

today: • Gibbs sampling
• variational methods

Gibbs sampling alg.

↳ M.H. with a clever choice of proposal $q_t(x'|x)$ [clavier: $\alpha(z'|x) = 1$]

examples of applications

UGM: $\tilde{p}(x) = \prod \psi_c(x_c)$

difficult conditional
in DGM

$$\tilde{p}^c(x) = p(x_{E^c}, \bar{x}_E) \delta(x_E, \bar{x}_E)$$

$$\text{or } p(x | \bar{x}_E)$$

(UGM)

cyclic Gibbs sampling alg: nodes $i=1, \dots, n$

start at some $x^{(0)}$

for $t=1, \dots$

• pick $i = (t \bmod n) + 1$

• sample $x_i^{(t)} \sim p(X_i = \cdot | X_{\setminus i} = x_{\setminus i}^{(t-1)})$

true conditional on x_i as a proposal

• set $x_j^{(t)} = x_j^{(t-1)}$ for $j \neq i$

end

⊛ Gibbs sampling is M.H. with a time varying proposal

suppose we pick i at time t

then the proposal is $q_t(x' | x^{(t-1)}) = p(x_i' | x_{\setminus i}^{(t-1)}) \delta(x_{\setminus i}', x_{\setminus i}^{(t-1)})$

for $x_{\setminus i}$ to stay constant

M.H. acceptance ratio: $\frac{p(x_i^{(t-1)} | x_{\setminus i}^{(t-1)}) \delta(x_{\setminus i}^{(t-1)}, x_{\setminus i}^{(t-1)})}{p(x_i^{(t)} | x_{\setminus i}^{(t-1)}) \delta(x_{\setminus i}^{(t-1)}, x_{\setminus i}^{(t-1)})}$

$$q(x' | x^{(t-1)}) = \frac{q_t(x^{(t-1)} | x') p(x')}{q_t(x' | x^{(t-1)}) p(x^{(t-1)})} = 1$$

$$q_t(x' | x^{(t-1)}) p(x^{(t-1)}) \rightarrow p(x_i^{(t-1)}) p(x_i^{(t-1)} | x_{-i}^{(t-1)})$$

$$\hookrightarrow p(x_i | x_{-i}^{(t-1)}) \delta(x_i, x_i^{(t-1)})$$

always accepts

Convergence of G.S.:

- let A be a Markov transition kernel of one full cycle of Gibbs sampling (i.e. n steps)

$\rightarrow$ homogeneous M.C.

if suppose that $\underline{p(x) > 0 \forall x}$

$$\Rightarrow p(x_i | x_{-i}) > 0 \quad \forall x_i, x_{-i}$$

$\Rightarrow A$ is irreducible & aperiodic because $A_{ii} > 0$

$$A_{kl} > 0 \quad \forall k, l$$

since can get to any state with n "steps"

$$\Rightarrow A^t \pi_0 \xrightarrow{t \rightarrow \infty} p$$

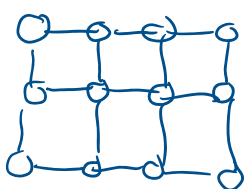
by detailed balance, p is stationary dist. of chain

(*) also works for random scan (pick $i \sim \text{unif}(1:n)$ at each step)

example: G.S. for Ising model

Ising model $x_i \in \{0, 1\}$

UGM:



$$p(x) = \frac{1}{Z(n)} \exp\left(\sum_i \eta_i x_i + \sum_{\langle i, j \rangle \in E} \eta_{ij} x_i x_j\right)$$

[minimal exp. family representation]

for G.S.

want to compute $p(x_i | x_{-i}) \stackrel{\text{by cond. indep.}}{=} p(x_i | x_{\text{neighbors}(i)})$

$$\propto \exp\left(\eta_i x_i + \sum_{j \in N(i)} \eta_{ij} x_i x_j + \text{rest}\right)$$

$\Rightarrow$ renormalize to get conditional

$$p(x_i = 1 | x_{-i}) = \frac{\exp(\eta_i + \sum_{j \in N(i)} \eta_{ij} x_j) \exp(\text{rest})}{(1 + \exp(\eta_i + \sum_{j \in N(i)} \eta_{ij} x_j)) \exp(\text{rest})}$$

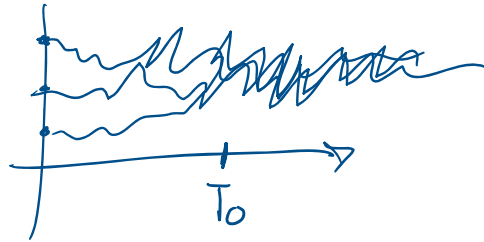
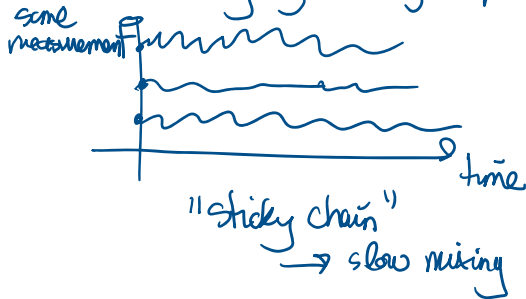
$$= \frac{\exp(\eta_i + \sum_{j \in N(i)} \eta_{ij} x_j)}{1 + \exp(\eta_i + \sum_{j \in N(i)} \eta_{ij} x_j)}$$

$$| \dots (t) \dots (t-1) \dots (t-1) \dots (t-1) |$$

$$p(x_i=1 | x_{-i}) = \sigma(\eta_i + \sum_{j \in \mathcal{N}(i)} \eta_{ij} x_j^{(t)})$$

diagnostic of mixing

monitor mixing by running independent chains



15h16

bad at 15h40

Variational methods

general idea: say we want to approximate Θ^*

then, express it as a solution to opt. problem

$$\Theta^* = \arg \min_{\Theta \in \Theta} f(\Theta) \quad \text{OPT}$$

idea: approximate Θ^* via an approximation of OPT

linear algebra example:

say want sol'n to $Ax=b$ (ie. $x^* = A^{-1}b$)

$$x^* = \arg \min_x \|Ax - b\|^2$$

Variational EM (motivation for objective)

recall EM trick

latent $p(x, z | \theta)$

$$\log p(x | \theta) \geq \mathbb{E}_q \left[\log \frac{p(x, z | \theta)}{q(z)} \right] \triangleq \mathcal{L}(q, \theta)$$

$$\log p(x|y) = \log \int p(x,z|y) dz = \log \int \frac{p(x,z|y)}{q(z)} q(z) dz = \mathbb{E}_{q(z)} [\log p(x,z|y)] - \mathbb{E}_{q(z)} [\log q(z)]$$

$$\log p(x|\theta) - \mathbb{E}_{q(z)} [\log p(x,z|\theta)] = \mathbb{E}_{q(z)} [\log p(z|x,\theta) - \log q(z)] = \mathbb{E}_{q(z)} [\log p(z|x,\theta) - \log q(z)] = \mathbb{E}_{q(z)} [\log p(z|x,\theta) - \log q(z)] = \mathbb{E}_{q(z)} [\log p(z|x,\theta) - \log q(z)]$$

$$\text{E step: } \arg\max_{q \in \text{all distributions on } z} \mathbb{E}_{q(z)} [\log p(x,z|\theta^{(t)})] \Leftrightarrow \arg\min_q \text{KL}(q(\cdot) \| p(\cdot|x,\theta^{(t)}))$$

(*) a variational approx. for E step:

$$\text{do } q_{\text{approx}}^{(t)} = \arg\min_{q \in Q_{\text{simple}}} \text{KL}(q \| p(\cdot|x,\theta^{(t)}))$$

↑ source of approx → is approximate $p(z|x,\theta^{(t)})$

approximate M step:

$$\theta^{(t+1)} = \arg\max_{\theta \in \Theta} \mathbb{E}_{q_{\text{approx}}^{(t)}} [\log p(x,z|\theta)]$$

$$\downarrow$$

$$\mathbb{E}_{q_{\text{approx}}^{(t)}} [\log p(x,z|\theta)] \approx \mathbb{E}_{q_{\text{approx}}^{(t)}} [\log p(x,z|\theta)] = \mathbb{E}_{q_{\text{approx}}^{(t)}} [\log p(x,z|\theta)] = \mathbb{E}_{q_{\text{approx}}^{(t)}} [\log p(x,z|\theta)] = \mathbb{E}_{q_{\text{approx}}^{(t)}} [\log p(x,z|\theta)]$$

still a lower bound on $\log p(x|\theta)$

but lose monotonicity guarantee on $\log p(x|\theta^{(t)})$ as fct. of t

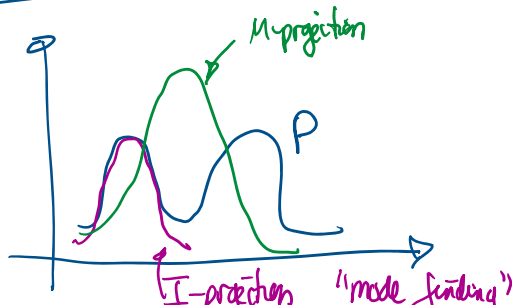
more generally, using $\arg\min_{q \in Q} \text{KL}(q \| p)$ is a variational approach to approximate p

note: I-projection; if q is simple, $\mathbb{E}_q [\log p/q]$ can compute

$$\text{alternative: } \arg\min_{q \in Q} \text{KL}(p \| q) \quad \text{M-projection}$$

↳ "moment matching"

"motivation" for EP algorithm
"expectation propagation"



(see fig. 10.2 in Bishop)

expectation propagation



(see fig. 10.2 in Bishop)

Mean-field approximation (section 10.1 in Bishop)

let's suppose that $p(z)$ is in exp. family

$$z_1, \dots, z_d \quad p(z) = \exp(n^T T(z) - A(n))$$

mean field approximation $Q_{MF} = \{q(z) = \prod_i q_i(z_i)\}$
set of fully factored dist.

$$\begin{aligned} KL(q \| p) &= \mathbb{E}_q[\log q/p] \\ &= -n^T \mathbb{E}_q[T(z)] + A(n) + \sum_z q(z) \log q(z) \\ &\quad \left(\prod_j q_j(z_j) \right) \leq \log q_j(z_j) \\ &\leq \sum_i \sum_z q_i(z_i) q_i(z_i) \log q_i(z_i) \\ &\quad \underbrace{1 \leq \sum_z q_i(z_i)}_{\sum_z q_i(z_i)} \\ &\leq \sum_i q_i(z_i) \log q_i(z_i) \end{aligned}$$

coordinate descent on q_i 's

$$\begin{aligned} \text{fix } q_j \text{ for } j \neq i; \quad \min_{\text{w.r. to } q_i} KL(q_i \cdot q_{-i} \| p) \\ = -\mathbb{E}_{q_i} \left[\underbrace{n^T \mathbb{E}_{q_{-i}}[T(z)]}_{\triangleq f_i(z_i)} \right] + \text{const.} + \sum_z q_i(z_i) \log q_i(z_i) \end{aligned}$$

$$\begin{aligned} (\text{like MaxEnt}) \quad \text{add Lagrange multiplier for } \sum_z q_i(z_i) = 1 &\rightarrow \lambda (1 - \sum_z q_i(z_i)) \\ \frac{\partial}{\partial q_i(z_i)} \Rightarrow -f_i(z_i) + \log q_i(z_i) + 1 - \lambda = 0 \\ \Rightarrow q_i^*(z_i) \propto \exp(f_i(z_i)) \end{aligned}$$

⊛ general mean field update when target p is in exp. family

$$q_i^{(t+1)}(z_i) \propto \exp(n^T \mathbb{E}_{q_{-i}^{(t)}}[T(z)])$$

Ising model

$$T(z) \Rightarrow \begin{pmatrix} z_i \\ (z_i z_j)_{z_i, z_j \in E} \end{pmatrix} \quad z_i \in \{0,1\}$$

$$\mathbb{E} q_{ji}^{(t)}(z_j) = q_j^{(t)}(z_j=1) \triangleq \mu_j^{(t)}$$

$$\mathbb{E} q_{ji}^{(t)}(z_i z_j) = z_i \mu_j^{(t)}$$

no $z_i \Rightarrow$ constant

$$n^T \mathbb{E} q_{ji}^{(t)} [T(z)] = n_i z_i + \underbrace{\sum_{j \in N(i)} n_{ij} \mathbb{E} q_{ji}^{(t)}(z_j)}_{\mu_j^{(t)}} + \sum_{j \in N(i)} n_{ij} \underbrace{\mathbb{E} q_{ji}^{(t)}(z_i z_j)}_{z_i \mu_j^{(t)}} + \text{rest}$$

no z_i

result: $q_i^{(t+1)}(z_i) \propto \exp \left(n_i z_i + z_i \sum_{j \in N(i)} n_{ij} \mu_j^{(t)} \right)$

$$\mu_i^{(t+1)} = \sigma \left(n_i + \sum_{j \in N(i)} n_{ij} \mu_j^{(t)} \right)$$

parameter for $q_j^{(t)}$

MF update for $q_i(z_i)$ with parameter μ_j

compare with GS. update

where $z_i^{(t)}=1$ with prob. $\sigma \left(n_i + \sum_{j \in N(i)} n_{ij} z_j^{(t)} \right)$