

today: sampling - approximate inference

Approximate inference - sampling

motivation: NP hard to do exact inference in Ising model $\rightarrow$ need approximation

why sampling? $X = (x_1, \dots, x_p)$

a) simulation $X^{(i)} \sim p$

b) approximate marginal $p(x_i)$

$\rightarrow$ special case of expectations

consider $f: \mathbb{R}^p \rightarrow \mathbb{R}$

we want approximate $\mu = \mathbb{E}_p[f(x)]$

special case: if $f(x) \triangleq \mathbb{1}\{x_A = x_A\}$ $\mathbb{E}_p[f(x)] = p(x_A = x_A)$

Monte Carlo integration / estimation $\rightarrow$ appears in physics, applied math., ML, statistics

to approximate $\mu = \mathbb{E}_p[f(x)]$

MC estimation alg.: $\dots n$ samples $X^{(i)} \stackrel{\text{iid.}}{\sim} p$

estimate $\hat{\mu} = \frac{1}{n} \sum_{i=1}^n f(X^{(i)}) = \mathbb{E}_{\hat{p}_n}[f(x)]$

$\hookrightarrow$ emp. dist.

$\hat{p}_n(x) \triangleq \frac{1}{n} \sum_{i=1}^n \mathbb{1}\{x^{(i)} = x\}$

properties:

1) unbiased estimator $\mathbb{E}[\hat{\mu}] = \frac{1}{n} \sum_{i=1}^n \underbrace{\mathbb{E}[f(X^{(i)})]}_{\substack{\text{expectation} \\ \text{over } (X^{(i)})_{i=1}^n}} = \frac{1}{n} \mu = \mu$

$\hookrightarrow$ this is still true even if $X^{(i)}$'s are dependent

2) expected error (l2-error) $\mathbb{E}[\|\mu - \hat{\mu}\|_2^2] = \mathbb{E}\left[\left\langle \frac{1}{n} \sum_{i=1}^n f(X^{(i)}) - \mu, \frac{1}{n} \sum_{j=1}^n f(X^{(j)}) - \mu \right\rangle\right]$
 $\text{tr}(\text{cov}(\hat{\mu}, \hat{\mu})) = \mathbb{E}\left[\frac{1}{n^2} \sum_{i,j=1}^n \langle f(X^{(i)}) - \mu, f(X^{(j)}) - \mu \rangle\right]$

by independence $\Rightarrow$ off-diagonal terms are zero

$$\text{i.e. } \mathbb{E} \left(\langle f(x^{(i)}) - \mu, f(x^{(j)}) - \mu \rangle \right)$$

$$\langle \mathbb{E} \left(\frac{f(x^{(i)})}{n} \right) - \mu, \mathbb{E} \left(\frac{f(x^{(j)})}{n} \right) - \mu \rangle$$

$$= \frac{1}{n^2} \sum_{i,j} \mathbb{E} \left[\langle f(x^{(i)}) - \mu, f(x^{(j)}) - \mu \rangle \right] = \frac{n \sigma^2}{n^2}$$

$$\mathbb{E} [\|f(x^{(i)}) - \mu\|^2] \triangleq \sigma^2$$

$$\text{tr}(\text{cov}(f(x), f(x)))$$

$$= \frac{\sigma^2}{n}$$

$$\mathbb{E} [\|\hat{\mu} - \mu\|^2] = \frac{\sigma^2}{n}$$

note: there is no explicit dimension in rate

(apart σ^2 which could depend implicitly)

$$\text{eg } f(x) = x$$

$$x_j \sim \mathcal{N}(0, \tilde{\sigma}^2)$$

$$\mathbb{E} [\|f(x) - \mu\|^2] = p \tilde{\sigma}^2$$

How to sample?

1) $X \sim \text{Unif}([0,1]) \rightarrow$ pseudo-random generator "rand"

2) $X \sim \text{Bernoulli}(p) \quad X = \mathbb{1}\{U \leq p\}$ where $U \sim \text{unif}([0,1])$

3) inverse transform sampling trick

let F be target c.d.f. of dist. p for X

$$F(x) \triangleq \mathbb{P}\{X \leq x\}$$

(first, suppose F is invertible)

$$\text{let } X = F^{-1}(U) \text{ with } U \sim \text{Unif}([0,1])$$

claim that X has cdf $F(x)$

F is invertible (and monotone)

$$\text{proof: } \mathbb{P}\{X \leq y\} = \mathbb{P}\{F^{-1}(U) \leq y\} \stackrel{\downarrow}{=} \mathbb{P}\{U \leq F(y)\} = F(y)$$

[if F is not invertible, define

$$X \triangleq \min \{x : F(x) \geq U\}$$

(recall that F is cdf from right)

n.s.m.b.

F is cdf from right

example:

want $X \sim \text{Exp}(\lambda)$

density $p(x) = \lambda \exp(-\lambda x) \mathbb{1}_{\mathbb{R}^+}(x)$

$$F(x) = 1 - \exp(-\lambda x)$$

$$\text{inverse } F^{-1}(u) = -\frac{1}{\lambda} \log(1-u)$$

Multivariate distribution?

can generalize above trick using "chain rule"

$X_{1:p}$ (dim p)

$$\text{from } p(x_{1:p}) = \prod_{i=1}^p p(x_i | x_{1:i-1})$$

use cdf for this conditional

$$F_{X_i | X_{1:i-1}}(x_i | x_{1:i-1}) \triangleq \mathbb{P}\{X_i \leq x_i | X_{1:i-1} = x_{1:i-1}\} \\ \triangleq \int_{-\infty}^{x_i} p(x | x_{1:i-1}) dx$$

"conditional density same" for $X_{1:i-1} = x_{1:i-1}$

could use $U_1, \dots, U_p$ i.i.d. $\text{Unif}([0,1])$

$$X_1 = F_{X_1}^{-1}(U_1)$$

$$X_2 = F_{X_2 | X_1}^{-1}(U_2 | X_1)$$

$\vdots$

$$X_p = F_{X_p | X_{1:p-1}}^{-1}(U_p | X_{1:p-1})$$

inverse of $F_{X_i | X_1}(\cdot | X_1)$

is a very complicated function

(curse of dimensionality)

[aside: "copulas" $\rightarrow$ model for multivariate data with uniform marginals]

exception is multivariate Gaussian

$$N(\mu, \Sigma) \quad \Sigma = U \Lambda U^T$$

(where $U U^T = I_p$
 Λ is diagonal)

(Cholesky decomposition)
 $\Sigma = L L^T$

generate $V \sim N(0, I_p)$

(V_p i.i.d. $N(0,1)$)

$$X = U \underbrace{\Lambda^{1/2}}_L V + \mu$$

$$\mathbb{E}X = \mu$$

$$\text{cov}(X) = U \Omega^{1/2} \overset{I_P}{\sim} \text{cov}(U) \Omega^{1/2} U^T = \Sigma$$

Box-Muller transformation to sample (2d) Gaussian

$$\begin{aligned} R^2 &\sim \text{Exp}(1) \\ \Theta &\sim \text{unif}([0, 2\pi]) \end{aligned} \Rightarrow \begin{aligned} X &\triangleq R \cos \Theta \\ Y &\triangleq R \sin \Theta \end{aligned} \quad \begin{pmatrix} X \\ Y \end{pmatrix} \sim N(0, I)$$

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sampling from a DGM is (relatively) easy & ancestral sampling

$(X_1, \dots, X_d) \sim p \in \mathcal{P}(G)$ where G is a DAG

$$p(x_1, \dots, x_d) = \prod_{i=1}^d p(x_i | x_{\pi_i})$$

suppose wlog $1, \dots, d$ is a tp. sort of G

ancestral sampling:

for $i=1, \dots, d$

sample $X_i \sim p(X_i = \cdot | X_{\pi_i})$

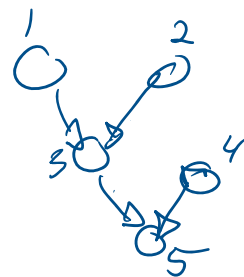
end

can show by induction $(X_1, \dots, X_d)$ has dist. p

⊗ important side note! when you sample from joint

you are also sampling from "marginals" by just ignoring joint aspect

i.e. $(X, Y) \sim p(x, y)$ then look at X by itself
 $X \sim p(x)$



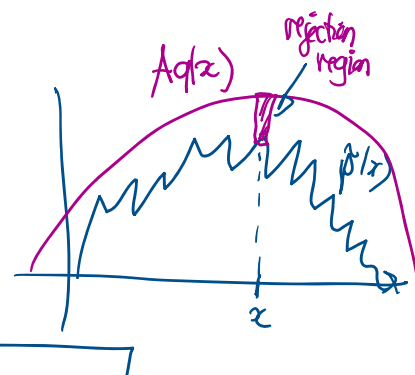
rejection sampling:

$$\text{say } p(x) = \frac{\tilde{p}(x)}{Z_p}$$

$$Z_p \triangleq \int_x \tilde{p}(x) dx$$

let's say can form a d/o "proposal" that is easy to sample from

s.t. $Aq(x) \geq \tilde{p}(x) \forall x$



rule:

- sample $X \sim q(x)$
- Accept with prob $\frac{\tilde{p}(x)}{A q(x)} \in [0,1]$
- reject $\rightarrow$ start again

Let's show that accepted samples have correct dist.

(say X is discrete)

$$\underbrace{P\{X=x, X \text{ is accepted}\}}_{\text{sampling mechanism}} = \underbrace{P\{X \text{ is accepted} | X=x\}}_{\frac{\tilde{p}(x)}{A q(x)}} \underbrace{P\{X=x\}}_{q(x)} = \frac{\tilde{p}(x)}{A}$$

$$P\{X \text{ is accepted}\} = \sum_x \frac{\tilde{p}(x)}{A} = \frac{Z_p}{A}$$

(marginal probs of acceptance
 $\rightarrow$ want this to be high)

$$P\{X=x | X \text{ is accepted}\} = \frac{\frac{\tilde{p}(x)}{A}}{Z_p/A} = \frac{\tilde{p}(x)}{Z_p} = p(x)$$

application to conditioning in a DGM

say want to sample $p(x | \bar{x}_E)$

here, could use $\tilde{p}(x) = p(x_E, x_{E^c}) \delta(x_E, \bar{x}_E) \Rightarrow p(x) = p(x_{E^c} | \bar{x}_E)$

Let $q(x)$ be original joint in DGM (sample using ancestral sampling) $\delta(x_E, \bar{x}_E)$

$$q(x) = p(x_E, x_{E^c})$$

$$q(x) \geq \tilde{p}(x) \quad \forall x \quad [\text{take } A=1]$$

$$\text{acceptance prob. } \frac{\tilde{p}(x)}{A q(x)} = \delta(x_E, \bar{x}_E)$$

alg.:

- do ancestral sampling
- accept if $x_E = \bar{x}_E$
- o.w. reject

(rejection sampling for DGM sampling)

$$P\{\text{accept}\} = \frac{Z_p}{A} = p(\bar{x}_E)$$

Importance sampling:

in context of computing $\mathbb{E}_p[f(X)] = \mu$ $X \sim p$
 $\leadsto$ can "weight" sample $X^{(i)}$

$$\mathbb{E}_p[f(X)] = \int f(x)p(x) = \int f(x) \underbrace{p(x)}_{q(x)} \cdot q(x) \quad \text{for some dist. } q$$

$$= \mathbb{E}_q \left[f(Y) \frac{p(Y)}{q(Y)} \right] \quad \text{where } Y \sim q$$

$$\approx \frac{1}{n} \sum_{i=1}^n g(Y^{(i)}) \quad \text{where } Y^{(i)} \stackrel{\text{iid}}{\sim} q$$

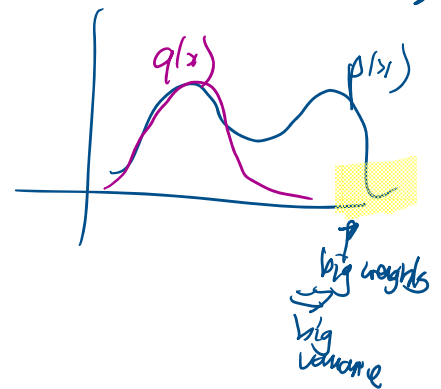
$$\text{and } g(Y) \triangleq f(Y)w(Y) \\ \text{where } w(y) \triangleq \frac{p(y)}{q(y)} \quad \text{"weights"}$$

$$\hat{\mu}_{\text{IS.}} = \frac{1}{n} \sum_{i=1}^n f(Y_i) w_i \quad Y_i \stackrel{\text{iid}}{\sim} q \\ w_i \triangleq \frac{p(Y_i)}{q(Y_i)} \\ \text{"importance weight"}$$

indeed $\text{Var}(\hat{\mu})$ can be so sometimes?

$$\mathbb{E}[\hat{\mu}_{\text{IS.}}] = \mu \\ \text{Var}[\hat{\mu}] = \frac{1}{n} \left[\mathbb{E}_p \left[f(X)^2 \frac{p(X)}{q(X)} \right] - \mu^2 \right]$$

issues when q is small and p "big"



intuitively, you want $q(x) \propto |f(x)|p(x)$

extension to unnormalized dist.

$$p(x) = \frac{\tilde{p}(x)}{Z_p} \quad q(x) = \frac{\tilde{q}(x)}{Z_q}$$

$$\mu = \mathbb{E}_q \left[f(Y) \frac{p(Y)}{q(Y)} \right]$$

$$= \mathbb{E}_q \left[f(Y) \frac{\tilde{p}(Y)}{\tilde{q}(Y)} \right] \cdot \left(\frac{Z_q}{Z_p} \right)$$

$$\text{estimate } \frac{Z_p}{Z_q} \text{ with } \frac{Z_p}{Z_q} \triangleq \frac{1}{n} \sum_{i=1}^n \frac{\tilde{p}(Y_i)}{\tilde{q}(Y_i)} \\ = \frac{1}{n} \sum_{i=1}^n w_i$$

$$\hat{\mu}_{\text{NIS}} = \frac{\frac{1}{n} \sum_{i=1}^n f(x_i) w_i}{\frac{1}{n} \sum_{i=1}^n w_i} \quad \begin{array}{l} x_i \sim q \\ w_i = \frac{p(y_i)}{q(y_i)} \end{array}$$

note: $\hat{\mu}_{\text{NIS}}$ is (slightly biased), but asymptotically unbiased $n \rightarrow \infty$

- This estimator has often lower variance than $\hat{\mu}_{\text{IS}}$ even when $Z_p = Z_q = \mathbb{I}$ (normalized "stabilizes" estimator new weights $\tilde{w}_i = \frac{w_i}{\frac{1}{n} \sum w_j} \in [0, n]$)

see 2017 notes for

- variance reduction (link with SAGA)
- Rao-Blackwellization

Good reference on sampling:

Monte Carlo Statistical Methods, Robert & Casella, 2004