

today: • Fisher LDA
• math. tricks & MLE for Gaussian

generative model for classification: (Fisher) linear discriminant analysis

FLD (instead of LDA)

for classification $y \in \{0, 1\}$

$$x \in \mathbb{R}^d$$

generative approach $p(x, y; \theta) = \overbrace{p(x|y; \theta)}^{\text{class conditional}} p(y; \theta)$

vs.

conditional approach $p(y|x; \theta)$

shaded across classes

⊛ For Fisher model: we assume $p(x|y; \theta) = N(x|\mu_y, \Sigma)$

$$\theta = (\underbrace{\mu_0, \mu_1}_{\text{mean of class 0}}, \underbrace{\Sigma}_{\text{shared}}, \underbrace{\pi}_{p(y=1)})$$

as before (see exponential family argument)

can show that $p(y|x; \theta) = \sigma(w^T x)$ where w is a fct. of $(\mu_0, \mu_1, \Sigma, \pi)$

[note: if use use $\Sigma_0 \neq \Sigma_1$, get "quadratic discriminant analysis"]

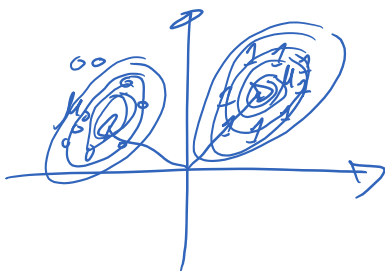
i.e. $\sigma(w^T q(x))$ where $q(x)$ is a quadratic fct. of x [see hwk 2]

(QDA)

⊛ gen. approach: do joint MLE to estimate

$$\hat{\theta} = \underset{\theta \in \Theta}{\operatorname{argmax}} \sum_i \log p(x_i, y_i; \theta)$$

[vs. $\underset{w}{\operatorname{argmax}} \sum_i \log p(y_i|x_i; w)$ for logistic regression]



sidenote: MLE for multivariate Gaussian

$$x_i \sim N(\mu, \Sigma)$$

$$\mu \in \mathbb{R}^d$$

$$\Sigma \in \mathbb{R}^{d \times d}$$

$$\hat{\Sigma} \stackrel{\Delta}{=} \frac{1}{n} \sum_{i=1}^n (x_i - \mu)(x_i - \mu)^T$$

$$\hat{\Sigma} \stackrel{T}{=} \frac{1}{n} \sum_{i=1}^n (x_i - \mu)^T (x_i - \mu) = \hat{\Sigma}^T$$

$$\mu \in \mathbb{R}^d$$

$$\Sigma \in \mathbb{R}^{d \times d}$$

Σ is symmetric
 $\Sigma \succ 0$

$$\Sigma^T = \Sigma$$

"

$$= \Sigma$$

$$V^T \Sigma V = \mathbb{E} [V^T (x - \mu)(x - \mu)^T V]$$

$$(x - \mu)^T V)^2 \geq 0$$

$$p(x) = \frac{1}{\sqrt{(2\pi)^d |\Sigma|}} \exp\left(-\frac{1}{2} (x - \mu)^T \Sigma^{-1} (x - \mu)\right)$$

$$\text{tr}(AB) = \text{tr}(BA)$$

$$\Theta = (\mu, \Sigma)$$

$$\begin{aligned} & \text{tr}((x - \mu)^T \Sigma^{-1} (x - \mu)) \\ &= \text{tr}(\Sigma^{-1} (x - \mu)(x - \mu)^T) = \langle \Sigma^{-1}, (x - \mu)(x - \mu)^T \rangle \end{aligned}$$

$$\langle A, B \rangle \triangleq \sum_{i,j} A_{ij} B_{ij} = \text{tr}(A^T B)$$

$$\begin{aligned} \text{log-likelihood: } \sum_{i=1}^n \log p(x_i; \Theta) &= \text{const.} - \frac{n}{2} \log |\Sigma| - \frac{1}{2} n \langle \Sigma^{-1}, \underbrace{\frac{1}{n} \sum_{i=1}^n (x_i - \mu)(x_i - \mu)^T}_{\triangleq \tilde{\Sigma}(\mu)} \rangle \\ &\quad + \frac{n}{2} \log |\Sigma^{-1}| \end{aligned}$$

$$|\Sigma^{-1}| = \frac{1}{|\Sigma|}$$

vector derivative review:

$o(\| \Delta \|)$ "little o "
means that $\frac{o(\| \Delta \|)}{\| \Delta \|} \rightarrow 0$ as $\| \Delta \| \rightarrow 0$

suppose $f: \mathbb{R}^m \rightarrow \mathbb{R}^n$

f is differentiable at x_0 iff $\exists$ a linear operator $df_{x_0}: \mathbb{R}^m \rightarrow \mathbb{R}^n$
s.t. $\forall \Delta \in \mathbb{R}^m$ $f(x_0 + \Delta) - f(x_0) = df_{x_0}(\Delta) + o(\| \Delta \|)$

"derivative"

$$\lim_{\| \Delta \| \rightarrow 0} \frac{f(x_0 + \Delta) - f(x_0)}{\| \Delta \|} = \lim_{\| \Delta \| \rightarrow 0} \left(\underbrace{df_{x_0}(\Delta)}_{\| \Delta \|} + \underbrace{o(\| \Delta \|)}_{\| \Delta \|} \right)$$

$$df_{x_0} \left(\frac{\Delta}{\| \Delta \|} \right)$$

$\rightarrow$ directional derivative
of f at x_0 in direction $\vec{d}$

• if $n=1$

$$df_{x_0}(\vec{d}) = \langle \nabla f(x_0), \vec{d} \rangle$$

$$\nabla f(x_0) = (df_{x_0})^T$$

chain rule:

$$f: \mathbb{R}^m \rightarrow \mathbb{R}^n$$

$$d(f \circ g) = df \circ dg$$

$$f: \mathbb{R}^m \rightarrow \mathbb{R}$$

df_{x_0} is a row vector $(1 \times m)$

$$df_{x_0} = \nabla f(x_0)^T$$

"differential"

df_{x_0} is linear

$$\text{means } df_{x_0}(a_1 + b a_2) = df_{x_0}(a_1) + b df_{x_0}(a_2)$$

can represent as a $n \times m$ matrix
called the Jacobian matrix

$$\text{standard representation } (df_{x_0})_{i,j} = \frac{\partial f_i}{\partial x_j}$$

$$\text{then } df_{x_0}(\Delta) = df_{x_0} \cdot \Delta$$

1) this gives a way to get df_{x_0} for
"anything" (matrix, tensor, so-dim fct,
etc.)

2) be careful with dimensions

chain rule:

$$f: \mathbb{R}^m \rightarrow \mathbb{R}^n$$

$$g: \mathbb{R}^n \rightarrow \mathbb{R}^q$$

$$d(g \circ f)_{x_0} = dg_{f(x_0)} \circ df_{x_0}$$

$$g(f(x_0))$$

$$= \begin{pmatrix} & \end{pmatrix} \begin{pmatrix} & \end{pmatrix}$$

matrix product of Jacobians

df_{x_0} is a "row vector" $(1 \times m)$

$$df_{x_0} = (Df(x_0))^T$$

e.g.

$$f(\mu) = x - \mu$$

$$g(w) = w^T A w$$

$$df_{\mu_0} = -I$$

$$dg_{w_0} = w_0^T (A + A^T)$$

$$g \circ f(\mu) = (x - \mu)^T A (x - \mu)$$

$$d(g \circ f)_{\mu_0} = dg_{f(\mu_0)} \circ df_{\mu_0}$$

$$= (x - \mu_0)^T (A + A^T) (-I)$$

for Gaussian: $-\frac{1}{2} \sum_i (x_i - \mu)^T \Sigma^{-1} (x_i - \mu)$

$$\nabla_{\mu}:$$

$$(d(g \circ f)_{\mu})^T$$

$$+\frac{1}{2} \sum_i 2 \Sigma^{-1} (x_i - \mu) = 0$$

$$\Rightarrow \hat{\mu}_{MLE} = \frac{1}{n} \sum_i x_i$$

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example 2: derivative of $f(A) \triangleq \log \det(A)$ where assume A is symmetric $A > 0$

can represent the derivative of a fct. from matrix to scalar, as a matrix

$$f(A + \Delta) - f(A) = \text{tr}(f'(A)^T \Delta) + o(\|\Delta\|)$$

$$= \langle f'(A), \Delta \rangle + o(\|\Delta\|)$$

$A > 0 \Rightarrow$ invertible & has unique square root $A^{1/2}$

$$\log \det(A + \Delta) - \log \det(A)$$

$$= \log \det(A^{1/2} (I + A^{-1/2} \Delta A^{-1/2}) A^{1/2}) - \log \det(A)$$

$$= \log |A|^{1/2} |I + A^{-1/2} \Delta A^{-1/2}| |A|^{1/2} - \log |A|$$

$$= \log |I + A^{-1/2} \Delta A^{-1/2}|$$

$$= \sum_i \log \lambda_i(I + A^{-1/2} \Delta A^{-1/2})$$

$$= \sum_i \log(1 + \lambda_i(A^{-1/2} \Delta A^{-1/2}))$$

$$= \sum_i [\lambda_i(A^{-1/2} \Delta A^{-1/2}) + o(\lambda_i(A^{-1/2} \Delta A^{-1/2})^2)]$$

$$= \|\Delta\|^2 \lambda_i(A^{-1/2} \Delta A^{-1/2})^2$$

$$\rightarrow o(\|\Delta\|^2) = o(\|\Delta\|)$$

$$= \text{tr}(A^{-1/2} \Delta A^{-1/2}) + o(\|\Delta\|)$$

e-value of B

$$\text{use } \det(B) = \prod_i \lambda_i(B)$$

$$Bv = \lambda v$$

$$\lambda(I + B) = 1 + \lambda(B) \quad (I + B)v = (1 + \lambda)v$$

λ is homogeneous fct.

$$\text{i.e. } Bv = \lambda v$$

$$\left(\frac{B}{b}\right)v = \left(\frac{\lambda}{b}\right)v$$

$$\frac{\|B\|^2}{\|B\|} = \|B\| \rightarrow 0$$

as $\|B\| \rightarrow 0$

$$= \text{tr}(A^{-1/2} \Delta A^{-1/2}) + o(\|\Delta\|)$$

$$= \text{tr}(A^{-1} \Delta) + o(\|\Delta\|)$$

$\langle A^{-1}, \Delta \rangle$

(recall A is symmetric)

$$\Rightarrow \frac{d}{dA} \log \det(A) = A^{-1}$$

see Boyd's book A.4.1 for the above proof

back to log-likelihood of Gaussian:

$$+ \frac{n}{2} \log |\Sigma^{-1}| - \frac{n}{2} \langle \Sigma^{-1}, \tilde{\Sigma}(\mu) \rangle \quad (\text{concave fct. of } -\Lambda = \Sigma^{-1})$$

take derivative w.r.to

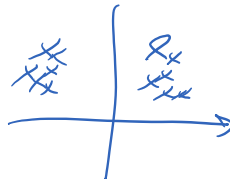
$$\Sigma^{-1} = \Lambda \quad \frac{n}{2} \underbrace{(\Sigma^{-1})^{-1}}_{\tilde{\Sigma}} - \frac{n}{2} \tilde{\Sigma}(\mu) \stackrel{\text{want}}{=} 0$$

$$\Rightarrow \hat{\Sigma}_{MLE} = \tilde{\Sigma}(\mu_{MLE}) = \frac{1}{n} \sum_{i=1}^n (x_i - \mu_{MLE})(x_i - \mu_{MLE})^T$$

(the empirical covariance matrix)

unsupervised learning

here X without any label Y



consider the Gaussian mixture model (GMM)
(can be obtained from FLD)

$$Y \sim \text{mult}(\pi) \quad \pi \in \Delta_K$$

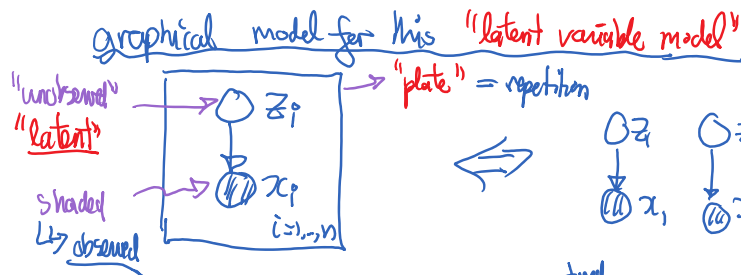
[extension of FLD to multiple classes]

$$X|Y=j \sim N(\mu_j, \Sigma)$$

$$p(x) = \sum_y p(x, y) = \sum_y p(x|y)p(y) = \sum_{j=1}^K \pi_j N(x|\mu_j, \Sigma)$$

"GMM model"

(more generally, can have ℓ_j per class)



two views on $p(x)$

unstructured plate

cl. i.



GMM model:

- $Z_i \sim \text{Mult}(\pi)$
- $x_i | Z_i \sim N(x_i | \mu_{Z_i}, \Sigma)$

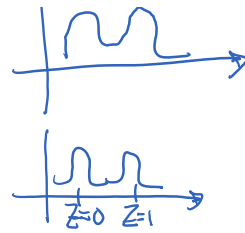
mixture distribution $p(x)$

two ways on $p(x)$

structured

latent variable model

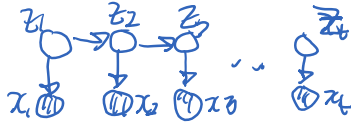
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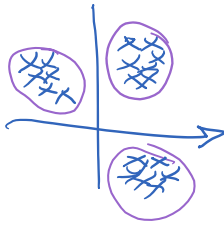
mixture distribution $p_\theta(x)$

$$p(x) = \sum_z p_\theta(x|z) p_\theta(z)$$

(later in class, we will add time structures)



K-means → to do clustering i.e. group data



we want to get a cluster assignment for every data pt. z :

represent $z_{i,j} = 1$ to mean ^{that} z_i belongs to cluster j

$j = 1, \dots, k$ # of clusters (specified in advance for K-means)

applications: • vector quantization (compression)

• in computer vision: use K-means to get "bag of visual words" representation of image patches

• many many others ▽