

today: • Gibbs sampling
• variational methods

Gibbs sampling alg.

↳ M.H. with a clever choice of proposal $q_t(x'|x)$ [clever: $a(x'|x)=1$]

example of applications:

UGM: $\hat{p}(x) = \prod \psi_c(x_c)$

difficult conditional in UGM: $\tilde{p}(x) = p(x_{E^c}, \bar{x}_E) \delta(x_E, \bar{x}_E) \propto p(x | \bar{x}_E)$

(UGM)

cyclic Gibbs sampling alg.: nodes $i=1, \dots, n$

start at some $x^{(0)}$

for $t=1, \dots$

- pick $i = (t \bmod n) + 1$
- sample $x_i^{(t)} \sim p(x_i = \cdot | x_{\setminus i}^{(t-1)})$
true conditional on x_i as proposal
- set $x_j^{(t)} = x_j^{(t-1)}$ for $j \neq i$

end

⊛ Gibbs sampling is M.H. with a time varying proposal

suppose we pick i at time t

then the proposal is $q_t(x' | x^{(t-1)}) = p(x_i' | x_{\setminus i}^{(t-1)}) \delta(x_{\setminus i}', x_{\setminus i}^{(t-1)})$

M.H. acceptance ratio:

$$q(x' | x^{(t-1)}) = \frac{q_t(x^{(t)} | x') p(x')}{q_t(x' | x^{(t-1)}) p(x^{(t-1)})}$$

for $x_{\setminus i}$ to stay constant

$\rightarrow p(x_i' | x_{\setminus i}^{(t-1)}) \delta(x_{\setminus i}', x_{\setminus i}^{(t-1)})$

$\rightarrow p(x_i^{(t)} | x_{\setminus i}^{(t-1)}) \delta(x_{\setminus i}^{(t)}, x_{\setminus i}^{(t-1)})$

$\rightarrow p(x_i' | x_{\setminus i}^{(t-1)}) \delta(x_{\setminus i}', x_{\setminus i}^{(t-1)})$

$\rightarrow p(x_i^{(t)} | x_{\setminus i}^{(t-1)}) \delta(x_{\setminus i}^{(t)}, x_{\setminus i}^{(t-1)})$

$\rightarrow 1$

always accepts!

$$\hookrightarrow p(x_i | x_{-i}^{(t-1)}) \delta(x_i, x_{-i}^{(t-1)})$$

always accepts!

convergence of GS:

- let A be a Markov transition kernel of one full cycle of Gibbs Sampling (i.e. n steps)
- $\hookrightarrow$ homogeneous M.C.

if suppose that $p(x) > 0 \forall x \Rightarrow A$ is irreducible & aperiodic because $A_{ii} > 0$

$$\Rightarrow p(x_i | x_{-i}) > 0 \forall x_i \& x_{-i}$$

$A_{ij} > 0$
 $\begin{pmatrix} i \neq j \\ \text{since can get to any state with } n \text{ "flips"}$

$$\Rightarrow A^t \pi_0 \xrightarrow{t \rightarrow \infty} p$$

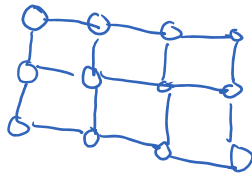
by detailed balance, p is stationary dist. of chain...

⊗ also works for a random scan (pick $i \sim \text{unif}(1:n)$ at each step)

example: G.S. for Ising model

Ising model $x_i \in \{-1, 1\}$

UGM:



$$p(x) = \frac{1}{Z(n)} \exp\left(m_i x_i + \sum_{i,j \in E} m_{ij} x_i x_j\right)$$

[minimal exp. family representation]

for G.S.,

want to compute $p(x_i | x_{-i}) \stackrel{\text{by cond. indep}}{=} p(x_i | x_{\text{neighbors}(i)})$

$$\propto \exp\left(m_i x_i + \sum_{j \in N(i)} m_{ij} x_i x_j + \text{rest}\right)$$

$\Rightarrow$ renormalize to get conditional:

$$p(x_i = 1 | x_{-i}^{(t-1)}) = \frac{\exp\left(m_i + \sum_{j \in N(i)} m_{ij} x_j^{(t-1)}\right) \exp(\text{rest})}{\left(1 + \exp\left(m_i + \sum_{j \in N(i)} m_{ij} x_j^{(t-1)}\right)\right) \exp(\text{rest})}$$

$$\left(1 + \exp\left(m_i + \sum_{j \in N(i)} m_{ij} x_j^{(t-1)}\right)\right) \exp(\text{rest})$$

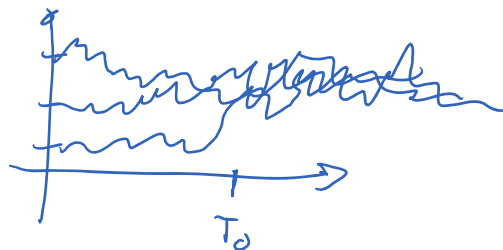
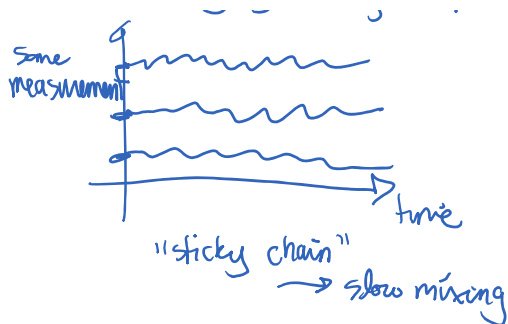
$$p(x_i = 1 | x_{-i}^{(t-1)}) = \sigma\left(m_i + \sum_{j \in N(i)} m_{ij} x_j^{(t-1)}\right)$$

diagnostic of mixing

monitor mixing by running independent chains

some measurement

from multiple chains



16/02

Variational methods

general idea: say we want to approximate θ^*

then, express it as solution to opt. problem

$$\theta^* = \underset{\theta \in \Theta}{\operatorname{argmin}} f(\theta) \quad] \text{OPT}$$

Idea: approximate θ^* via an approximation to OPT

linear algebra example:

say want sol'n to $Ax=b$ (ie. $x^* = A^{-1}b$)

$$x^* = \underset{x}{\operatorname{argmin}} \|Ax - b\|^2$$

Variational EM (motivation for objectives)

recall EM trick

latent variable $p(x, z | \theta)$
unobserved z

$$\log p(x | \theta) \geq \mathbb{E}_q \left[\log \frac{p(x, z | \theta)}{q(z)} \right] \triangleq \mathcal{L}(q, \theta)$$

$$\log p(x | \theta) - \mathcal{L}(q, \theta) = \text{KL}(q(\cdot) \| p(z|x; \theta))$$

$$\text{E step: } \underset{\substack{q \in \text{all distributions} \\ \text{on } \mathcal{Z}}}{\operatorname{argmax}} \mathcal{L}(q, \theta^{(t)}) \Leftrightarrow \underset{q}{\operatorname{argmin}} \text{KL}(q(\cdot) \| p(\cdot | x, \theta^{(t)}))$$

⊗ a variational approx. for E step:

$$\text{do } q_{\text{approx}}^{(t+1)} = \underset{\substack{q \in \mathcal{Q}_{\text{simple}} \\ \text{source of approx}}}{\operatorname{argmax}} \text{KL}(q \| p(\cdot | x, \theta^{(t)}))$$

to approximate $p(z|x, \theta^{(t)})$

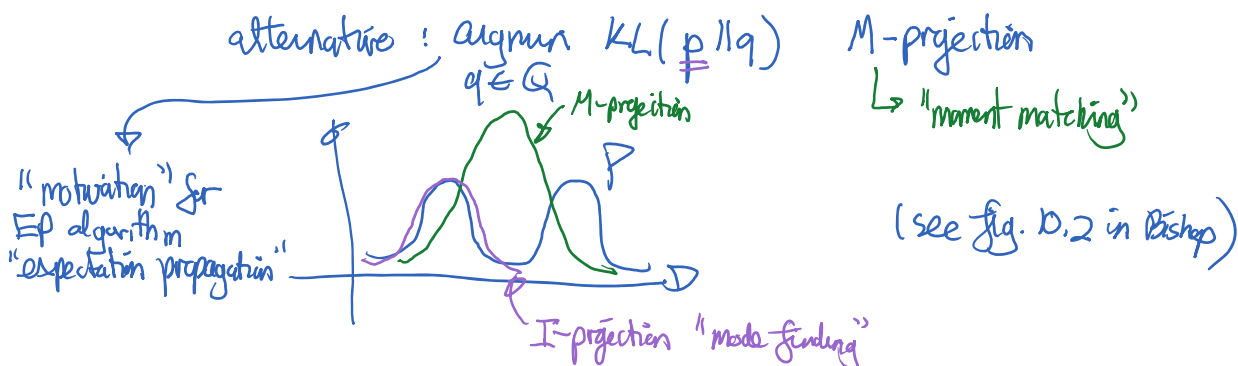
..

approximate M step: $\theta^{(t+1)} = \underset{\theta \in \Theta}{\operatorname{argmax}} \underbrace{\mathbb{E}_{q^{(t+1)}_{\text{approx}}} [\log p(\mathbf{z}|\theta)]}_{J(q^{(t+1)}_{\text{approx}}, \theta)}$

still a lower bound on $\log p(\mathbf{z}|\theta)$
 but lose monotonicity guarantee
 on $\log p(\mathbf{z}|\theta^{(t)})$ as fct. of t

more generally, using $\underset{q \in Q}{\operatorname{argmin}} KL(q||p)$ is a variational approach to approximate p

note: I-projection; if q is simple, $\mathbb{E}_q[\log p/q]$
 can compute



Mean-field approximation (section 10.1 in Bishop)

let's suppose that $p(\mathbf{z})$ is in exp family

$$\mathbf{z}_1, \dots, \mathbf{z}_d \quad p(\mathbf{z}) = \exp(\boldsymbol{\eta}^T T(\mathbf{z}) - A(\boldsymbol{\eta}))$$

mean field approximation $Q_{MF} = \{q(\mathbf{z}) = \prod_i q_i(\mathbf{z}_i)\}$
 set of fully factorized dist.

$$KL(q||p) = \mathbb{E}_q[\log \frac{q}{p}]$$

$$= -\boldsymbol{\eta}^T \mathbb{E}_q[T(\mathbf{z})] + A(\boldsymbol{\eta}) + \sum_{\mathbf{z}} q(\mathbf{z}) \log q(\mathbf{z})$$

$$\sum_i \sum_{\mathbf{z}} q_{-i}(\mathbf{z}_{-i}) q_i(\mathbf{z}_i) \log q_i(\mathbf{z}_i) = \sum_i \sum_{\mathbf{z}_i} q_i(\mathbf{z}_i) \log q_i(\mathbf{z}_i)$$

coordinate descent on q_i 's

$$\begin{aligned} \text{fix } q_j \text{ for } j \neq i; \min_{\text{w.r. to } q_i} \quad & \text{KL}(q_i \cdot q_{-i} \parallel p) \\ & = -\mathbb{E}_{q_i} \left[\underbrace{\eta^T \mathbb{E}_{q_{-i}} [T(z)]}_{\triangleq f_i(z_i)} \right] + \text{const.} + \sum_{z_i} q_i(z_i) \log q_i(z_i) \end{aligned}$$

(like MaxENT) add Lagrange multiplier for $\sum_{z_i} q_i(z_i) = 1 \rightarrow \lambda (1 - \sum_{z_i} q_i(z_i))$

$$\begin{aligned} \partial_{q_i(z_i)} = 0 & \Rightarrow -f_i(z_i) + \log q_i(z_i) + 1 - \lambda = 0 \\ & \Rightarrow q_i^*(z_i) \propto \exp(f_i(z_i)) \end{aligned}$$

⊗ general mean-field update when target p is in exp family

$$q_i^{(t+1)}(z_i) \propto \exp(\eta^T \mathbb{E}_{q_{-i}^{(t)}} [T(z)])$$

Ising model:

$$\begin{aligned} T(z) & \Rightarrow (z_i)_{i \in V} \quad z_i \in \{0, 1\} \\ & (z_i z_j)_{\{i, j\} \in E} \end{aligned}$$

$$\mathbb{E}_{q_{-i}^{(t)}}(z_j) = q_j^{(t)}(z_j=1) \triangleq \mu_j^{(t)}$$

$$\mathbb{E}_{q_{-i}^{(t)}}(z_i z_j) = z_i \mu_j^{(t)}$$

$$\eta^T \mathbb{E}_{q_{-i}^{(t)}} [T(z)] = \eta_i z_i + \sum_{j \in N(i)} \underbrace{\eta_j \mathbb{E}_{q_{-i}^{(t)}} [z_j]}_{\mu_j^{(t)}} + \sum_{j \in N(i)} \underbrace{\eta_j \mu_j^{(t)}}_{z_i \mu_j^{(t)}} + \text{rest (no } z_i)$$

$$\text{result: } q_i^{(t+1)}(z_i) \propto \exp(\eta_i z_i + z_i \sum_{j \in N(i)} \mu_j^{(t)})$$

$$\mu_i^{(t+1)} = \sigma\left(\eta_i + \sum_{j \in N(i)} \eta_j \mu_j^{(t)}\right)$$

parameter for $q_j^{(t)}$
MF update for $q_i(z_i)$
[with parameter] μ_i

Compare with G-S. update where $z_i^{(t+1)} = 1$ with prob. $\sigma(\eta_i + \sum_{j \in N(i)} \eta_j z_j^{(t)})$