

today: inference: graph Eliminate
sum-product alg.

graph elimination alg. (for inference in generic VGM)

• consider $p \in \mathcal{P}(\mathcal{C})$ $p(x) = \frac{1}{Z} \prod_{c \in \mathcal{C}} \psi_c(x_c)$
undirected

say want to compute $p(x_F)$ for some $F \subseteq V$ "query nodes"

main trick: use distributivity of $\oplus$ over $\odot \leadsto c \odot (a \oplus b) = c \odot a \oplus c \odot b$

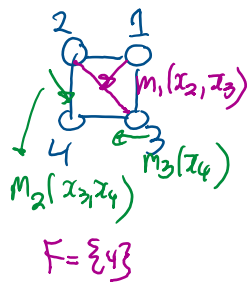
$$\sum_{x_1, x_2} f(x_1) g(x_2) = \left(\sum_{x_1} f(x_1) \right) \left(\sum_{x_2} g(x_2) \right)$$

[convince yourself]

more generally $\sum_{x_1:n} \prod_i f_i(x_i) = \prod_{i=1}^n \left(\sum_{x_i} f_i(x_i) \right)$

$$O(k^n) \rightarrow O(k \cdot n)$$

x_i takes k values



$$p(x_4) = \frac{1}{Z} \sum_{x_1, x_2, x_3} \psi(x_1, x_2) \psi(x_2, x_4) \psi(x_1, x_3) \psi(x_3, x_4)$$

$$= \frac{1}{Z} \left[\sum_{x_3} \psi(x_3, x_4) \left[\sum_{x_2} \psi(x_2, x_4) \left(\sum_{x_1} \psi(x_1, x_2) \psi(x_1, x_3) \right) \right] \right]$$

$m_1(x_2, x_3)$ ← "message"

$m_2(x_3, x_4)$

$$= \frac{1}{Z} m_3(x_4) \quad \text{last message is proportional to marginal } p(x_4)$$

$$\sum_{x_4} m_3(x_4) = Z \quad \left[p(x_4) = \frac{m_3(x_4)}{Z} \right] = \frac{m_3(x_4)}{\sum_{x_4} m_3(x_4)}$$

general alg: graph Eliminate

init: a) choose an elimination ordering st. F are the last nodes

b) put all $\psi_c(x_c)$ on "active list"

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"update" c) repeat, in order of variables to eliminate

1) (say x_i is variable to eliminate)

remove all factors from active list with x_i in it } take their product

$$\text{i.e. } \prod_{\substack{\alpha \in \text{active list} \\ i \in \alpha}} \psi_{\alpha}(x_{\alpha})$$

2) sum over x_i to get a new factor $m_i(x_{S_i})$ (think as $\psi_{S_i}(x_{S_i})$)

i.e. S_i are all variables in these factors except i

$$\text{get } m_i(x_{S_i}) \triangleq \sum_{x_i} \prod_{\substack{\alpha \in \text{active list} \\ i \in \alpha}} \psi_{\alpha}(x_{\alpha})$$

$$S_i \triangleq \left(\bigcup_{\substack{\alpha \in \text{active list} \\ i \in \alpha}} \alpha \right) \setminus \{i\} \quad \text{new clique to sum over } S_i \cup \{i\}$$

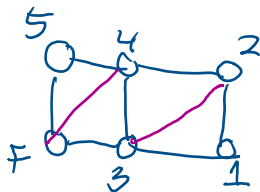
3) put back $m_i(x_{S_i})$ in active list ($\psi_{S_i}(x_{S_i})$)

"normalize": d) last product of factors has only $x_F \Rightarrow$ proportional $p(x_F)$

suppose $x_i \in \{0,1\}$ memory needed? $\approx 2^{\max_i |S_i|}$ (max size of active list $\leq |E|$)

computational = $\left(2^{(\max_i |S_i|) + 1} \right) n$
data, related "tree width" of a graph

⊛ "augmented graph" $\rightarrow$ graph obtained by running graph elimination + keeping track of all edges added (for specific ordering)

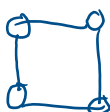


⊛ note augmented graph obtained after graph elimination is always

a triangulated graph

def.: graph with no cycle of size 4 or more that cannot be broken by a "chord"

↑
an edge between two non-neighboring nodes in a cycle



$\leftarrow$ not triangulated



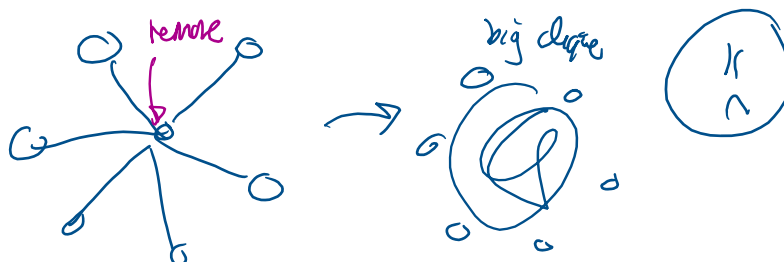
$\leftarrow$ Δ -graph



treewidth of a graph $\triangleq$ min over all possible elimination orderings $\{ \text{size of biggest } -1 \}$
 degree in augmented graph $\rightarrow$ $\text{caterpillar tree width (tree)} = 1$

both memory & running time of graph Elimination is dominated by $\sum \text{size of biggest degree}$
 $\sum \text{treewidth} + 1$
 when using best ordering

not all orderings are good



bad news:

a) NP hard to compute treewidth of a general graph (or find best ordering)

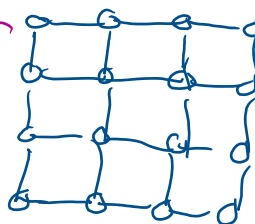
b) NP hard to do (exact) inference in general UGM
 $\Rightarrow$ need approximate methods

example:

treewidth of a grid

$$\approx \sqrt{|V|}$$

side length
 treewidth

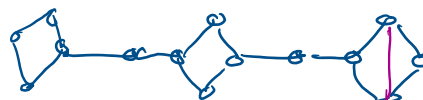


5h26 good news:

* inference is linear time for tree (treewidth 1) ("sum-product dg.")
 $\hookrightarrow |V| + |E|$ (HMM, Markov chains)

* efficient for "small treewidth" graph

$\rightarrow$ use junction tree dg.



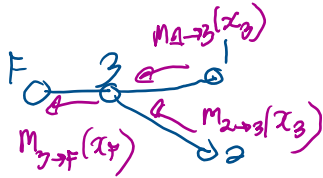
inference on trees

reach Eliminate on a tree

inference on trees

graph Eliminate on a tree

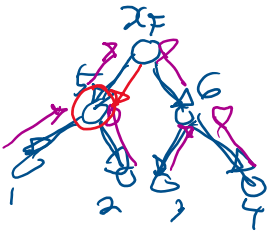
→ good order is to eliminate leaves first



$$p(x) = \frac{1}{Z} \prod_i \psi_i(x_i) \prod_{i,j \in E} \psi_{ij}(x_i, x_j)$$

(assuming F is singleton)

Order: make a directed tree by using x_F as a root

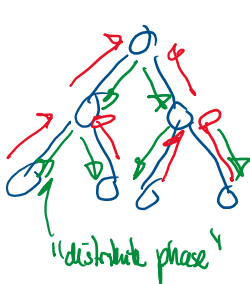


$$m_{i \rightarrow j}(x_j) = \sum_{x_i} \psi_i(x_i) \psi_{ij}(x_i, x_j) \prod_{k \in \text{children}(i)} m_{k \rightarrow i}(x_i)$$

new factors containing i in the active list

Sum-product alg. (for trees)

alg. to get all node/edge marginals cheaply by forward (caching) & re-using messages (dynamic programming)



"collect phase"

goal: $\forall i, j \in E$, compute $m_{i \rightarrow j}(x_j)$

$m_{j \rightarrow i}(x_i)$

rule: i can only send messages to neighbor j

when it has received all messages from other neighbors



$$m_{i \rightarrow j}(x_j) \triangleq \sum_{x_i} \psi_i(x_i) \psi_{ij}(x_i, x_j) \prod_{k \in N(i) \setminus \{j\}} m_{k \rightarrow i}(x_i)$$

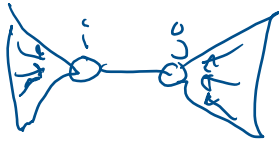
at end

(node marginal) $p(x_i) \propto \psi_i(x_i) \prod_{j \in N(i)} m_{j \rightarrow i}(x_i)$

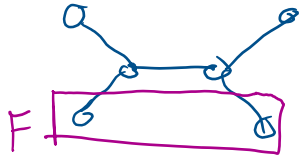
normalise $Z = \sum_{x_i} (\quad)$

(edge marginal)

(edge marginal)



$$p(x_i, x_j) = \frac{1}{Z} \psi_i(x_i) \psi_j(x_j) \psi_{ij}(x_i, x_j) \cdot \prod_{k \in N(i) \setminus \{j\}} m_{k \rightarrow i}(x_i) \cdot \prod_{k' \in N(j) \setminus \{i\}} m_{k' \rightarrow j}(x_j)$$



for this marginal need to use graph elimination

sum-product schedules

a) above, collect/distribute schedule

b) (flooding) parallel schedule

1) initialize all $m_{i \rightarrow j}(x_j)$ to uniform dist. $\forall (i, j)$ s.t. $\{i, j\} \in E$

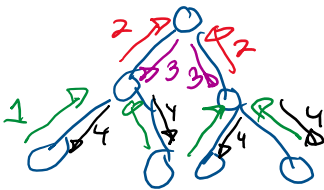
2) at every step (in parallel) compute $m_{i \rightarrow j}^{(new)}(x_j) \leftarrow \prod_{k \in N(i) \setminus \{j\}} m_{k \rightarrow i}(x_i)$

as if the neighbors were correctly computed

→ one can prove that after "diameter of tree" # of steps

all messages are correctly computed (for a tree)

(and are fixed to a fixed point)



loopy belief propagation (loopy BP) : approximate inference for graphs with cycles

$$m_{i \rightarrow j}^{new}(x_j) = \left(m_{i \rightarrow j}^{old}(x_j) \right)^{1-\alpha} \left(\sum_{x_i} \psi_i(x_i) \psi_{ij}(x_i, x_j) \prod_{k \in N(i) \setminus \{j\}} m_{k \rightarrow i}^{old}(x_i) \right)^{\alpha}$$

$\alpha \in [0, 1]$
↑ step-size

"damping"

⊗ this gives exact answer on trees
(fixed pt. → yields correct marginals)

✗ on (not too loopy) graph → "nice" approximate solution



