

today: - Gibbs sampling
- variational methods

Gibbs sampling alg.

↳ M.H. with a clever choice of proposal $q_t(x'|x)$ [clever: $q(x'|x) = 1$]

examples of applications

$$\begin{aligned} & \text{UGM} \quad \tilde{p}(x) = \prod \psi_c(x_c) \\ & \text{difficult conditional in UGM} \quad p(x) = p(x_E^c, \bar{x}_E) \delta(x_E, \bar{x}_E) \propto p(x|\bar{x}_E) \end{aligned}$$

(UGM)

cyclic Gibbs sampling alg.: nodes $i=1, \dots, n$
start at some $x^{(0)}$

for $t=1, \dots$

- pick $\bar{i} = (t \bmod n) + 1$
- sample $x_i^{(t)} \sim p(X_i = \cdot \mid X_{\bar{i}} = x_{\bar{i}}^{(t-1)})$
true conditional on x_i as a proposal
- set $x_j^{(t)} = x_j^{(t-1)}$ for $j \neq i$

end

⊛ Gibbs sampling is M.H. with a time varying proposal

suppose we pick i at time t

then proposal is $q_t(x'|x^{(t-1)}) = p(x_i' | x_{\bar{i}}^{(t-1)}) \delta(x_{\bar{i}}, x_{\bar{i}}^{(t-1)})$
for $x_{\bar{i}}$ to stay constant

M.H. acceptance ratio: $\frac{p(x_i^{(t+1)} | x_{\bar{i}}^{(t-1)}) \delta(x_{\bar{i}}, x_{\bar{i}}^{(t-1)})}{p(x_i^{(t)} | x_{\bar{i}}^{(t-1)}) \delta(x_{\bar{i}}, x_{\bar{i}}^{(t-1)})} \rightarrow \frac{p(x_i^{(t+1)})}{p(x_i^{(t)})}$

$$\begin{aligned} a(x' | x^{(t-1)}) &= \frac{q_t(x' | x^{(t-1)}) p(x')}{q_t(x' | x^{(t-1)}) p(x^{(t-1)})} \\ &= \frac{p(x_i^{(t+1)})}{p(x_i^{(t)})} = 1 \quad // \text{ always accepts! } \end{aligned}$$

convergence of G.S.:

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- let A be a Markov transition kernel of one full cycle of Gibbs sampling (i.e. n steps)
 $\rightarrow$ homogeneous M.C.

if suppose that $p(x) > 0 \forall x$

$$\Rightarrow p(x_i | x_{-i}) > 0 \forall x_i \neq x_{-i}$$

$\Rightarrow A$ is irreducible & aperiodic because $A_{ii} > 0$
 $\hookrightarrow A_{ii} > 0$
 the time can get to any state with n jumps

$$\Rightarrow A^t \pi_0 \xrightarrow{t \rightarrow \infty} p$$

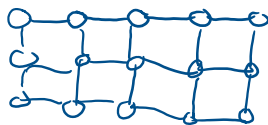
by detailed balance, p is stationary of chain

also works for random scan (pick $i \sim \text{unif}(1:n)$ at each step)

example: G.S. for Ising model

Ising model $x_i \in \{-1, 1\}$

UGM:



$$p(x) = \frac{1}{Z(n)} \exp\left(\sum_i \eta_i x_i + \sum_{i,j \in E} \eta_{ij} x_i x_j\right)$$

[minimal exp. family representation]

for G.S. want to compute $p(x_i | x_{-i})$ by cond. indep. $p(x_i | \mathcal{N}_{\text{neighbor}}(i))$

$$\propto \exp\left(\eta_i x_i + \sum_{j \in \mathcal{N}(i)} \eta_{ij} x_i x_j + \text{rest}\right)$$

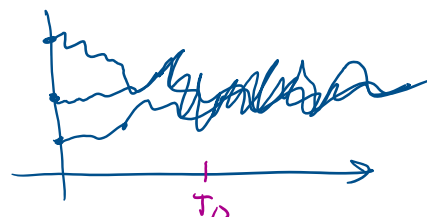
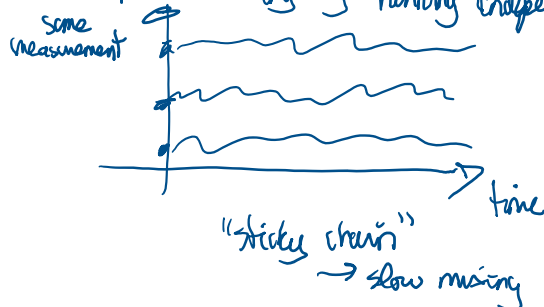
$\Rightarrow$ renormalize to get conditional

$$p(x_i = 1 | x_{-i}) = \frac{\exp(\eta_i + \sum_{j \in \mathcal{N}(i)} \eta_{ij} x_j) \exp(\text{rest})}{\left(1 + \exp(\eta_i + \sum_{j \in \mathcal{N}(i)} \eta_{ij} x_j)\right) \exp(\text{rest})}$$

$$p(x_i = 1 | x_{-i}) = \sigma\left(\eta_i + \sum_{j \in \mathcal{N}(i)} \eta_{ij} x_j\right)$$

diagnostic of mixing

monitor mixing by running independent chains



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variational methods

general idea: say we want to approximate θ^*

then, express it as a solution to opt. problem

$$\theta^* = \underset{\theta \in \Theta}{\operatorname{argmin}} f(\theta) \quad] \text{OPT}$$

idea: approximate θ^* via an approximation of OPT

linear algebra example:

say want sol'n to $Ax=b$ (ie. $x^* = A^{-1}b$)

$$x^* = \underset{x}{\operatorname{argmin}} \|Ax - b\|^2$$

Variational EM (motivation for objective)

recall EM trick:

latent $p(x, \underset{\text{unobserved}}{z} | \theta)$

$$\log p(x | \theta) \geq \mathbb{E}_q \left[\log \frac{p(x, z | \theta)}{q(z)} \right] \triangleq J(q, \theta)$$

$$\log p(x | \theta) - J(q, \theta) = KL(q(\cdot) \| p(\cdot | x, \theta))$$

$$\text{E step: } \underset{\substack{q \in \text{all distributions} \\ \text{on } Z}}{\operatorname{argmax}} J(q, \theta^{(t)}) \Leftrightarrow \underset{q}{\operatorname{argmin}} KL(q(\cdot) \| p(\cdot | x, \theta^{(t)}))$$

⊗ a variational approx for E step

$$\text{do } q_{\text{approx}}^{(t+1)} = \underset{q \in \text{sample}}{\operatorname{argmin}} KL(q(\cdot) \| p(\cdot | x, \theta^{(t)}))$$

source of approx $\rightarrow$ to approximate $p(z | x, \theta^{(t)})$

approximate M step:

$$\theta^{(t+1)} = \underset{\theta \in \Theta}{\operatorname{argmax}} \underbrace{\mathbb{E}_{q_{\text{approx}}^{(t+1)}} [\log p(x, z | \theta)]}_{J(q_{\text{approx}}^{(t+1)}, \theta)}$$

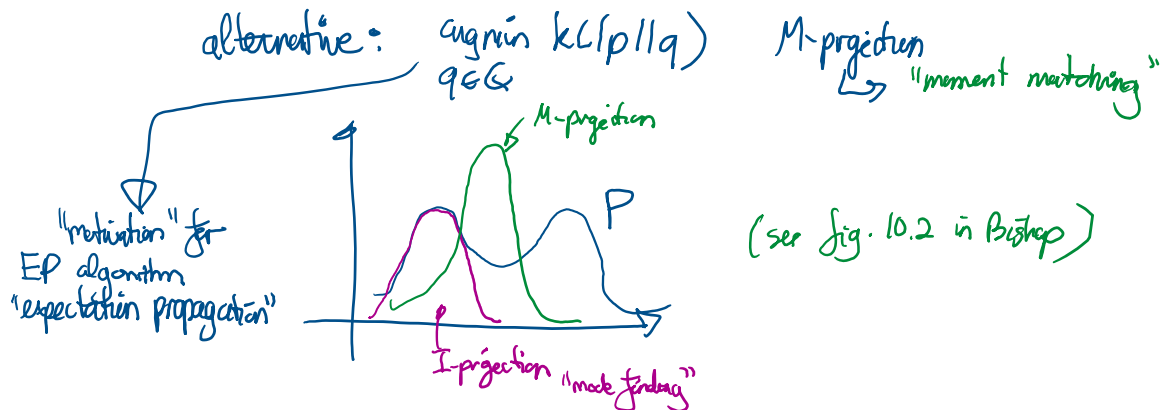
still a lower bound on $\log p(x | \theta)$

but lose monotonicity guarantee

but lose monotonicity guarantee
on $\log p(z|E^k)$ as fct. of E

more generally, using $\argmin_{q \in \mathcal{Q}} KL(q||p)$ is a variational approach to approx. p

note: I-projection; if q is simple, $\mathbb{E}_q [\log p/q]$
often can compute



Mean-field approximation (section 10.1 in Bishop)

let's suppose that $p(z)$ is in exp. family

$$z_1, \dots, z_d \quad p(z) = \exp(n^T T(z) - A(n))$$

mean field approximation $\mathcal{Q}_{MF} = \{q(z) = \prod_i q_i(z_i)\}$
set of fully factored dist.

$$\begin{aligned} KL(q||p) &= \mathbb{E}_q [\log q/p] \\ &= -n^T \mathbb{E}_q [T(z)] + A(n) + \sum_z q(z) \log q(z) \\ &\quad \xrightarrow{\substack{\prod_i q_i(z_i) \sum_j \log q_j(z_j)}}} \sum_i \sum_z q_{-i}(z_{-i}) q_i(z_i) \log q_i(z_i) \\ &\quad \xrightarrow{\substack{\prod_i \sum_{z_i} q_i(z_i)}}} \sum_i \sum_{z_i} q_i(z_i) \log q_i(z_i) \end{aligned}$$

coordinate descent on q_i 's

fix q_j for $j \neq i$ min w.r. to q_i

$$KL(q_i q_{-i} || p)$$

$$= -\mathbb{E}_{q_i} \left[\underbrace{n^T \mathbb{E}_{q_{-i}} (T(z))}_{\text{r.l.s.}} \right] + \text{cst.} + \sum_{z_i} q_i(z_i) \log q_i(z_i)$$

$$= -\mathbb{E}_{q_i} \left[\underbrace{n^T \mathbb{E}_{q_i} (T(z))}_{f_i(z_i)} \right] + \text{const.} + \sum_{z_i} q_i(z_i) \log q_i(z_i)$$

(like MaxENT) add Lagrange multiplier for $\sum_{z_i} q_i(z_i) = 1 \rightarrow \lambda (1 - \sum_{z_i} q_i(z_i))$

$$\frac{\partial}{\partial q_i(z_i)} = 0 \Rightarrow -f_i(z_i) + \log q_i(z_i) + 1 - \lambda = 0$$

$$\Rightarrow q_i^*(z_i) \propto \exp(f_i(z_i))$$

⊛ general mean field update when target p is in exp. family

$$q_i^{(t+1)}(z_i) \propto \exp(n^T \mathbb{E}_{q_i^{(t)}} [T(z)])$$

this is fct. of z_i only.
 $\rightarrow$ sufficient statistics
 for exp. family for q_i^*

Ising model:

$$T(z) \Rightarrow \begin{pmatrix} z_i \\ (z_i z_j)_{i,j \in E} \end{pmatrix} \quad z_i \in \{0,1\}$$

$$\mathbb{E}_{q_i^{(t)}} [z_j] = q_j^{(t)}(z_j=1) \triangleq \mu_j^{(t)}$$

$$\mathbb{E}_{q_i^{(t)}} [z_i z_j] = z_i \mu_j^{(t)}$$

$\rightarrow$ no $z_i \sim$ constant

$$n^T \mathbb{E}_{q_i^{(t)}} [T(z)] = n_i z_i + \underbrace{\sum_{j \in N(i)} n_{ij} \mathbb{E}_{q_i^{(t)}} [z_j]}_{\mu_j^{(t)}} + \sum_{j \in N(i)} n_{ij} \underbrace{\mathbb{E}_{q_i^{(t)}} [z_i z_j]}_{z_i \cdot \mu_j^{(t)}} + \text{rest}$$

ϕ
no z_i

result: $q_i^{(t+1)}(z_i) \propto \exp(n_i z_i + z_i (\sum_{j \in N(i)} n_{ij} \mu_j^{(t)}))$

$$\mu_i^{(t+1)} = \sigma(n_i + \sum_{j \in N(i)} n_{ij} \mu_j^{(t)})$$

MF update for $q_i(z_i)$
 [with parameter μ_i]

parameters for $q_i^{(t)}$

compare with GS update

where $z_i^{(t)} = 1$ with prob. $\sigma(n_i + \sum_{j \in N(i)} n_{ij} z_j^{(t)})$