

## Lecture 19 - exponential families

November 12, 2021 2:53 PM

- today:
  - exp. family
  - estimation DGM/UGM
  - sampling

moment matching different than MLE in exp. family

$$\text{gamma dist. has } T(z) = \begin{bmatrix} \log z \\ z \end{bmatrix}$$

so moment matching with  $\tilde{T}(x) = \begin{bmatrix} x \\ x^2 \end{bmatrix}$  will yield  
different estimate than MLE

example 2: 1d Gaussian

$$X \sim N(\mu, \sigma^2) \quad X = \mathbb{R} \quad \Theta = (\mu, \sigma^2) \quad \text{"moment parameterization"}$$

$$\begin{aligned} p(x; \mu, \sigma^2) &= \frac{1}{\sqrt{2\pi\sigma^2}} \exp\left(-\frac{(x-\mu)^2}{2\sigma^2}\right) \\ &= \exp\left(-\frac{x^2}{2} \underbrace{\left[\frac{1}{\sigma^2}\right]}_{m_2} + x \underbrace{\left[\frac{\mu}{\sigma^2}\right]}_{m_1} - \left[\frac{\mu^2}{2\sigma^2} + \frac{1}{2} \log(2\pi\sigma^2)\right]\right) \end{aligned}$$

$$T(x) = \begin{bmatrix} x \\ -\frac{x^2}{2} \end{bmatrix} \quad m(\Theta) = \begin{bmatrix} \mu/\sigma^2 \\ 1/\sigma^2 \end{bmatrix} = \begin{bmatrix} m_1 \\ m_2 \end{bmatrix}$$

$$m_2 = \frac{1}{\sigma^2} = \text{precision} > 0$$

$$m_1 = m_2 \cdot \mu$$

$$h(x) = 1 \quad \begin{array}{l} (\text{most people}) \\ \text{use } h(x) = \frac{1}{\sqrt{2\pi}} \text{ for Gaussian} \end{array}$$

$$\mathcal{L} = \{(m_1, m_2) : m_2 > 0, m_1 \in \mathbb{R}\}$$

$$[\text{we'll see later: Multivariate Gaussian } T(x) = \begin{bmatrix} x \\ -\frac{x^T x}{2} \end{bmatrix} \quad \begin{cases} \mathcal{L} = \mathbb{Z}^{-1} \\ m = \mathcal{L}\mu = \mathbb{Z}^{-1}\mu \end{cases}]$$

example 3: discrete UGM

let  $p \in \mathcal{P}(G)$ ,  $G$  is undirected  
with  $N_C(x_C) \geq 0 \forall C, x_C$

$$p(x) = \frac{1}{Z} \prod_{C \in G} N_C(x_C) = \exp\left(\sum_C \log N_C(x_C) - \log Z\right)$$

$$= \exp\left(\sum_{C \in G} \sum_{y_C \in X_C} \underbrace{\underbrace{\mathbb{1}_{\{y_C = x_C\}}}_{T_{C, y_C}(x)} \underbrace{\log N_C(y_C)}_{m_{C, y_C}}}_{\sim \log Z}\right)$$

$$T(x) = \begin{pmatrix} \vdots \\ \mathbb{1}_{\{x_C = y_C\}} \\ \vdots \end{pmatrix}_{y_C \in X_C, C \in G} \quad X_C = \{(y_i)_{i \in C} : y_i \in X_i\}$$

$$m(\Theta) = \int \dots \int_{y_1, \dots, y_n} \dots \int_{y_{n-1}, y_n} \quad [\text{not a minimal representation}]$$

$$n(\theta) = \left( \log \sum_{\substack{y_c \in \mathcal{Y}_c \\ c \in \mathcal{C}}} \theta_c^{x_c} \right) \quad [\text{not a minimal representation}]$$

notes: a) Mult( $x$ ) is a special case where have complete graph (1 big clique)

b) feature perspective: instead of using all possible indicators  $\{1 \mid y_c = x_c\}$   
you could use a subset for a task

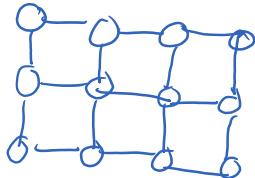
for example: suppose  $x$  is a sentence  
 $x_i$  is "word"

feature on  $x_p \mid x_{i+1}$  e.g.  $\{1 \mid x_p \text{ is a verb}, x_{i+1} \text{ is noun}\}$

→ much smaller set of parameters

c) binary Ising model

$$x_i \in \{0, 1\} \quad |G| \leq 2$$



Suppose use nodes & pairs (edges) as degrees

⇒ dimension of  $T(x)$  is  $2|M| + 4|E| \rightarrow$  "overparameterized"

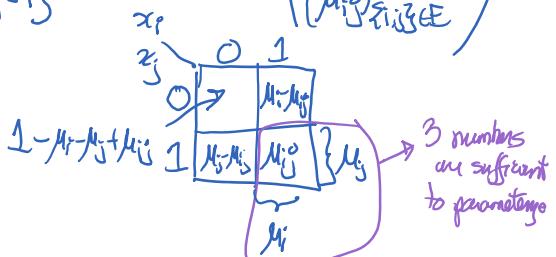
$$\sum_{y_c} T_{c,y_c}(x) = 1 \quad \text{for any } c$$

→ not a min. exp family

\* a minimal representation

$$\text{i.e. } T(x) = \begin{pmatrix} (x_i)_{i \in V} \\ (x_i x_j)_{i, j \in E} \end{pmatrix}_{n_i, n_{ij}} \rightarrow \dim: |V| + |E|$$

$$ET(x) = \begin{pmatrix} (\mu_i)_{i \in V} \\ (\mu_{ij})_{i, j \in E} \end{pmatrix}$$



properties of  $A$ :

- $\nabla_m A(m) = \mathbb{E}_{p(x|m)} [T(x)] \triangleq \mu(m)$  "moment vector" (for  $m \in \text{int}(\Omega)$ )
- $\left( \frac{\partial^2 A(m)}{\partial m_i \partial m_j} \right)_{ij} = \mathbb{E}_{p(x|m)} [ [T(x) - \mu(m)] [T(x) - \mu(m)]^T ] = \text{cov}(T(x))$   
(proof as exercise)

"cumulant generating fn."

Cumulant generating fct.

16h02

## Estimation of parameters DGM/UGM

DGM:  
(fully observed)

parametric family  $P_{\Theta} = \{ p(x) = \prod_i p(x_i | z_{\eta_i}, \Theta_i) \}_{\Theta = (\Theta_1, \dots, \Theta_M)}$

$\Theta = (\Theta_1, \dots, \Theta_M)$

$E(\Theta) = \Theta_1 \times \Theta_2 \times \dots \times \Theta_M$

Independent parameterization  
i.e. no tying parameters

$\Rightarrow$  MLE decouples in  $M$  independent MLE problems

$$\{x^{(i)}\}_{i=1}^n \quad p(\text{data} | \Theta) = \prod_{i=1}^n p(x^{(i)} | \Theta) = \prod_{i=1}^n \prod_{j=1}^{M_i} p(x_j^{(i)} | z_{\eta_j}^{(i)}, \Theta_j)$$

$$\log [ ] = \sum_{j=1}^{M_i} \left( \sum_{i=1}^n \log p(x_j^{(i)} | z_{\eta_j}^{(i)}, \Theta_j) \right)$$

example: for discrete r.v.  
(multinomial  
conditionals)

$\Rightarrow \hat{\Theta}_j^{\text{MLE}} = \text{proportion of observations}$

$$\hat{p}(x_j=k | z_{\eta_j} = \text{stuff}) \approx \frac{\#(x_j=k, z_{\eta_j} = \text{stuff})}{\#(z_{\eta_j} = \text{stuff})}$$

(fully observed DGM is relatively easy)

⊕ if have latent variable (i.e. unobserved variables)  
 $\Rightarrow$  use EM, (like HMM)

UGM:

example for expo family

$$p(x|m) = \exp \left( \sum_c m_c T_c(x) - A(m) \right)$$

$\rightarrow$  unlike in a DGM,  $\log p(x|m)$  does not separate as  $\sum_c f_c(m_c)$

gradient ascent on log-likelihood

$$\frac{1}{n} \sum_{i=1}^n \log p(x^{(i)}|m) = \sum_c m_c^T \left( \left( \sum_{i=1}^n T_c(x_i^{(i)}) \right) - n \bar{A}(m) \right)$$

$$\nabla_{m_c} [ ] = \hat{m}_c - m_c(m) \xrightarrow{\text{compute}} \mathbb{E}_{p(x|m)} [T_c(x)]$$

to compute this, need inference

e.g. Ising model  $T_{ij}(x_i, x_j) = x_i \cdot x_j \quad (x_i \in \{-1, 1\})$

$$\mathbb{E}[T_{ij}] = \hat{M}_{ij} = p(x_i=1, x_j=1|m)$$

here need approx. inference  
 $\xrightarrow{\text{Sampling}}$  e.g. gibbs sampling

here need approx. inference  
 ↓  
 sampling  
 variational  
 method

[e.g. Gibbs sampling]  
 [e.g. mean field]

## Approximate inference - Sampling

example: NP hard to do exact inference in Ising model  $\rightarrow$  need approximation

why sampling?  $X = (X_1, \dots, X_p)$

a) simulation:  $X^{(i)} \sim P$

b) approximate marginal  $p(x_i)$

$\rightarrow$  special case of expectations

consider:  $f: \mathbb{R}^P \rightarrow \mathbb{R}$

we want to approximate  $\mu = \mathbb{E}_P[f(X)]$

special case: if  $f(x) \triangleq \mathbb{1}\{X_A = x_A\}$   $\mathbb{E}_P[f(x)] = p(X_A = x_A)$

Monte Carlo integration / estimation  $\rightarrow$  appears in physics, applied math., ML, statistic, ...

to approximate  $\mu = \mathbb{E}_P[f(x)]$

### MC estimation

alg.: • n samples  $X^{(1)} \sim P$

• estimate  $\hat{\mu} = \frac{1}{n} \sum_{i=1}^n f(X^{(i)}) = \mathbb{E}_{P_n}[\hat{f}(x)]$

properties: 1) unbiased estimator  $\mathbb{E}[\hat{\mu}] = \frac{1}{n} \sum_{i=1}^n \mathbb{E}[f(X^{(i)})] = \frac{1}{n} \mu = \mu$   
 expectation over  $(X^{(i)})_{i=1}^n$   $\hat{P}_n(x) = \frac{1}{n} \sum_{i=1}^n \mathbb{1}\{x^{(i)} = x\}$   
 this is still true if  $X^{(i)}$  are dependent

$$\begin{aligned} 2) \text{ expected error (L2-error)} \quad & \mathbb{E}[\|\hat{\mu} - \mu\|^2] = \mathbb{E}\left[\left\langle \frac{1}{n} \sum_i f(X^{(i)}) - \mu, \frac{1}{n} \sum_j f(X^{(j)}) - \mu \right\rangle\right] \\ & = \mathbb{E}\left[\frac{1}{n^2} \sum_{i,j} \langle f(X^{(i)}) - \mu, f(X^{(j)}) - \mu \rangle\right] \end{aligned}$$

by independence  $\Rightarrow$  off-diagonal terms are zero

$$\text{i.e. } \langle \underbrace{\mathbb{E}[f(X^{(i)})] - \mu}_{\hat{\mu}}, \underbrace{\mathbb{E}[f(X^{(j)})] - \mu}_{\hat{\mu}} \rangle$$

$$\begin{aligned} & = \frac{1}{n^2} \sum_{i,j} \mathbb{E}[\langle f(X^{(i)}) - \mu, f(X^{(j)}) - \mu \rangle] \\ & \quad \mathbb{E}[\|f(X^{(i)}) - \mu\|^2] \stackrel{\triangle}{=} \sigma^2 \\ & = \text{tr}(\text{cov}(f(x), f(x))) \end{aligned}$$

$$\boxed{\mathbb{E} [\|\hat{\mu} - \mu\|_2^2] = \frac{\sigma^2}{n}}$$

$$= \frac{\sigma^2}{n}$$

$$= \text{tr}(\text{cov}(g(x), \hat{f}(x)))$$

note: that no dimension Errate (apart  $\sigma^2$   
which could depend  
implicitly)

$$\text{e.g. } f(x) = X$$

$$x_j \sim N(0, \sigma^2)$$

$$\mathbb{E} [\|f(x) - \mu\|^2] = d\sigma^2$$