boxed{\mu(\gamma^*) = \hat{\mu}_n} \text{ i.e. moment matching?}$$

\rightarrow see lecture 16 in 2017 for "KL Pythagorean theorem."

15h40

(see end of old lecture 16 2017 for "KL Pythagorean theorem"
 and I-projection vs. M-projection for KL + geometry)

Exponential family

a (flat/canonical) exponential family on X

is a parametric family of distributions defined by two quantities

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I) $h(x) d\mu(x)$ → reference measure on X
 reference base measure ⇐ counting (discrete R.V.)
 density measure ⇐ Lebesgue (cts. R.V.)

II) $T: X \rightarrow \mathbb{R}^P$ called "sufficient statistics" vector
 a.k.a. feature vector
 defining pieces ($\rightarrow \sum x_i$)

members of family will have dist:

$$p(x; n) d\mu(x) = \exp(n^T T(x) - A(n)) h(x) d\mu(x)$$

canonical parameter
 log normalizing or cumulant generating func.
 log partition func.

If $\sum x_i$ is discrete, then $p(x; n)$ is a pmf
 " " cts. " " " " pdf

* want $1 = \int_X p(x; n) d\mu(x) = \int_X \exp(n^T T(x)) e^{-A(n)} h(x) d\mu(x)$

$$\int_X \exp(n^T T(x)) h(x) d\mu(x) \stackrel{z(n)}{=} A(n) \triangleq \log \left(\int_X \exp(n^T T(x)) h(x) d\mu(x) \right)$$

domain $\Omega \triangleq \{n \in \mathbb{R}^P \mid A(n) < \infty\}$
 (set of valid canonical parameters)

Note: $A(n)$ is convex in n

$\Rightarrow \Omega$ is convex

⊕ more generally, consider a reparameterization of a subset of the family

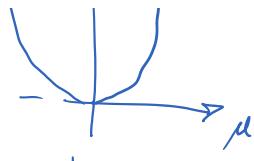
by defining the mapping $M: \Theta \rightarrow \Omega$
 ↗ new set of parameters

consider $p(x; \theta) \triangleq p(x; n(\theta))$ for $\theta \in \Theta$

(get a "curved exponential family" if $M(\Theta)$ is a curved manifold in Ω)

↳ e.g. could consider Gaussians where $N(\mu, \sigma^2)$





* note: any single distribution can be put in an exponential family by using $h(x) \stackrel{\Delta}{=} p(x)$

- two examples of family not an exp. family:
- mixture of Gaussians
(latent variable models)
 - $\text{unif}(0, \theta)$

Example: (Multinomial)

$$X \sim \text{Mult}(\pi) \quad X = \{0, 1\}^K$$

$$\Omega_X = \Delta_K \cap X \quad (\text{one encoding})$$

parameters $\pi \in \Delta_K$; suppose $\pi_i > 0 \forall i$

$$\begin{aligned} p(x; \pi) &= \prod_{j=1}^k \pi_j^{x_j} = \exp \left(\sum_j x_j \log \pi_j \right) \\ &\text{think as "G"} \\ &= \exp(\eta(\pi)^T x - C) \end{aligned}$$

$$\text{we have } M_j(\pi) = \log \pi_j$$

$$T(x) = x$$

$d\mu(x) \sim \text{counting measure on } X$

$$h(x) = \mathbb{1}\{x \in \Omega_X\} = \mathbb{1}\{x \text{ has exactly one non-zero entry equal to 1}\}$$

$$\textcircled{H} = \text{int}(\Delta_K) \quad \text{here, } A(h(\pi)) = 0 \quad \forall \pi \in \textcircled{H}$$

$$\text{but here } \textcircled{L} = \mathbb{R}^K$$

$\textcircled{H} \rightarrow \text{dimension } K-1$

$$\eta(\textcircled{H}) \rightarrow \dots \quad K-1$$

$$\textcircled{L} \rightarrow \text{dimension } K$$

we do not have a "minimal exponential family"

note: for any x s.t. $h(x) \neq 0$

$$\text{here, } \sum_j T_j(x) = \sum_j x_j = 1$$

$$\text{here, } \sum_{j=1}^k T_j(x) = x_j = 1$$

affine linear dep between components of T

\Rightarrow multiple n 's give rise to same distribution;
("overparametrization")

not a "minimal" exp. family

⊕ for multinomial, minimal exp. family

$$T(x) = \begin{pmatrix} x_1 \\ \vdots \\ x_{k-1} \end{pmatrix}$$

$$Z(n) = \sum_{x \in \Omega_x} \exp(n^T x) = \sum_{j=1}^{k-1} \exp(n_j) + 1$$

$$p(x; n) = \exp \left(\sum_{j=1}^{k-1} n_j x_j - \log \left(\sum_{j=1}^{k-1} e^{n_j} + 1 \right) \right)$$

$$\text{recall: } D_n A(n) = \mathbb{E}_{p(x; n)} [T(x)] \quad (\text{valid for } n \in \text{int}(\Omega))$$

$$\begin{aligned} \text{for multinomial, } \frac{\partial A(n)}{\partial n_j} &= \frac{1}{Z(n)} \exp(n_j) = p(x=j | n) \\ &= \mathbb{E}_{p(x; n)} [T_j(x)] \text{ as required} \end{aligned}$$