

today:

- Gibbs sampling
- Variational methods

Gibbs sampling alg.

↳ M.H. with a clever choice of proposal $q_t(x^*|x_t)$ [Clever: $d\pi(x^*) = 1$]

Example of applications

$$\text{UGM: } \tilde{p}(x) = \prod_c \pi_c(x_c)$$

$$\text{difficult condition in a DGM} \quad \tilde{p}(x) = p(x_{Fc}, \bar{x}_E) \delta(x_E, \bar{x}_E) \propto p(x) \delta(x_E)$$

(UGM)

Cyclic Gibbs Sampling alg.: nodes $i=1, \dots, n$

start at some $x^{(0)}$

for $t=1, \dots$

- pick $i = (t \bmod n) + 1$
- sample $x_i^{(t)} \sim p(x_i^{(t)} | X_{\setminus i}^{(t-1)})$
- set $x_j^{(t)} = x_j^{(t-1)}$ for $j \neq i$

end

⊗ Gibbs sampling is M.H. with a time varying proposal

Suppose i is picked at time t

for $x_{\setminus i}$ to stay constant

$$\text{then proposal is } q_t(x^* | x^{(t-1)}) = p(x_i^* | x_{\setminus i}^{(t-1)}) \delta(x_{\setminus i}^{(t-1)}, x_{\setminus i}^{(t-1)})$$

$$\rightarrow p(x_i^{(t-1)} | x_{\setminus i}^{(t-1)}) \delta(x_{\setminus i}^{(t-1)}, x_{\setminus i}^{(t-1)}) \rightsquigarrow x_{\setminus i}^{(t-1)} = x_{\setminus i}^t$$

M.H. acceptance ratio:

$$\alpha(x^* | x^{(t-1)}) = \frac{q_t(x^{(t-1)} | x^*) \underbrace{p(x^*)}_{p(x^{(t-1)})}}{q_t(x^* | x^{(t-1)}) \underbrace{p(x^{(t-1)})}_{p(x^*)}} \rightarrow \frac{p(x_i^*)}{p(x_i^{(t-1)})} \frac{p(x_{\setminus i}^{(t-1)})}{p(x_{\setminus i}^*)} \delta(x_{\setminus i}^{(t-1)}, x_{\setminus i}^*)$$

$$= 1 \rightsquigarrow \text{always accepts!}$$



Convergence of G.S.

- Let A be a Markov transition kernel of one full cycle of G.S. (i.e. n steps)

→ homogeneous M.C.

If we suppose that $p(x) > 0 \forall x$

$$\Leftrightarrow p(x_i | x_{-i}) > 0$$

$\forall x_i \in \mathcal{X}_i$

$\Rightarrow A$ is irreducible & aperiodic
because
 $A_{ii} > 0$

$$\Rightarrow A^t \pi_0 \xrightarrow{t \rightarrow \infty} p$$

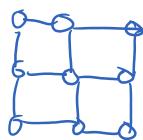
Since can get to any state with n steps

⊗ also works for a random scan (pick $i \sim \text{Unif}(1:n)$ at each step)

example: G.S. for Ising model

Ising model $x_i \in \{-1, 1\}$

VGMs



$$p(x) = \frac{1}{Z(n)} \exp\left(\sum_i m_i x_i + \sum_{(i,j) \in E} m_{ij} x_i x_j\right)$$

[minimal exp. family representation]

to do G.S.:

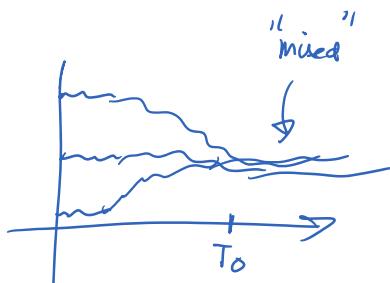
$$\begin{aligned} \text{want to compute } p(x_i | x_{-i}) &= p(x_i | x_{\text{neighbor}(i)}) \\ &\propto \exp(m_i x_i + \sum_{j \in N(i)} m_{ij} x_i x_j) \end{aligned}$$

\Rightarrow renormalize to get conditional

$$\begin{aligned} p(x_i^{(t)} = 1 | x_{-i}^{(t-1)}) &= \frac{\exp(m_i + \sum_{j \in N(i)} m_{ij} x_j^{(t-1)}) \exp(\text{rest})}{(\exp(m_i + \sum_{j \in N(i)} m_{ij} x_j^{(t-1)}) + 1) \exp(\text{rest})} \\ &= \sigma\left(m_i + \sum_{j \in N(i)} m_{ij} x_j^{(t-1)}\right) \end{aligned}$$

diagnostic of mixing

monitor mixing by running independent chains
some measurement
"sticky chain" → slow mixing



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variance methods

general idea: use optimization for approximating a quantity

e.g. say want to approximate $\langle \rangle$

then, express it as solution to opt. problem

$$\theta^* = \underset{\theta \in \Theta}{\operatorname{argmin}} f(\theta) \quad] \text{ OPT}$$

idea: approximate θ^* via an approximation to OPT

linear algebra example

say want sol'n to $Ax = b$ (i.e. $x^* = A^{-1}b$)

$$x^* = \underset{x}{\operatorname{argmin}} \|Ax - b\|^2$$

Variational EM (motivation for objective)

recall EM trick:

$$\log p(x|\theta) \geq \mathbb{E}_q \left[\log \frac{p(x, z|\theta)}{q(z)} \right] \stackrel{!}{=} \mathcal{J}(q, \theta)$$

$$\log p(x|\theta) - \mathcal{J}(q, \theta) = KL(q(\cdot) || p(z|x; \theta))$$

$$\text{E step: } \underset{\substack{q \in \text{all distributions} \\ \text{on } z}}{\operatorname{argmax}} \mathcal{J}(q, \theta^{(t)}) \Leftrightarrow \underset{q}{\operatorname{argmin}} KL(q || p(z|x; \theta^{(t)}))$$

✿ a variational approx for E step:

$$\text{do } q_{\text{approx}}^{(t+1)} = \underset{q \in Q_{\text{simple}}}{\operatorname{argmin}} KL(q || p(z|x; \theta^{(t)}))$$

Purpose of approx to approximate $p(z|x; \theta^{(t)})$

approximate M step:

$$\theta^{(t+1)} = \underset{\theta \in \Theta}{\operatorname{argmax}} \underbrace{\mathbb{E}_{q_{\text{approx}}^{(t+1)}} [\log p(x, z|\theta)]}_{\mathcal{J}(q_{\text{approx}}^{(t+1)}, \theta)}$$

still a lower bound on $\log p(x|\theta)$

but base monotonicity guarantee
on $\log p(x|\theta^{(t)})$ as a function of t

more generally, using $\underset{q \in Q}{\operatorname{argmin}} KL(p || q)$ is a variational approach
to approximate p

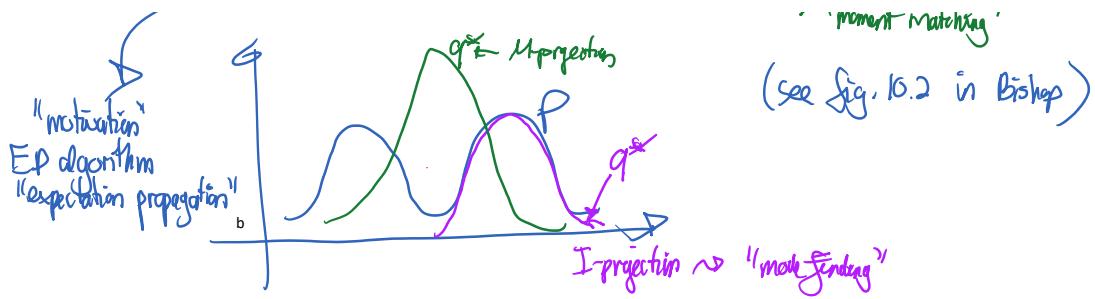
note: I-projection: if q is simple, $\mathbb{E}_q [\log \frac{p}{q}]$
can compute

$$\text{alternative: } \underset{q \in Q}{\operatorname{argmin}} KL(p || q)$$

M-projection

↳ "moment matching"

(see Fig. 10.2 in Bishop)



Mean-field approximation (section 10.1 in Bishop)

let's suppose that $p(z)$ is in exp. family

$$z_1, \dots, z_p \quad p(z) = \exp(n^T T(z) - A(n))$$

mean-field approximation $Q_{MF} = \{q(z) = \prod_i q_i(z_i)\}$
set of fully factorized distributions

$$\begin{aligned} KL(q || p) &= \mathbb{E}_q [\log \frac{q}{p}] \\ &= -n^T \mathbb{E}_q [T(z)] + A(n) + \sum_z q(z) \log \frac{q(z)}{\mathbb{E}_q [q(z)]} \\ &\quad \sum_i \sum_z q_{zi}(z_i) q_i(z_i) \log q_i(z_i) \\ &\quad \sum_i \sum_z q_i(z_i) \log q_i(z_i) \end{aligned}$$

coordinate descent on q_i 's

$$\text{fix } q_j \text{ for } j \neq i; \quad \min_{\text{w.r.t. } q_i} \underbrace{KL(q_i q_{\bar{i}} || p)}_{- \mathbb{E}_{q_i} [n^T \mathbb{E}_{q_{\bar{i}}} [T(z)]]} + \text{const.} + \sum_{z_i} q_i(z_i) \log q_i(z_i)$$

(like MaxEnt)

$$\text{add Lagrange multiplier } \lambda \text{ for } \sum_{z_i} q_i(z_i) = 1 \rightarrow \lambda (1 - \sum_{z_i} q_i(z_i))$$

$$\begin{aligned} \frac{\partial}{\partial q_i(z_i)} &= 0 \Rightarrow -f_i(z_i) + \log q_i(z_i) + \lambda - \lambda = 0 \\ &\Rightarrow q_i^*(z_i) \propto \exp(f_i(z_i)) \end{aligned}$$

④ general mean-field update when target p is in exp family

$$q_i^{(t+1)}(z_i) \propto \exp(n^T \mathbb{E}_{q_i^{(t)}} [T(z)])$$

Ising model:

$$T(z) \Rightarrow (z_i)_{i \in V} \quad z_i \in \{0, 1\}$$

$$(z_i z_j)_{(i,j) \in E}$$

$$j \neq i : \quad \mathbb{E} q_{ji}^{(t)}(z_j) = q_j^{(t)}(z_j=1) \stackrel{def}{=} \mu_j^{(t)}$$

$$\mathbb{E} q_{ji}^{(t)}(z_i z_j) = z_i \mu_j^{(t)}$$

$$m^T \mathbb{E} q_{ji}^{(t)} T(z) = m_i z_i + \underbrace{\sum_{j \in N(i)} n_j \mathbb{E} q_{ji}^{(t)}[z_j]}_{\mu_j^{(t)}} + \underbrace{\sum_{j \in N(i)} m_j \mathbb{E} q_{ji}^{(t)}[z_i z_j]}_{z_i \mu_j^{(t)}} + \text{rest (no } z_i \text{)}$$

result: $q_i^{(t+1)}(z_i) \propto \exp(m_i z_i + z_i \sum_{j \in N(i)} n_j \mu_j^{(t)})$

$$\boxed{\mu_i^{(t+1)} = \sigma(m_i + \sum_{j \in N(i)} n_j \mu_j^{(t)})}$$

MF update for $q_i(z_i)$
[with parameter μ_i]

compare with

GS. update where $z_i^{(t+1)} = 1$ with prob $\sigma(m_i + \sum_{j \in N(i)} n_j z_j^{(t)})$