

today:

- exp. family
- estimation PGM
- Sampling

Exponential family

✓ a (flat/canonical) exponential family on X

is a parametric family of dist. defined by two quantities

I) $h(x)$ $\text{d}u(x)$ \rightarrow reference measure

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base measure

 counting measure (discrete R.V.)
Lebesgue measure (cts. R.V.)

II) $T: X \rightarrow \mathbb{R}^P$ called "sufficient statistics" vector

aka. feature vector

members of the family will have dist.

$$p(x; \theta) d\mu(x) = \exp(\theta^\top T(x) - A(\theta)) |h(x) d\mu(x)|$$

"canonical parameter" → log normalization or cumulant gen. fct.
or
log partition fct.

If Ω_X is discrete, then $p(x; n)$ is a pmf
 " " Cfs. " " " " " " a pdf

$$* \text{ want } 1 = \int_X p(x; n) d\mu(x) = \exp(m^T T(x)) e^{-A(n)} h(x) d\mu(x)$$

$$\Rightarrow A(m) \triangleq \log \left(\int_X \exp(m^\top T(x)) h(x) d\mu(x) \right)$$

$$\underline{\text{domain}} \quad \Omega \triangleq \{n \in \mathbb{N}^P \mid A(n) < \infty\}$$

(set of valid canonical parameters)

Note: $A(n)$ is convex in $n \Rightarrow \Omega$ is convex

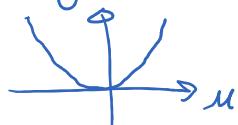
 more generally , consider a reparameterization of a subset of the family

by defining $\eta: \mathbb{H} \rightarrow \mathbb{R}$
 new set of parameters

consider $p(x; \theta) \triangleq p(x; \eta(\theta)) \text{ for } \theta \in \mathbb{A}$

(get a "curved exponential family" if $\eta(\mathbb{H})$ is a curved manifold in \mathbb{R})

↳ e.g. could consider Gaussians where $N(\mu, \sigma^2)$



* note: any single dist. $p(x)$ can be put in
 an exponential family by using $h(x) = p(x)$

* two examples of family not an exp. family:

- Mixture of Gaussians
 (latent variable model)
- unif(0, 1)

Example: (Multinomial)

$$X \sim \text{Mult}(\pi) \quad X = \{\alpha_1, \beta\}^K$$

$$\Omega_X = \Delta_K \cap X \quad (\text{one-hot encoding})$$

parameters $\pi \in \Delta_K$; suppose $\pi_i > 0 \quad \forall i$

$$p(x; \pi) = \frac{1}{\prod_{j=1}^K \pi_j^{x_j}} = \exp \left(\sum_{j=1}^K x_j \log \pi_j \right)$$

think as "S"

$$= \exp \left(\sum_{j=1}^K x_j \log \pi_j - 0 \right)$$

$$\text{we have } \eta_j(\pi) = \log \pi_j \quad \Omega = \mathbb{R}^K$$

$$T(x) = x$$

cl_{ul}(x) = counting measure on X

$$h(x) = \mathbb{1}\{x \in \Omega_X\} = \mathbb{1}\{x \in \Delta_X \cap X\}$$

$$\mathbb{H} = \text{int}(\Delta_K) \quad A(\eta(\pi)) = 0 \quad \forall \pi \in \mathbb{H}$$

$\mathbb{H} \rightarrow \text{dimension } K-1$

$\eta(\mathbb{A}) \rightarrow \text{'' } K-1$

$\Omega \rightarrow \mathbb{R}^K$

we do not have a "minimal exp family"

Note: for any x s.t. $h(x) \neq 0$

$$\text{then, } \sum_{j=1}^k T_j(x) = \sum_{j=1}^k x_j = 1$$

affine linear dep. between T

\Rightarrow multiple n 's give rise to same distribution
"overparametrization"

not a "minimal" exp family

(*) for multinomial, minimal exp family

$$T(x) = \begin{pmatrix} x_1 \\ \vdots \\ x_{k-1} \end{pmatrix}$$

$$Z(n) = \sum_{x \in \Omega} \exp(n^T T(x)) = \sum_{j=1}^{k-1} \exp(n_j) + 1$$

$$p(x; n) = \exp\left(\sum_{j=1}^{k-1} n_j x_j - \underbrace{\log\left(\sum_{j=1}^{k-1} e^{n_j} + 1\right)}_{A(n)}\right)$$

recall: $D_n A(n) = \mathbb{E}_{p(x; n)}[T(x)]$ (valid for $n \in \text{int}(\Omega)$)

$$\text{for multinomial, } \frac{\partial A(n)}{\partial n_j} = \frac{1}{Z(n)} e^{n_j} = p(x=j | n)$$

$$= \mathbb{E}_{p(x|n)}[T_j(x)] \text{ as required //}$$

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example 2: 1d Gaussian

$X \sim N(\mu, \sigma^2)$ $X \in \mathbb{R}$ $\Theta = (\mu, \sigma^2)$ "moment parameterization"

$$p(x; (\mu, \sigma^2)) = \frac{1}{\sqrt{2\pi\sigma^2}} \exp\left(-\frac{(x-\mu)^2}{2\sigma^2}\right)$$

$$= \exp\left(-\frac{x^2}{2} \left[\frac{1}{\sigma^2}\right] + x \left[\frac{\mu}{\sigma^2}\right] - \left[\frac{\mu^2}{2\sigma^2} + \frac{1}{2} \log(2\pi\sigma^2)\right]\right)$$

$$T(x) = \begin{bmatrix} x \\ -x^2 \end{bmatrix} \quad n(\theta) = \begin{bmatrix} \mu/\sigma^2 \\ -\mu^2/(2\sigma^2) - \log(2\pi\sigma^2)/2 \end{bmatrix} = \begin{bmatrix} n_1 \\ n_2 \end{bmatrix}$$

$$T(x) = \begin{bmatrix} x \\ -\frac{x^2}{2} \end{bmatrix} \quad m(\theta) = \begin{bmatrix} \mu/\sigma^2 \\ 1/\sigma^2 \end{bmatrix} = \begin{bmatrix} m_1 \\ m_2 \end{bmatrix}$$

$$m_2 = \frac{1}{\sigma^2} = \text{precision} > 0$$

$$m_1 = m_2 \cdot \mu$$

$$\mathcal{L} = \{(m_1, m_2) : m_2 > 0, m_1 \in \mathbb{R}\}$$

[we'll see later: multivariate Gaussian $\mathcal{L} = \mathcal{E}^{-1}$
 $m = \mathcal{L}\mu = \Sigma^{-1}\mu$]

$$T(x) = \begin{bmatrix} x \\ -\frac{x^2}{2} \end{bmatrix}$$

Example 3: discrete UGM?

let $p \in \mathcal{P}(G)$, G is undirected

with $\psi_c(x_c) > 0 \quad \forall c, x_c$

$$\begin{aligned} p(x) &= \prod_{c \in C} \psi_c(x_c) = \exp \left(\sum_c \log \psi_c(x_c) - \log z \right) \\ &= \exp \left(\sum_{c \in C} \sum_{y_c \in X_c} \underbrace{\mathbb{I}_{\{x_c = y_c\}}}_{T_{c,y_c}(x)} \underbrace{\log \psi_c(y_c)}_{m_{c,y_c}} - \log z \right) \end{aligned}$$

$$T(x) = \begin{pmatrix} \vdots \\ \mathbb{I}_{\{x_c = y_c\}} \\ \vdots \end{pmatrix}_{y_c \in X_c \atop c \in C} \quad X_c = \{(y_i)_{i \in c} : y \in X\}$$

$$m(\theta) = \begin{pmatrix} \log \psi_c(y_c) \\ \vdots \end{pmatrix} \quad [\text{not a minimal representation}]$$

Notes: a) Mult(π) is a special case where complete graph (1 big clique)

b) feature perspective: instead of using all possible indicators $\mathbb{I}_{\{x_c = y_c\}}$
you could use a subset for a task

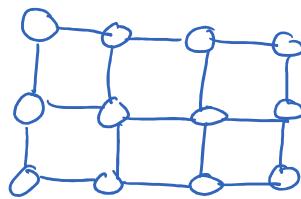
for example: suppose x is sentence
 x_i is a word

feature on $x_i \in \{x_{(i)} \text{ e.g. } \mathbb{I}_{\{x_i \text{ is a verb}\}}\}$

$x_{i,j}$ is a noun

c) binary Ising model

$$x_i \in \{0, 1\} \quad |C| \leq 2$$



Suppose use radius $\frac{1}{2}$ pairs (edges) as cliques

\Rightarrow dimension of $T(x)$ is $2|V| + 4|E|$ \rightsquigarrow "overparametrized"
exp. family

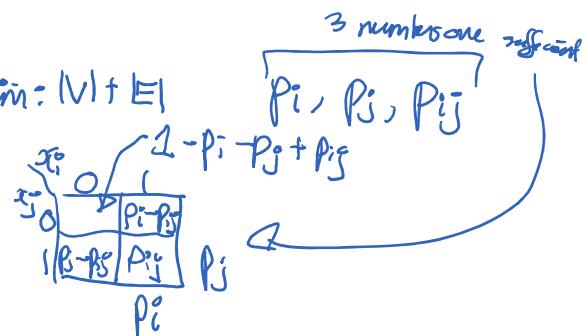
$$\sum_{y_C} T_{C,y_C}(x) = 2 \text{ for any } C \Rightarrow \text{not a min-exp family}$$

* a minimal representation:

is

$$T(x) = \begin{pmatrix} (x_i)_{i \in V} \\ (x_i x_j)_{\{(i,j)\} \in E} \\ \downarrow \prod_{i,j} x_i = 1, x_j = 1 \end{pmatrix}$$

\rightarrow dim: $|V| + |E|$



Properties of A :

- $D_m A(n) = \mathbb{E}_{p(x; n)} [T(x)] \triangleq \mu(n)$ "moment vector" (for $n \in \text{int}(\Omega)$)
- $\left(\frac{\partial^2 A(n)}{\partial n_i \partial n_j} \right)_{ij} = \mathbb{E}_{p(x; n)} [(T(x) - \mu(n)) (T(x) - \mu(n))^T] = \text{cov}(T(x))$
(proof as exercise)

Estimation of parameters in DGM

DGM: parametric family $P_{\Theta} = \{f_{\Theta}(x) = \prod_i p(x_i | x_{\pi_i}; \Theta_i)\}_{\Theta}$

$$\Theta = (\theta_1, \dots, \theta_m)$$

$$\in \mathcal{G} = \Theta_1 \times \Theta_2 \times \dots \times \Theta_m$$

independent parameterization
ie. no tying of parameters

\Rightarrow MLE decouples in $|V|$ independent MLE problems

$$\{x^{(i)}\}_{i=1}^n \quad p(\text{data} | \Theta) = \prod_{i=1}^n p(x^{(i)} | \Theta) = \prod_{i=1}^n \prod_{j=1}^{|V|} p(x_j^{(i)} | x_{\pi_j}^{(i)}; \Theta_j)$$

$$\log [\dots] = \sum_{j=1}^{|\mathcal{Y}|} \left(\sum_{i=1}^n \log p(x_j^{(i)} | x_{\pi_j^{(i)}}; g_j) \right)$$

Example: for discrete R.V.

$$\Rightarrow G_j^{\text{MLE}} = \text{proportion of observations}$$

$$(\text{fully observed DGM is relatively easy})$$

$$G_j^{\text{MLE}} = \frac{\#(x_j = k, x_{\pi_j} = \text{something})}{\#(x_{\pi_j} = \text{something})}$$

- ⊕ if have latent variable (i.e. unobserved variables)
- ⇒ use EM. (like HMM)

DGM:

example for exp. family

$$p(x|n) = \exp \left(\sum_c n_c T_c(x_c) - A(n) \right)$$

→ unlike in a DGM, $\log p(x|n)$ does not separate as $\sum_c f_c(n_c)$

gradient ascent on log likelihood

$$\frac{1}{n} \sum_i^n \log p(x^{(i)}|n) = \sum_c n_c^T \left(\underbrace{\frac{1}{n} \sum_{i=1}^n T_c(x_c^{(i)})}_{\mu_c} \right) - \gamma \frac{A(n)}{n}$$

$$\nabla_{m_c} [\dots] = \mu_c - \mu_c(n) \quad \hookrightarrow \mathbb{E}_{p(x_i|n)} [T_c(x_c)]$$

to compute this, need inference

e.g. Ising model $T_{ij}(x_i, x_j) = x_i \cdot x_j$

$$\mathbb{E}[T_{ij}] = \mu_{ij} = p(x_i=1, x_j=1 | n)$$

here need approx. inference

Sampling
Variational method